

NS-series HMIs

NS12-TS00□-V1, NS12-TS01□-V1

NS10-TV00□-V1, NS10-TV01□-V1

NS8-TV00□-V1, NS8-TV01□-V1

NS5-SQ00□-V1, NS5-SQ01□-V1

Non-PLC Host Connections




CONFIGURATION MANUAL

OMRON

Notice

OMRON products are manufactured for use according to proper procedures by a qualified operator and only for the purposes described in this manual.

The following conventions are used to indicate and classify precautions in this manual. Always heed the information provided with them. Failure to heed precautions can result in injury to people or damage to property.

-  **DANGER** Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.
-  **WARNING** Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.
-  **Caution** Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or property damage.

OMRON Product References

All OMRON products are capitalized in this manual. The word "Unit" is also capitalized when it refers to an OMRON product, regardless of whether or not it appears in the proper name of the product.

The abbreviation "Ch," which appears in some displays and on some OMRON products, often means "word" and is abbreviated "Wd" in documentation in this sense.

The abbreviation "PLC" means Programmable Controller.

The abbreviation "host" means a controller, such as an IBM PC/AT or compatible computer, that controls a PT (Programmable Terminal).

Visual Aids

The following headings appear in the left column of the manual to help you locate different types of information.

- Note** Indicates information of particular interest for efficient and convenient operation of the product.
- Reference** Indicates supplementary information on related topics that may be of interest to the user.
- 1, 2, 3...** 1. Indicates lists of one sort or another, such as procedures, checklists, etc.
- CS1G-CPU□□-VI Boxes in model numbers indicate variable characters. For example, "CS1G-CPU□□-EV1" indicates the following models: CS1G-CPU42-EV1, CS1G-CPU43-EV1, CS1G-CPU44-EV1, and CS1G-CPU45-EV1.

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About this Manual

Section 1 Possible Combinations

This section provides information of possible combination of NS-Designer and system program when making connection with PT and host other than OMRON PLCs.

Section 2 Connection of Temperature Controller

This section provides information on connection methods and communications setting in connecting NS-series PTs with a Temperature Controller by serial port. It also provides information Temperature Controller which can be connected to the PT.

Section 3 Connection via Memory Link

This section describes information on connection methods and communication setting in connecting NS-series PTs with a host by Memory Link.

**WARNING**

Failure to read and understand the information provided in this manual may result in personal injury or death, damage to the product, or product failure. Please read each section in its entirety and be sure you understand the information provided in the section and related sections before attempting any of the procedures or operations given.

Related Manuals

The following manuals are used for NS-series PTs. (The boxes at the end of the catalog numbers indicate the revision code.)

NS Series -V1 Host Connection Manual.....V085-E1-□

Provides information on NS Series V1 models (i.e., NS12-V1, NS10-V1, NS8-V1, and NS5-V1).

Describes how to connect the PT to the host and peripheral devices, methods to setup communications and operation, and procedures for maintenance.

Refer to the *NS Series Programming Manual* (V073-E1-□) for information on PT functions and specific operating procedures.

NS Series -V1 Setup ManualV083-E1-□

Provides information on NS Series V1 models (i.e., NS12-V1, NS10-V1, NS8-V1, and NS5-V1).

Describes how to connect the PT to the host and peripheral devices, methods to setup communications and operation, and procedures for maintenance.

Refer to the *NS Series Programming Manual* (V073-E1-□) for information on PT functions and specific operating procedures.

NS Series Setup Manual.....V072-E1-□

Provides information on existing NS Series models (i.e., NS12, NS10, and NS7).

Describes how to connect the PT to the host and peripheral devices, methods to setup communications and operation, and procedures for maintenance.

Refer to the *NS Series Programming Manual* (V073-E1-□) for information on PT functions and specific operating procedures.

NS Series Programming ManualV073-E1-□

Describes the screen configurations, object functions, and host communications for the PT.

NS-Designer Operation Manual.....V074-E1-□

Describes operating procedures for the NS-Designer, which is used to create the screens displayed on the PT and transfer them to the PT. It includes screen creation and transfer procedures.

Terminology

The following terminology is used in this manual.

| | |
|-----------------------------|--|
| PT | In this manual, indicates an NS-series Programmable Terminal. |
| NS Series | Indicates products in the OMRON NS□□ Series of Programmable Terminals. |
| PLC | Indicates a Programmable Controller in the OMRON SYSMAC CS/CJ, C, or CVM1/CV Series of Programmable Controllers. |
| CS/CJ Series | Indicates Programmable Controllers in the OMRON SYSMAC CS/CJ Series of Programmable Controllers: CS1G, CS1H, CS1G-H, CS1H-H, CJ1G, CJ1M. |
| C Series | Indicates products in the OMRON SYSMAC C Series of Programmable Controllers: C200HS, C200HX(-Z), C200HG(-Z), C200HE(-Z), CQM1, CQM1H, CPM1A, CPM2A, CPM2C. |
| CVM1/CV Series | Indicates products in the OMRON SYSMAC CVM1/ CV Series of Programmable Controllers: CV500, CV1000, CV2000, CVM1 |
| Serial Communications Unit | Indicates a Serial Communications Unit for an OMRON CS/CJ-series PLC. |
| Serial Communications Board | Indicates a Serial Communications Board for an OMRON CS-series or CQM1H PLC. |
| Communications Board | Indicates a Communications Board for an OMRON C200HX/HG/HE(-Z) PLC. |
| CPU Unit | Indicates a CPU Unit in the OMRON SYSMAC CS/CJ, C, or CVM1/CV Series of Programmable Controllers. |
| NS-Designer | Indicates the OMRON NS-Designer (NS-NSDC1-V□). |
| Host | Indicates the PLC, IBM PC/AT or compatible computer, or personal computer functioning as the control device and interfaced with the NS-series PT. |
| Programming Manual | Indicates the <i>NS Series Programming Manual</i> (V073-E1-□). |

Introduction

• Intended Audience



This manual is intended for the following personnel, who must also have knowledge of electrical systems (an electrical engineer or the equivalent).

- Personnel in charge of introducing FA systems into production facilities.
- Personnel in charge of designing FA systems.
- Personnel in charge of installing and connecting FA systems.
- Personnel in charge of managing FA systems and facilities.

• General Precautions

- The user must operate the product according to the performance specifications described in the operation manuals.
- Do not use the PT touch switch input functions for applications where danger to human life or serious property damage is possible, or for emergency switch applications.
- Before using the product under conditions which are not described in the manual or applying the product to nuclear control systems, railroad systems, aviation systems, vehicles, combustion systems, medical equipment, amusement machines, safety equipment, and other systems, machines and equipment that may have a serious influence on lives and property if used improperly, consult your OMRON representative.
- Make sure that the ratings and performance characteristics of the product are sufficient for the systems, machines, and equipment, and be sure to provide the systems, machines, and equipment with double safety mechanisms.
- This manual provides information for connecting and setting up an NS-series PT. Be sure to read this manual before attempting to use the PT and keep this manual close at hand for reference during installation and operation.

• Safety Precautions

| | |
|--|---|
|  WARNING | |
| Do not attempt to take the Unit apart and do not touch any internal parts while the power is being supplied. Doing either of these may result in electrical shock. |  |

• Operating Environment Precautions

1. Do not install the Unit in the following places:
 - Locations subject to direct sunlight
 - Locations subject to temperatures or humidity outside the range specified in the specifications
 - Locations subject to condensation as the result of severe changes in temperature
 - Locations subject to corrosive or flammable gases
 - Locations subject to dust (especially iron dust) or salts
 - Locations subject to exposure to water, oil, or chemicals

- Locations subject to shock or vibration
2. Take appropriate and sufficient countermeasures when installing systems in the following locations:
 - Locations subject to static electricity or other forms of noise
 - Locations subject to strong electromagnetic fields
 - Locations subject to possible exposure to radioactivity
 - Locations close to power supplies

• Application Precautions

1. When unpacking the Units, check carefully for any external scratches or other damage. Also, shake the Units gently and check for any abnormal sound.
2. The mounting panel must be between 1.6 and 4.8 mm thick. Tighten the Mounting Brackets evenly to a torque of between 0.5 and 0.6 N·m to maintain water and dust resistance. Make sure the panel is not dirty or warped and that it is strong enough to hold the Units.
3. Do not let metal particles enter the Units when preparing the panel.
4. If conformance to EC Directives (Low Voltage Directive) is required, use reinforced insulation for the power supplies.
5. Do not connect an AC power supply to the power terminals.
6. Use a DC power supply with minimal fluctuation voltage.
Rated power supply voltage: 24 VDC
(Allowable range: 20.4 to 27.6 VDC)
Capacity: 25 W min. (NTLP:INFORMATION MISSING IN JAPANESE NS5: ???W min.)
7. Do not perform a dielectric voltage test.
8. Use a twisted-pair cable with a cross-sectional area of at least 2 mm² to connect to the power terminals and always use M3.5 crimp terminals. Tighten the terminal screws to a torque of 0.8 N·m. Make sure the screws are properly tightened.
9. Ground the Unit correctly to prevent operational errors caused by noise.
10. Do not touch the surface of the circuit board or the components mounted on it with your bare hands. Discharge any static electricity from your body before handling the board.
11. Confirm that the current capacity of the connected device is 250 mA or less before using the 5-V power supply from pin 6 of the serial port A, B connectors. The 5-V output of the PT is 250 mA max. at 5 V ±5%.
12. Turn OFF the power supply before connecting or disconnecting cables.
13. Always tighten the connector screws after connecting communications cables.
14. The maximum tensile load for cables is 30 N. Do not apply loads greater than this.
15. Confirm the safety of the system before turning ON or OFF the power supply or before pressing the reset button.
16. The whole system may stop depending on how the power supply is turned ON or OFF. Turn ON or OFF the power supply according to the specified procedure.
17. Start actual system application only after sufficiently checking screen data, macros, and the operation of the program in the PC (host).
18. Always reset the power supply after changing switch settings.
19. After changing the settings of the DIP switch, always turn the power supply OFF and ON or reset the PT.
20. Do not perform the following operations while the Memory Card is being accessed:
 - Turning OFF the power supply to the PT
 - Pressing the PT's reset switch
 - Removing the Memory Card
 Always following the specified procedure when removing the Memory Card.
21. Do not press the touch switch with a force greater than 30 N.

22. Confirm the safety of the system before pressing touch switches.
23. Do not accidentally press touch switches when the backlight is not lit or when the display does not appear.
24. Signals from the touch switches may not be input if the switches are pressed consecutively at high speed. Confirm each input before proceeding to the next one.
25. Before initializing screen data, confirm that existing data is backed up at the NS-Designer.
26. When changing the password with the system menu, do not reset or turn OFF the power supply until writing is finished (i.e., until the Write Button returns to its original condition). It may become impossible to manipulate screens if the password is not set correctly.
27. When using the device monitor, confirm the safety of the system before performing the following operations.
 - Changing monitor data
 - Changing operation modes
 - Forced setting or resetting
 - Changing present values or set values
28. Do not use benzene, paint thinner, or other volatile solvents, and do not use chemically treated cloths.
29. Dispose of any battery that has been dropped on the floor or otherwise subjected to excessive shock.
30. Do not attempt to disassemble, repair, or modify the Unit in any way.
31. Dispose of the Units and batteries according to local ordinances as they apply.
32. To ensure system safety, incorporate a program that periodically calls PT operation bits from the host side to check that the PT is properly operating.
33. Do not connect an USB connector to any device that is not applicable.
34. Before connecting an USB connector to a device, make sure that the device is free of damage.
35. When mounting the Battery, be sure to use the correct Battery and mount it correctly.

Section 1

Possible combinations

This section explains in general how to connect hosts other than NS-V1 Series Omron PLC and which models to connect.

1-1List of combinations

1-2NS-Designer and System Program version

1-1 List of combinations

This explains the configuration when host is other than Omron PLCs.

1-1-1 Connection of temperature controller

Communicates with Omron temperature controller via RS-485.

Connect RS-422 converter CJ1W-CIF11 to serial port A or B and set communication mode to RS-485.

For details, refer to 'Chapter 2: connection of temperature controller'.

1-1-2 Connection with memory link

When host other than PLC such as board-controller and personal computer is used, connection via memory link is possible. Use serial port A or B to connect host equipment. For details, refer to 'chapter 3: connection via memory link'.

1-2 NS-Designer and System Program versions

1-2-1 NS-Designer versions

With NS-Designer Ver.5.0 or later version, you can create and edit projects for Temperature Controller connections and Memory Link connections.

1-2-2 System Program versions

System program Ver.5.0 or later.

A copy of this version is included NS-Designer Ver.5.0.

NS with -V1 suffix models (NS12/10/8/5 -V1) are supported for those connections.

NS without -V1 suffix models are not supported.

When system program version is earlier than Ver.5.0, you need to upgrade. For details on how to upgrade, refer to the manual (PDF)(Recover NS Ver.5) in NS-Designer.

Section 2

Connection of temperature controller

This section explains how to connect Omron temperature controllers (E5□N) and digital controllers (E5AR/ER) and which models to connect.

2-1Outline

2-2Possible combinations

2-3Configuration

2-4Setting projects

2-5Monitor variables area in temperature controller

2-6Operation of temperature controller

2-7Functional restrictions

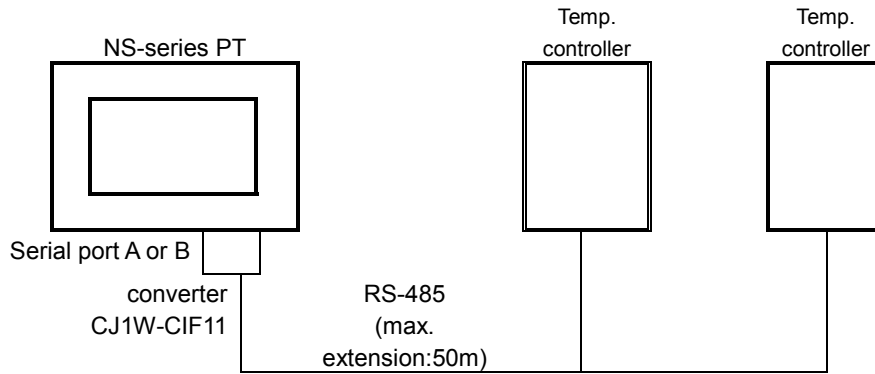
2-1 Outline

This explains how to connect temperature controllers.

Connectable are temperature controllers with a RS-485 port.

Use NS serial port A or B (either one), use converter to transform to RS-485.

1 serial port can accommodate max. 31 temperature controllers.



By using another communications port, you can simultaneously connect temperature controllers and a host. With one more serial port, NS can connect PLC, barcode reader, Memory Link and can communicate with NS-Designer.

If NS is equipped with Ethernet port, communications with Omron PLC via Ethernet is possible.

If equipped with Controller Link I/F, communication with Omron PLC via Controller Link is possible.

2-2 Possible combinations

2-2-1 Connectable temperature controller

Only models with RS-485 communications port that support CompoWay/F can be used.

The following models are connectable:

| Name | Series | Model |
|--------------------------------|--------|-----------------------------|
| Temperature controller | E5ZN | E5ZN-SCT24S (terminal unit) |
| | E5AN | E5AN- □ □ □ 03 □ -FLK |
| | E5EN | E5EN- □ □ □ 03 □ -FLK |
| | E5CN | E5CN- □ □ □ 03 □ -FLK |
| | E5GN | E5GN- □ □ □ 03 □ -FLK |
| Digital temperature controller | E5AR | E5AR-QC43DB-FLK |
| | | E5AR-QQ43DW-FLK |
| | | E5AR-CC43DWW-FLK |
| | E5ER | E5ER-QC43B-FLK |
| | | E5ER-PRQ43F-FLK |
| | | E5ER-QT3DW-FLK |
| | | E5ER-CT3DW-FLK |

2-2-2 Temperature controller Manuals

| Manual name | Catalog No. |
|--|-------------|
| E5CN/CN-U User's manual | H100-E1 |
| E5GN User's manual | H101-E1 |
| E5 EN User's manual Communications functions | H102-E1 |
| E5EN User's manual | H111-E1 |
| E5AN User's manual | H112-E1 |
| E5AR/ER User's manual | Z182-E1 |

2-3 Configurations

2-3-1 Necessary parts

■ RS-422A Converter

CJ1W-CIF11

■ Crimp terminal

● CJ1W-CIF11side communications path terminator

| | | |
|-----------------|---------------------------|----------------------|
| Phoenix Contact | AI Series AI-0.5-8WH-B | (serial No. 3201369) |
| Crimp tool | ZA3 | (serial No. 1201882) |

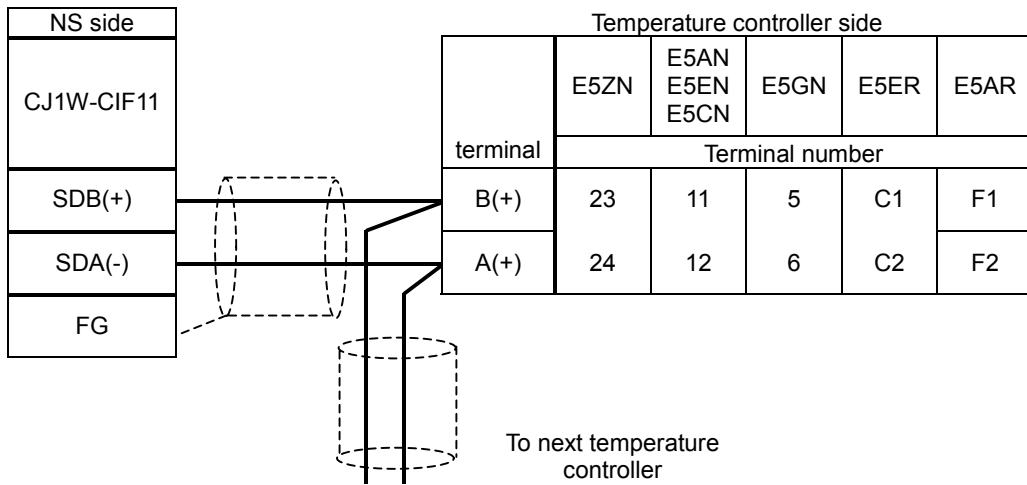
● CJ1W-CIF11 side other than communications path terminator

| | | |
|-----------------|-------------------------------|----------------------|
| Phoenix Contact | AI series AI-TWIN2×0.5-8WH | (serial No. 3200933) |
| Crimp tool | UD6 | (serial No. 1204436) |

● Temperature controller side

| Model | Terminal block screw size | Terminal size |
|---------|------------------------------|---------------|
| E5CN | M3.5 | 7.2mm max. |
| E5GN | | |
| E5EN | | |
| E5AN | | |
| E5ZN | M3 | 5.8mm max. |
| E5ER/AR | | |

2-3-2 Wiring diagram



- Connection: 1:1 or 1:N. If 1:N, max. 32 units (NS and temperature controllers combined) can be connected. (in case of E5ZN, the maximum is 16 units).
- Cable length: In total max. 50 m
- Use shielded twist pair cables (min. size AWG28)
- Connect terminating resistance (100 to 125Ω(1/2W)) to both ends of the communications path. Furthermore, combined resistance must be 54 Ω min.

2-3-3 Temperature controller communications settings

This summarizes temperature controller communications settings.

For more details on settings and operation procedure of setting specifications, refer to the relevant temperature controller manual.

■ E5ZN

| Setup Switch on E5ZN panel | | | |
|------------------------------|-----------------------|--|-------------|
| Unit number | 0 to 15 | When using multiple E5ZN units, be careful not to use the same number twice. | |
| Baud rate | 0 | 4800 Bps | |
| | 1 | 9600 Bps | |
| | 2 | 19200 Bps | |
| Communications setting level | | | |
| | CH | Value | |
| Data bits | C3 0013 or C3 0113 | 7 | 7 bits |
| Stop bits | C3 0014 or C3 0114 | 2 | 2 bits |
| Parity | C3 0015 or C3 0115 | 2 | Even (EvEn) |
| Response Waiting time | C3 0016 or C3 0116 | 0 to 270FH (0 to 9999) | In ms |

■ E5GN/E5AN/E5EN/E5CN/E5ER/E5AR

| Adjustment level L.Adj | | | |
|----------------------------------|------|-----------------------------------|---|
| Communications writing | CoWt | on | enable |
| | | OFF | disable |
| Communications setting level L.S | | | |
| Baud rate | bPS | 2.4 4.8 9.6 19.2 38.4 | In kbps Set all communicating temperature controllers to match parameters of NS E5ER/AR: choose between 9.6/19.2/38.4 E5□N: 38.4 cannot be selected. |
| Data bits | LEn | 7 | 7 bits |
| Stop bits | Sbit | 2 | 2 bits |
| Parity | Prty | EvEn | Even |
| Response Waiting time | SdWt | 0 to 270FH (0 to 9999) | In ms E5AR/ER range: 0 to 63H(0 to 99) |
| Communications Unit No. | U-no | 0 to 31 | E5AR/ER only |
| Protocol select | PSEL | CyF | Compoway/F (E5AR/ER only) |

2-3-4 CJ1W-CIF11 setting

Dip switch setting

| Pin No. | Function | setting | |
|---------|--------------------------------------|---------|---|
| 1 | Terminal resistance select ON/OFF | ON | Terminating resistance (on both ends of the communications path) |
| | | OFF | No terminating resistance (other than both ends of the communications path) |
| 2 | Switch between 2/4 line system | ON | 2 line system |
| 3 | Switch between 2/4 line system | ON | |
| 4 | Not used | - | |
| 5 | RD control by RS select ON/OFF | OFF | |
| 6 | SD control by RS Select ON/OFF | ON | RS control function ON |

2-3-5 NS setting

Before you can connect temperature controllers, you need to store the required project in the NS. For project setting, refer to '2-4 project setting'.

With communications settings under system menu, you can set the speed of communications.

| | | |
|-----------|---|-----|
| Baud rate | 2400 / 4800 / 9600 / 19200 / 38400 / 57600 / 115200 | bps |
|-----------|---|-----|

Of these values, 57600 / 115200 are for future use.

Present temperature controllers cannot operate at these rates.

Set PT unit and temperature controller baud rate values to match each other.

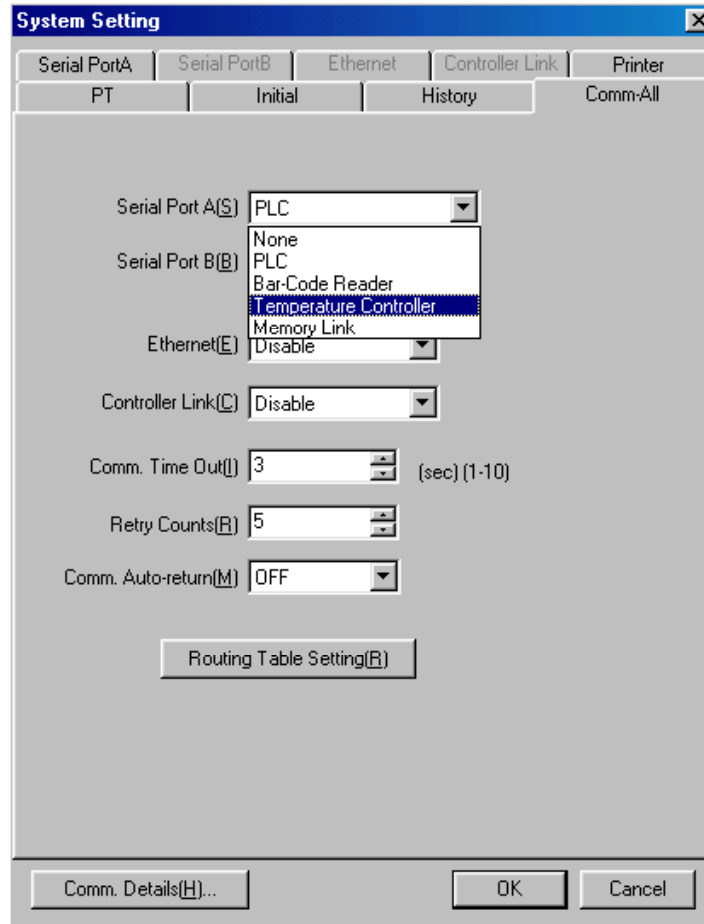
2-4 Setting Project

With this function, you set projects needed to connect temperature controllers.

Select **Setting - System Setting**. System Setting dialogue opens.

Select tab **Comm - All**.

Select Temperature Controller from the pull down menu for Serial Port A (or Serial B).

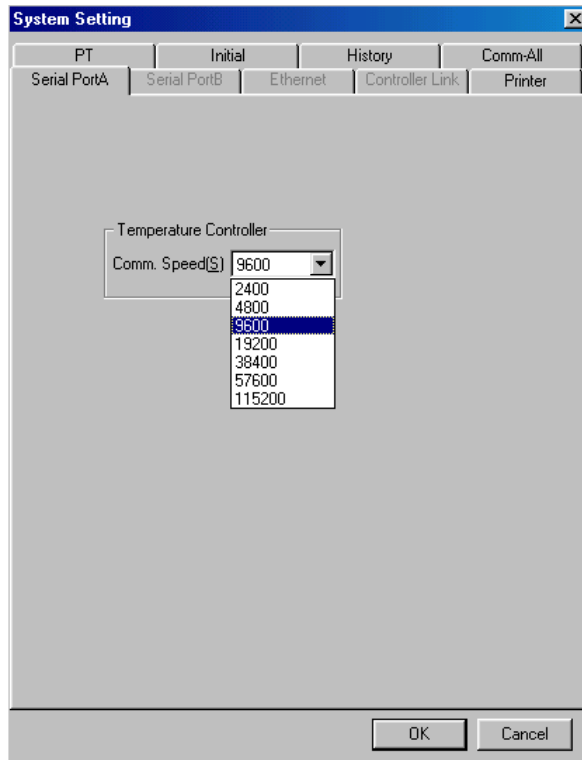


Select tab Serial Port A (or Serial Port B) and set baud rate.

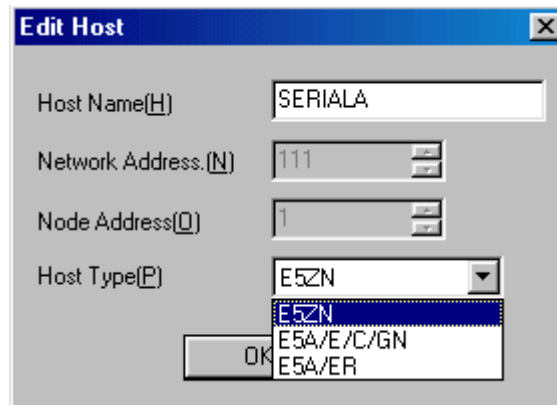
Selectable baud rate values are:

2400 / 4800 / 9600 / 19200 / 38400 / 57600 / 115200 (in bps).

Baud rates 57600 / 115200 are for future use. Present temperature controllers cannot operate at these rates.



Next, click **Settings - Register Host**. Host Registration Dialogue opens. Define temperature controller model to be connected.



2-5 Monitor variables area in temperature controller

2-5-1 Variables area in temperature controller

Data stored in variable area of the temperature controller are: Present Value, SP, Heater burnout alarm status and such.

By reading/writing these data from PT, you can monitor temperature controller status.

Values of variables you can display on PT screen as numbers and you can create save the changes of those as log data.

Temperature controller status (variable C0, address 0001) is information on bit level. You can show status by ON/OFF lamp and you can display/save the history log that shows status changes.

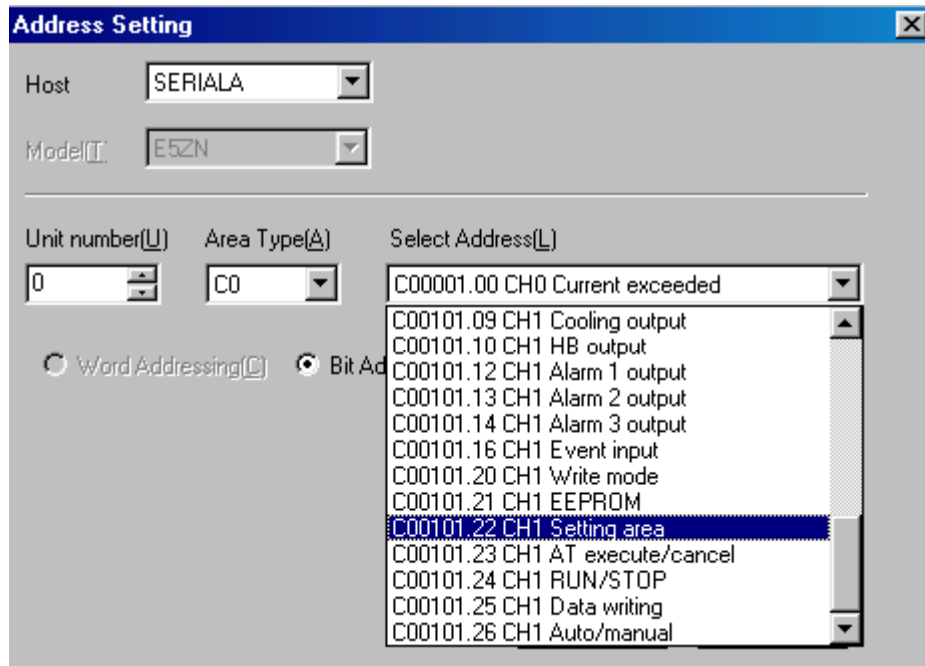
Address of variable are in a Temperature Controller should be assigned to the lamps, numeral display and input object, or graphs before monitoring the variable area.

Accessible address ranges vary with temperature controller models.

For details on accessible address ranges and definitions of settable address ranges, numerical values and contact status, refer to the following manuals.

| Model | Manual Number | Chapter |
|------------------------|---------------|----------------------------|
| E5AN E5EN E5CN E5GN | H102-E1 | 3 |
| E5ZN | H112-E1 | 5, 5.10 Variables area map |
| E5AR E5ER | Z182-E1 | Appendix Settings list |

NS-Designer shows accessible address range in accordance with the model specified in the Register Host dialog so that user can set an appropriate communication address.



You can also manually enter a communications address, which is not listed without opening Address Setting dialog. In this case, enter the desired address directly to the field shown in the property dialog.

2-5-2 Address notation in NS-Designer

| | | | | |
|---|---|---------------------------|-----------------------|---------------------|
| Address notation when accessed using word (address for word communications) | | | | |
| <port> | : | <Communications unit No.> | # <Variable category> | <Channel> <Address> |

| | | | | | | | |
|--|---|---------------------------|-----------------------|-----------|-----------|---|----------------|
| Address when accessed using bit (address for bit communications) | | | | | | | |
| <port> | : | <communications unit No.> | # <Variable category> | <channel> | <address> | . | <bit position> |

| Item | Value range & definition | |
|----------------------------|--------------------------|----------------------------|
| <Port> | SerialA | Connected to serial port A |
| | SerialB | Connected to serial port B |
| <communications unit No. > | 00 to 31 | |
| <Variable type> | C0 to D7 | |
| <Channel> | 00 to 03 | ch1 to ch4 |
| <Address> | variable category | Address range |
| | C0 to C3 | 00 to 3F |
| | C4 to CB | 00 to 7F |
| | CC to D7 | 00 to 3F |
| <Pit position> | 00 to 31 | |

Example:

| | |
|-------------------------|---|
| SerialA:24#C4001C | PortA:Unit No.24/area category C4/ch1/address 1CH |
| SerialB:17#D1036E. 3 | PortB:Unit No.17/area D1/ch4/address6EH/bit3 |

2-5-3 Use of double word numbers

Variable area in the Temperature Controller is composed of values in double-word format(32bit length). Negative values are expressed as the two's complement. Therefore, select DINT(signed 2 words) as storage type for the variable, which the decimal value will be stored. Select UDINT(unsigned 2 words) for the variable, which the hexadecimal value will be stored.

2-5-4 Communications writing enabled/disabled

Before you can write to variable area in temperature controller, you need to go to the adjustment level and set **Communications writing** on **Enabled: ON**. (Default setting is **Disabled: OFF**).

For monitoring only, so when no writing is carried out, the setting can be either **Disabled: OFF** or **Enabled: ON**.

Use either the panel on the Temperature Controller or Setting Tool to set "Communications Writing" parameter. It can be also set with Smart Active Parts in the PT.

2-6 Operation of Temperature Controller

The use of Smart Active Parts, allows you to operate PT screen to change Temperature Controller running conditions and to disable/enable communications writing.

2-6-1 How to create a Smart Active Parts part

In NS-Designer, you open the arrange Smart Active Parts screen.

When you select **Tools - Use Library** , the library dialogue opens.

Under list of categories, tree of selectable libraries is shown.

Smart Active Parts for temperature controller you can find under **PartsLib -> Smart Active Parts -> Temperature Controller**.

Temperature controller is grouped by model, channel and broadcast. For each operation instruction, a Smart Active Parts part is available.

There are 2 categories: Instructions to the unit itself and broadcast .

When same instruction is given to all units, no results response is sent. For that reason error judgment is omitted.

Selectable Smart Active Parts are shown in the preview box on the right. Title of the selected Smart Active Parts are shown in the bottom center dialogue box.

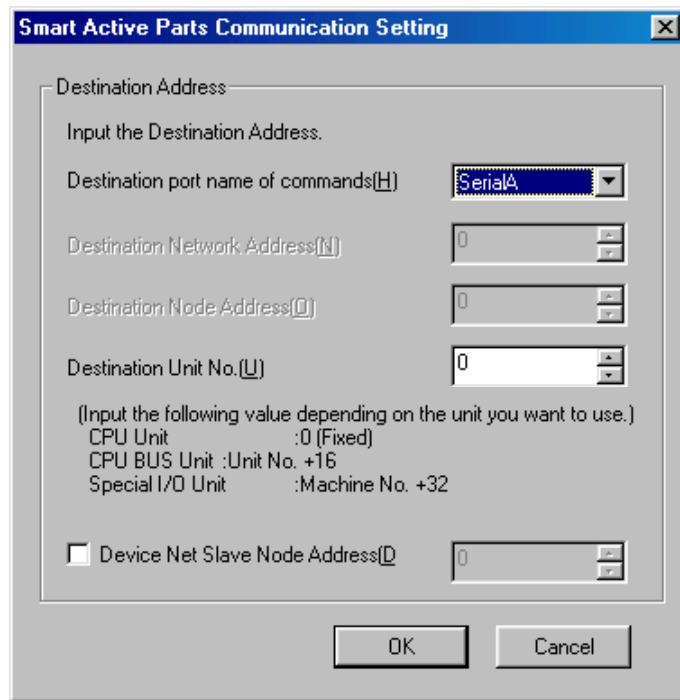
Select appropriate Smart Active Parts and click **Use**.

By doing so, the selected Smart Active Parts is pasted onto the screen that is being edited.

The Smart Active Parts part is pasted onto the upper left corner of the screen. Move to the desired location.

Or, click the Smart Active Parts part and set communications parameters.

| | |
|-------------------------------|---|
| port to which command is sent | SerialA :when connected to serial port A |
| | SerialB :when connected to serial port B |
| Destination Unit No. | 0 to 31 :Communications unit No. of the temperature controller you want to operate. |
| | With broadcast to all parts, this parameter is not used. Keep default value 0. |



When you want to change the label and color setting of the Smart Active Parts, go to Tools – Options – Edit/Disp tab and check the **Edit Smart Active Parts properties**. Double click on the desired object to open the property dialog and the settings can be changed.

Do not change the communications address when editing the settings. Once it has been changed, the Smart Active Parts will not function properly anymore.

Furthermore, once you have selected certain options, you cannot set Smart Active Parts communications settings anymore. So when you want to modify the communications settings, deselected options.

2-6-2 Smart Active Parts Operations

Smart Active Parts for Temperature Controllers are grouped by Temperature Controller model, channel, instruction to single unit/broadcast, control details.

Smart Active Parts title indicates the operating instruction to be executed.

■ Communications writing enabled/disabled

You can either enable or disable the writing of set values from communications.

When communications writing is disabled, the writing of set values from communications and the execution of certain instructions is prohibited.

Default setting is set as **Disable**.

By executing Smart Active Parts **Enable communications writing/Disable communications writing**, you can switch between enabled/disabled.

If communications writing is not enabled before writing set values with numeral display & input object or word button, an error occurs.

Furthermore, by disabling communications writing, you can avoid that set values are being changed by accident.

A summary of executable/non executable instructions when communications writing is disabled, is given in table '2-6-3 Smart Active Parts list'.

■ Setting area 0/setting area 1

Temperature controller communications has 2 operation modes: setting area 0 and setting area 1.

In setting area 0, control operations are conducted. You cannot modify any set values that negatively affect the control operations. When power supply is turned on, this mode is selected.

In Setting area 1, the control operations are stopped. You can modify the set values protected in Setting area 0.

You can switch to Setting area 1 by executing Smart Active Parts part 'Move to setting area 1'.

To change from Setting area 1 to Setting area 0, you can either turn the power off and then back ON again or you can execute Smart Active Parts part: " Software Reset".

Executable operating instructions vary depending on which mode is selected: setting area 0 or 1.

| Non executable in setting Area 0 | Non executable in setting Area 1 |
|----------------------------------|--|
| Initialize set values | AT execute/cancel Move to protect level Auto/manual PV hold |

■ Confirm command results

Under certain conditions e.g. communications writing disabled, it can happen that a selected Smart Active Parts instruction cannot be executed.

But, when performing the broadcast, no response is given. In that case there is no check as to whether the action was completed successfully or not.

Therefore adopt a method that checks if the operation was carried out properly, e.g. lamp indication.

| Model | Title (operating instruction) | Addresses to be monitored | |
|--|----------------------------------|---------------------------|-----------------|
| Common | Communications writing disabled | ch1 | CO0001.25 |
| | Communications writing enabled | ch2 | CO0101.25 |
| | run | ch1 | CO0001.24 |
| | stop | ch2 | CO0101.24 |
| | AT execute | ch1 | CO0001.23 |
| | AT cancel | ch2 | CO0101.23 |
| | Writing mode: back-up | ch1 | CO0001.20 |
| | Writing mode: RAM | ch2 | CO0101.20 |
| | Move to setup area 1 | ch1 | CO0001.22 |
| | | ch2 | CO0101.22 |
| | auto | ch1 | CO0001.26 |
| manual | ch2 | CO0101.26 | |
| E5ZN | Cancel alarm 1 latch | ch1 | C00001.12 to 15 |
| | Cancel alarm 2 latch | ch2 | C00101.12 to 15 |
| | Cancel alarm 3 latch | *1 | |
| | Cancel all alarm latches | *1 | |
| E5□R | Cancel alarm latch | ch1 | C00001.12 to 15 |
| | | ch2 | C00101.12 to 15 |
| | | ch3 | C00201.12 to 15 |
| | | ch4 | C00301.12 to 15 |
| | | *1 | |
| | SP mode: local SP | ch1 | C00001.27 |
| | SP mode: remote SP | ch2 | C00101.27 |
| | Select bank: 0 to 7 | ch1 | C40408 |
| | | ch2 | C41408 |
| | | ch3 | C42408 |
| ch4 | | C43408 | |
| AT execute (confirm executing PID group No.) | ch1 | C4040A | |
| | ch2 | C4140A | |
| | ch3 | C4240A | |
| | ch4 | C4340A | |

*1 Confirm that alarm output has become OFF.

Attention: Under certain conditions such as PV that an alarm might be output, you cannot confirm because alarm output remains high even when the latch is cancelled

2-6-3 List of Smart Active Parts

For **broadcast** and **for single unit** commands respectively.

| Model | CH | Title (operating instruction) | Outline | *1 | |
|--------------------------|------------------------|--|--|----|----|
| E5□N | Common | Communications writing disabled | switch between Communications writing Enabled/disabled. | OK | |
| | | Communications writing Enabled | | | |
| | | Run | Start control (run). | | |
| | | stop | Stop control (stop). | | |
| | | Multi SP: select target Value 0 | Switch between multi SP target values | | |
| | | Multi SP: select target value 1 | | | |
| | | Multi SP: select target value 2 | | | |
| | | Multi SP: select target value 3 | | | |
| | | AT execution | Execute/cancel AT | NG | |
| | | AT cancel | | | |
| | | Writing mode: back up | Select whether or not to write operation/adjustment settings to internal non-volatile memory when writing from communications | | |
| | | Writing mode: RAM | | | |
| | | Save RAM data | Write operation/ adjustment level settings to internal non-volatile memory. | | |
| | | Reset soft | Reset software | | |
| | | Move to setup area 1 | Move to settings area 1 | | |
| Move to protect level | Move to protect level | | | | |
| E5ZN | Common | Communications writing disabled | Switch between communications writing enabled/disabled. | | OK |
| | | Communications writing enabled | | | |
| | | Writing mode: back up | Select whether or not to write operation/ adjustment level settings to internal non-volatile memory when writing from communications | NG | |
| | | Writing mode: RAM | | | |
| | | Save RAM data | Write operation/ adjustment level settings to internal non-volatile memory. | | |
| | | Reset soft | Reset soft. | | |
| | | Move to setup area 1 | Move to settings area 1 | | |
| | | Move to protect level | Move to protect level | | |
| | | PV hold | Save Present value at time of execution. | | |
| | | Initialize parameters | Set parameters to default values | | |
| | CH1/ CH2/ All CH | Run | Start control (run) | OK | |
| | | stop | Stop control (stop) | | |
| | | Multi SP: select target Value 0 | Switch between multi SP target values | | |
| | | Multi SP: select target Value 1 | | | |
| | | AT execute | Execute AT | NG | |
| AT cancel | | Cancel AT | | | |
| auto | | Switch between auto-operation/manual operation | | | |
| manual | | | | | |
| Cancel alarm 1 latch | Cancel alarm latch | | | | |
| Cancel alarm 2 latch | | | | | |
| Cancel alarm 3 latch | | | | | |
| Cancel all alarm latches | | | | | |

*1:cannot be executed when communications writing is disabled.

When you execute an operating instruction designated to all channels, models other than the analog output type E5ZN do not operate properly.

| Model | CH | Title (operating instruction) | outline | *1 | |
|--------------------|--|--|---|----|--|
| E5□R | Common | communications writing disabled | Switch between communications writing enabled/disabled | OK | |
| | | Communications writing enabled | | | |
| | | Writing mode: back up | Select whether or not to write operation/adjustment level settings to internal non-volatile memory when writing from communications | NG | |
| | | Writing mode: RAM | | | |
| | | Save RAM data | | | Write operation/adjustment level settings to internal non-volatile memory. |
| | | Reset soft | Reset soft | | |
| | | Move to setup area 1 | Move to setup area 1 | | |
| | | Move to protect level | Move to protect level | | |
| | | Initialize parameters | Set parameters to default values | | |
| | CH1/ CH2/ CH3/ CH4/ All CH | Run | Start control (run) | | OK |
| | | Stop | Stop control (stop) | | |
| | | Switch bank 0 | Switch setting bank of target value, alarm value, PID group No. setup bank | NG | |
| | | Bank Switch 1 | | | |
| | | Bank Switch 2 | | | |
| | | Bank Switch 3 | | | |
| | | Bank switch 4 | | | |
| | | Bank switch 5 | | | |
| | | Bank switch 6 | | | |
| | | Bank switch 7 | | | |
| | | AT execution:selected PID | Execute AT with presently selected PID or with designated PID group No. PID. | | |
| | | AT execution: PID 1 | | | |
| | | AT execution: PID 2 | | | |
| | | AT execution: PID 3 | | | |
| | | AT execution: PID 4 | | | |
| | | AT execution: PID 5 | | | |
| | | AT execution: PID 6 | | | |
| | | AT execution: PID 7 | | | |
| | | At execution: PID 8 | | | |
| | | At cancel | Cancel AT | | |
| | Auto | Select between Auto-operation/manual operation | | | |
| manual | | | | | |
| Cancel alarm latch | Cancel alarm latch | | | | |
| CH1/ CH2 | SP mode: local SP | Select SP mode (local SP/remote SP). | | | |
| | SP mode: remote SP | | | | |

*1:cannot be executed when communications writing is disabled.

When you execute an operating instruction designated to all channels, models other than the analog output type E5ZN do not operate properly.

2-7 Restrictions

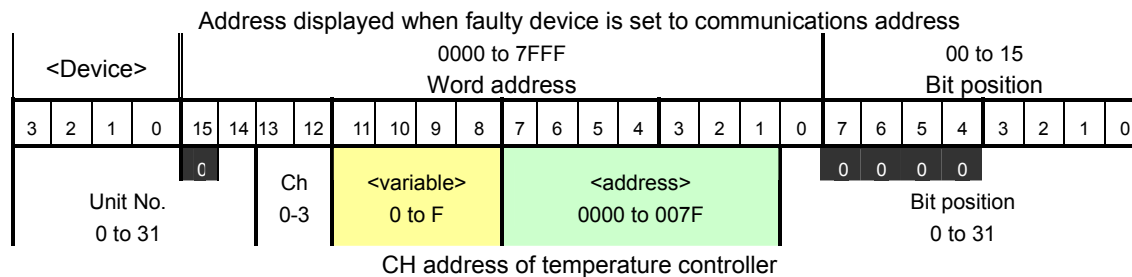
2-7-1 The behavior of 2 word number in the NS-Designer test function

In the temperature controller, a value equivalent to 2 words (32 bits) is stored for each communications address, but in the test function, the first 16 bits and the last 16 bits behave as one and the same value. For that reason, test function will not operate successfully when 2 word numbers are designated.

2-7-2 Address display when address error occurs

When faulty device is set to communications address set in functional object, this communications address is displayed in the device setting error dialogue.

If the communications address is allocated to the temperature controller, not the address for the temperature controller set with the NS-Designer, but the address in the PLC address format is displayed. Addresses will be converted as shown below.



| <Device> | Unit No. | |
|----------|----------|----|
| DM | 0 | 1 |
| EM | 2 | 3 |
| EM0 | 4 | 5 |
| EM1 | 6 | 7 |
| EM2 | 8 | 9 |
| EM3 | 10 | 11 |
| EM4 | 12 | 13 |
| EM5 | 14 | 15 |
| EM6 | 16 | 17 |
| EM7 | 18 | 19 |
| EM8 | 20 | 21 |
| EM9 | 22 | 23 |
| EMA | 24 | 25 |
| EMB | 26 | 27 |
| EMC | 28 | 29 |
| WR | 30 | 31 |

| <Variable > | Temp controller | | <Address> |
|-------------|-----------------|----|--------------|
| | Variable | | |
| 0 | C0 | C1 | 0000 to 003F |
| 1 | C2 | C3 | 0040 to 007F |
| 2 | C4 | | 0000 to 007F |
| 3 | C5 | | |
| 4 | C6 | | |
| 5 | C7 | | |
| 6 | C8 | | |
| 7 | C9 | | |
| 8 | CA | | |
| 9 | CB | | |
| A | CC | CD | 0040 to 007F |
| B | CE | CF | 0000 to 003F |
| C | D0 | D1 | 0040 to 007F |
| D | D2 | D3 | 0000 to 003F |
| E | D4 | D5 | 0040 to 007F |
| F | D6 | D7 | 0000 to 003F |

Device setting errors are not likely to occur. This because, setting is done using the method by which a selection is made from a list of accessible addresses for each temperature controller model.

However, in below cases in which the address is not selected from the list of accessible addresses an invalid address may have been assigned. In such a case, a device setting error may occur.

- Communications address set when functional object was copied using repeat command when index was assigned.
- Communications address set by 'Allocate Addresses Automatically' in the frame property.
- Communications address set by using the macro function.

Furthermore,

- Writing to read-only area
- Writing while communications writing was prohibited

cause device setting errors to occur.

2-7-3 Communications address set when functional part was copied using repeat command

In NS-Designer, you can select functional object and when you then execute 'repeat', you can copy while communications addresses are being added.

The temperature controller's address is a double word address. To increment a double word address by 1, you need to increment a single word address by 2.

Address in NS-Designer is expressed as a 1 word address. When repeat command is used to copy functional object, 1 word is added to 1 word address.

For that reason, when communications address offset width is 1 while repeat command is used, part with the same communications address is copied twice.

| Actual address | Internal address |
|----------------|------------------|
| Double word | Single word |
| +0 | +0 |
| +0 (0.5) | +1 |
| +1 | +2 |
| +1 (1.5) | +3 |

Address originally set for functional object

Omit figures below decimal 0.5->0

Omit figures below decimal 0.5->0

For that reason, set always offset in multiples of 2 to specify communications address with single word access.

Section 3

Connection via Memory Link

This chapter explains the Memory Link function and how to use it to connect host computer.

3-1How does Memory Link work

3-2Setup

3-3Communications procedures

3-4What has been changed since NS31/631

3-1 How does Memory Link work

3-1-1 PT memory

With Memory Link you assign objects word and bit to PT memory. PT memory is an imaginary PLC area inside the NS. NS performs read/write operations to internal PT memory. Host reads/writes PT memory as required and so controls and monitors NS.

PT memory consists of 2 territories: Bit (\$B) and Word (\$W).

PT memory can be also used to store functional object display character strings or as data area for the macro function.

3-1-2 Command and response

With Memory Link, the following commands enable data transmission between host and PT.

- Read-out command / response

This is the command for reading out PT memory of PT.

When host gives command, PT responds the contents of the designated data.

There are 2 commands that vary with the type of PT memory.

| Command | Title | Action |
|---------|--------------------------|--------------------------------|
| RM | Read out PT (\$W) memory | Read out \$W data in PT memory |
| RB | Read out PT (\$B) memory | Read out \$B data in PT memory |

- Write command/response

This is the command to write designated data to PT memory area in PT.

Host gives command. PT responds whether or not the writing was completed successfully.

The successful completion response may be omitted by particular setting the Response parameter in the communications conditions menu.

The following 4 commands can be given:

| Command | Title | Action |
|---------|--------------------------|---|
| WM | Write to PT memory (\$W) | Write data to PT memory \$W |
| WB | Write to PT memory (\$B) | Write data to PT memory \$B |
| FM | FILL PT memory (\$W) | Write designated data to multiple PT memory \$W |
| FB | FILL PT memory (\$B) | Write designated data (0 or 1) to Multiple PT memory \$B. |

- Notify Command

This is the command to communicate the results of PT operations to host.

PT gives command. For that reason, there is no response.

The following 2 commands can be given.

| command | Title | Action |
|---------|-------------------------------|---------------------------------------|
| SM | PT memory (\$W) change notice | Notify host of PT memory \$W changes. |
| SB | PT memory (\$B) change notice | Notify host of PT memory \$B changes. |

- Error response

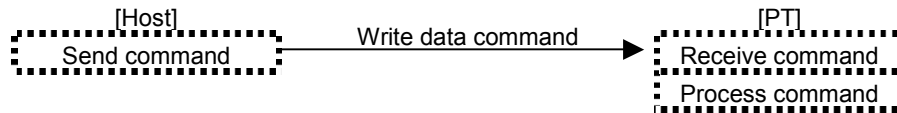
Response from PT when the received command is an invalid one.

| Command | Title | Action |
|---------|----------------|------------------------------|
| ER | Error response | Notify host of command error |

3-1-3 Action when command is used

There are 3 flows of communications between host and PT, depending on the type of command and Response Settings in Communications conditions.

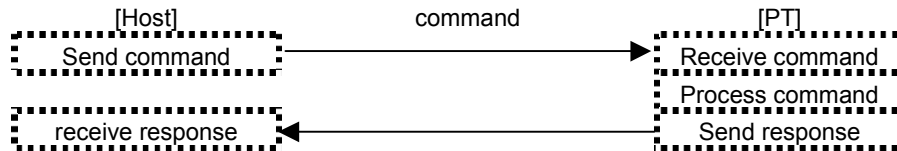
- Write data command while [response: OFF]



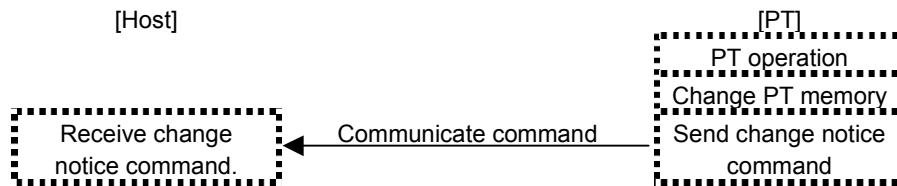
- Write Data command while [response: ON]

- Read-out data command

- Invalid command



- PT to host communications

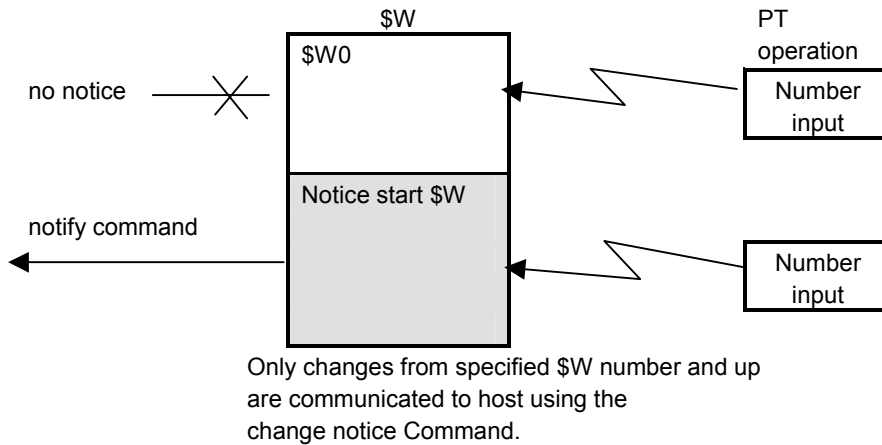


3-1-4 Notify Command Behavior

When anything has changed in the PT memory, by e.g. touch switch operation on PT, numerical input or character string input, PT sends change notice command to host.

In addition to Memory Link connection, PT memory serves other purposes as well. If all changes would be communicated to host, the host would be burdened more than is needed. For that reason, PT communicates only changes from a designated number and up. Changes in PT memory areas with a lower number are not communicated.

Set the number in Communications conditions -> **Start Communication \$B** and **Start Communication &W**.



3-1-4 Flow control

When too many commands are sent, PT cannot process timely. Communications buffer overflows. Commands and command sequence get lost.

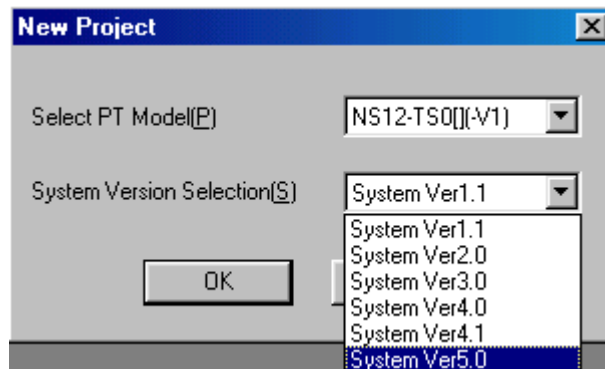
For that reason, set Communications conditions Response to ON when PT to host command interval frequency becomes high.

3-2 Settings

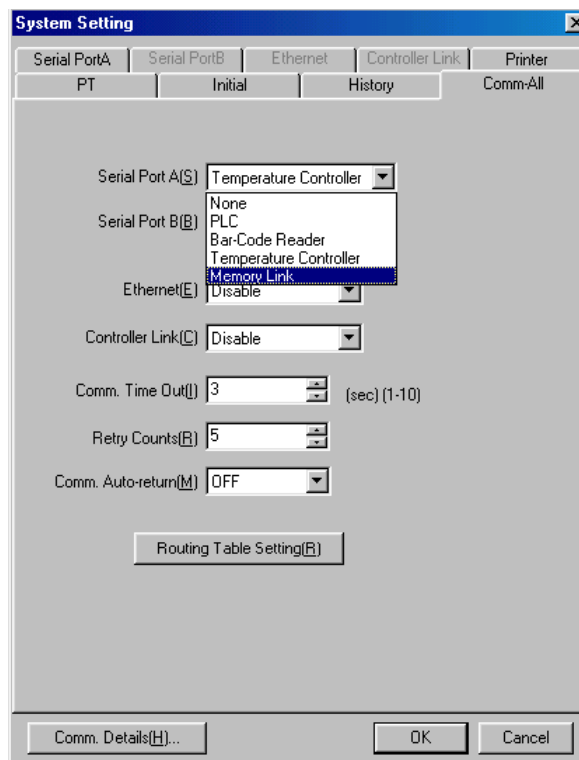
3-2-1 Making settings for the Project

The Memory Link can be used in combination with
NS system program Ver. 5.0 and later versions
System Ver.5.0 projects

With NS-Designer V5.0 and later, you can create and edit project developed by System Ver.5.0 projects.
A project created with NS-Designer Ver. 4.0 or earlier can be opened and converted to the data of Ver.5.0.



In NS-Designer Ver. 5.0 open SystemVer.5.0 project, click **Settings – System Setting**. Select tab '**Comm.– All**' and set Serial Port A (or Serial Port B) to **Memory Link** (select from the pull down menu).



You cannot simultaneously set Serial Port A and B to **Memory Link**.

3-2-2 Communications conditions setting

In NS-Designer, select tab 'Comm.-All' Serial Port A (or Serial Port B) and set to the following communications conditions.

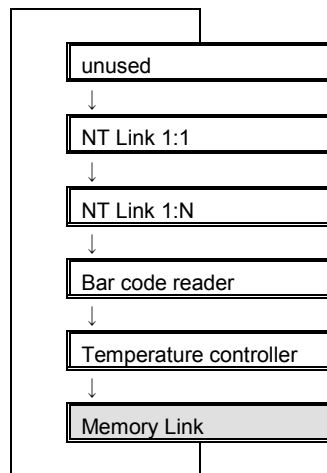
| Parameter | Set value | Default value |
|------------------|-------------------------------|---------------|
| Baud rate | 9600bps / 19200bps / 38400bps | 9600bps |
| Data bits | 7 / 8 | 7 |
| Stop bits | 1 / 2 | 1 |
| Parity | None / even / odd | none |
| response | OFF / ON | OFF |
| Notice start \$B | 0 to 32767 | 16384 |
| Notice start \$W | 0 to 32767 | 16384 |

3-2-3 NS system menu operation

You can also use the NS system menu to set the communications conditions for the Memory Link connection.

Under system menu, click tab **Communications Setting**.

By pressing the key beside the Serial Port A or Serial Port B, you can switch between communications methods.



After you have thus set communications to Memory Link, use the **Details** key to set the communications conditions for the Memory Link connection (for details, refer to section 2.2). However, with system menu you cannot set the **Notice start \$B** and **Notice start \$W**.

Set values are not saved until you press the **Write** key. Also, setting changes will be effective when you turn the power OFF and then ON again.

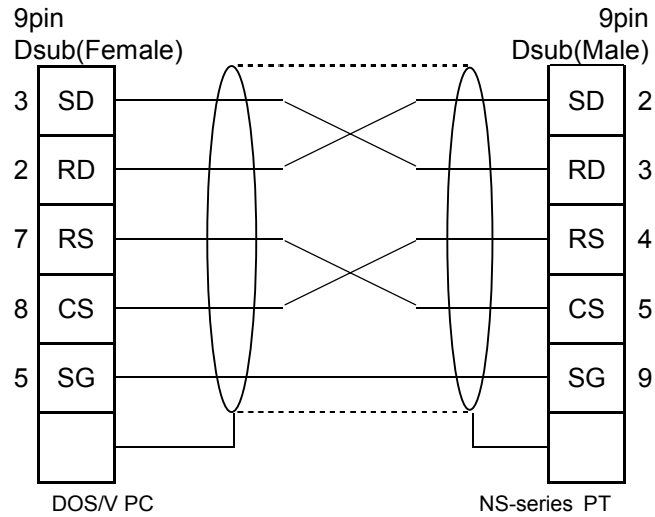
3-2-4 Connection Diagram

Use either NS Serial Port A or B to connect host computer via Memory Link.

You cannot simultaneously set Serial Port A and B to Memory Link.

The connecting cable varies with the specifications of the host computer communications port.

Below is a typical example, which shows the wiring diagram when DOS/V PC is connected.



Above wiring is identical with the NS to and from NS-Designer wiring.

If the cable length is conform, you can use the following cable with connector.

| | |
|-----------|---|
| XW2Z-S002 | Omron product Cable length 2m, 9 pin↔9 pin |
|-----------|---|

3-3 Communications procedures

3-3-1 Memory Link Commands

Command/response formats are as mentioned below.

- Read/write/change notify command

| | | | | | | | |
|-----|---------|----|----|----|----|-----|----|
| ESC | command | *S | *A | *L | *D | SUM | CR |
|-----|---------|----|----|----|----|-----|----|

- Read/write command (In above-mentioned format, the *L is regarded as 1 (fixed))

| | | | | | | |
|-----|---------|----|----|----|-----|----|
| ESC | command | *S | *A | *D | SUM | CR |
|-----|---------|----|----|----|-----|----|

- Write all (FILL) command

| | | | | | | | |
|-----|---------|----|----|----|----|-----|----|
| ESC | command | *S | *A | *B | *D | SUM | CR |
|-----|---------|----|----|----|----|-----|----|

- Read type command normal completion response format

| | | | | | | |
|-----|---------|----|----|----|-----|----|
| ESC | command | *A | *L | *D | SUM | CR |
|-----|---------|----|----|----|-----|----|

- Other responses

| | | | | |
|-----|---------|----|-----|----|
| ESC | command | *D | SUM | CR |
|-----|---------|----|-----|----|

| ESC | (\$1B) | Initial Command: ESC(\$1B) fixed |
|---------|--------------------------------------|--|
| command | 2 characters | 1 English capital letters which display the type of command |
| *S | 1 character | Designates SUM omission and *L omission. In some cases, specifies write to memory attributes as well. SUM OFF: SUM computing by host can be omitted. SUM ON: enables judgment if command is invalid as a result of noise interference. |
| *A | Hexadecimal 4 digits | Initial read/write address |
| *B | Hexadecimal 4 digits | Last Write all (FILL) address |
| *L | BCD 2 digits | Number of read/write elements |
| *D | Variable length | Data section |
| SUM | 2 characters (may be abbreviated) | The checksum of the command response is the 2 digit code in hexadecimal which is indicated using lower one-byte of the total sum from the ESC to the *D. It can be abbreviated by specifying *S. Be sure that it is added when PT is transmitting. |
| CR | (\$0D) | Command end: CR(\$0D) fixed |

Memory Link commands are as follows:

| Command | Command title | Action |
|----------------|-------------------------------|---|
| RM | Read PT memory (\$W) | Read contents of \$W data |
| RB | Read PT memory (\$B) | Read contents of \$B data |
| WM | Write PT memory (\$W) | Write to \$W data |
| WB | Write PT memory (\$B) | Write to \$B data |
| FM | Fill PT memory (\$W) | Fill multiple sequential \$W with the same value |
| FB | Fill PT memory (\$B) | Fill multiple sequential \$B with the same value. |
| SM | PT memory (\$W) change notice | Communicate \$W changes to host |
| SB | PT memory (\$B) change notice | Communicate \$B changes to host |

| | |
|----|----------------------|
| RM | Read PT memory (\$W) |
|----|----------------------|

Read \$W data in PT memory.

Per command, a maximum of 100 words can be read.

Response is up to 50 words per response.

When requesting command is parameter 2: number of words exceeds 51, then the response is split into two. The first response sends 50 words, the second response sends the remaining channels.

When entries were made on NS in between the first and second response, change notice command is not sent until after the second response has been sent.

- Command format

| ESC | command | | *S | *A | | | | *L | SUM | CR |
|------|---------|---|----|----|--|--|--|----|-----|------|
| \$1B | R | M | | | | | | | | \$0D |

[Settings]

| | | | |
|----|--------------|--|---|
| *S | | Sum value | |
| | 0 | OFF | Omit *L. Number of read-out words: 1 (fixed) |
| | 1 | ON | |
| | 8 | OFF | |
| 8 | ON | | |
| *A | 0000 to 7FFF | Initial address No. (hexadecimal 4 digits) | |
| *L | 00 to 99 | Number of read-out words (BCD 2 digits) 00 indicates 100. | |

- Successful completion response format

| ESC | command | | *A | | | | *L | *D | SUM | CR |
|------|---------|---|----|--|--|--|----|-----------------|-----|------|
| \$1B | R | M | | | | | | Variable length | | \$0D |

[Settings]

| | | |
|----|------------------|---|
| *A | 0000 to 7FFF | Initial address No. (hexadecimal 4 digits) |
| *L | 01 to 50 | Number of read-out words (BCD 2 digits) |
| *D | 0 to FFFF “,” | Word data (zero suppressed hexadecimal 1 to 4 digits) From 2 nd word onward, enter comma “,” (\$2C) before the next data. |

| | |
|----|----------------------|
| RB | Read PT memory (\$B) |
|----|----------------------|

Read \$B data in PT memory.

Per command, a maximum of 100 bits can be read.

After reading, bit data are displayed and returned per 8 bits as 8 bit value.

- Command format

| ESC | command | | *S | *A | *L | SUM | CR |
|------|---------|---|----|----|----|-----|------|
| \$1B | R | B | | | | | \$0D |

[Settings]

| | | | |
|----|--------------|---|---|
| *S | BCD1digit | Sum value | |
| | 0 | OFF | Number of tables: 1 (fixed). Omit Parameter2. |
| | 1 | ON | |
| | 8 | OFF | |
| 9 | ON | | |
| *A | 0000 to 7FFF | Initial address No. (hexadecimal 4 digits) | |
| *L | 00 to 99 | Read-out bit number (BCD 2 digits) 00 indicates 100. | |

- Response format

| ESC | command | | *A | *L | *D | SUM | CR |
|------|---------|---|----|----|-----------------|-----|------|
| \$1B | R | B | | | Variable length | | \$0D |

[Settings]

| | | |
|----|--------------|--|
| *A | 0000 to 7FFF | Initial address No. (hexadecimal 4 digits) |
| *L | 00 to 99 | Number of bits (BCD 2 digits) 00 indicates 100. |
| *D | 00 to FF | <p>Bit data (hexadecimal 2 digit value of 8 bits each) 0:OFF, 1: ON</p> <p>Fills addresses in ascending order starting with first digit. Turns 8 bits into a binary 8 digit value and displays this as a hexadecimal 2 digit value. The next hexadecimal 2 digit value continues with the following 8 bits.</p> <p>Fills any of the last 8 bits that does not actually have a valid read-out data with 0.</p> <p>[example]</p> <p>from \$B10 6 bits have read-out value \$B10 11 12 13 14 15 * *</p> <p>1 0 1 0 1 1 0 0 → AC (converted to hexadecimal form)</p> |

| | |
|----|--------------------------|
| WM | Write to PT memory (\$W) |
|----|--------------------------|

Write to \$W data in PT memory.

Per command, a maximum of 50 words can be written.

As writing attribute you can select SET, AND, OR, or XOR.

- Command format

| ESC | command | | *S | *A | | | | *L | *D | SUM | CR |
|------|---------|---|----|----|--|--|--|----|-----------------|-----|------|
| \$1C | W | M | | | | | | | Variable length | | \$0D |

[Settings]

| *S | BCD 1 digit | SUM | Writing attribute | |
|----|---------------------|---|-------------------|---|
| | 0 | OFF | SET | Writes designated value just as it is. |
| | 1 | ON | | |
| | 2 | OFF | AND | Ands present value of destination with designated value and writes outcome. |
| | 3 | ON | | |
| | 4 | OFF | OR | Ors present value of destination with designated value and writes outcome |
| | 5 | ON | | |
| | 6 | OFF | XOR | Xors present value of destination with designated value and writes outcome. |
| | 7 | ON | | |
| | 8 | OFF | SET | Omits *L . Number of destination words : 1 (fixed) |
| 9 | ON | | | |
| *A | 0000 to 7FFF | Initial address number (hexadecimal 4 digits) | | |
| *L | 01 to 50 | Number of destination words (BCD 2 digits) | | |
| *D | 0000 to FFFF “,” | Word data (zero suppressed hexadecimal, 1 to 4 digits) From 2 nd word on, enter comma [,] (\$2C) before next data. Data ending with comma cause error. | | |

- Normal completion response format (only when response under communications conditions is ON).

| ESC | command | | *D | | SUM | CR |
|------|---------|---|----|---|-----|------|
| \$1B | W | M | 0 | 0 | | \$0D |

[Settings]

| | |
|----|--|
| *D | 00 fixed. Indicates successful completion. |
|----|--|

| | |
|----|-----------------------|
| WB | Write PT memory (\$B) |
|----|-----------------------|

Write to \$B data in PT memory.

Per command, a maximum of 50 words can be written.

- Command format

| ESC | command | | *S | *A | | | | *B | *D | SUM | CR |
|------|---------|---|----|----|--|--|--|----|-----------------|-----|------|
| \$1B | W | B | | | | | | | Variable length | | \$0D |

[Settings]

| | | | |
|----|------------|--|---|
| *S | BCD1 digit | SUM value | |
| | 0 | OFF | |
| | 1 | ON | |
| | 8 | OFF | Bit number: 1 fixed. Parameter 2 omitted. |
| | 9 | ON | |
| *A | 0000to7FFF | Initial address number (hexadecimal 4 digits) | |
| *L | 00to99 | Entry bit number (BCD 2 digits) When 00, 100 is meant. | |
| *D | 00 to FF | Bit data (hexadecimal 2 digit value for 8 bits each) 0: OFF, 1: ON Fills data in descending order starting with first digit. Turns 8 bits into a binary 8 digit value and displays this as a hexadecimal 2 digit value. The next hexadecimal 2 digit value continues with the following 8 bits. Fills any of the last 8 bits that does not actually have a valid read-out data with 0. [example] from \$B10, 6 bits have read-out value \$B10 11 12 13 14 15 * * 1 0 1 0 1 1 0 0 → AC (converted to hexadecimal form) | |

- Normal completion response format (only when response under communications conditions is ON).

| ESC | command | | *D | | SUM | CR |
|------|---------|---|----|---|-----|------|
| \$1B | W | B | 0 | 0 | | \$0D |

[Settings]

| | |
|----|--|
| *D | 00 fixed. Indicates normal completion. |
|----|--|

| | |
|----|----------------------|
| FM | Fill PT memory (\$W) |
|----|----------------------|

Fills PT memory \$W with the same word data. Range: first to last address number.

- Command format

| ESC | command | | *S | *A | | | | *B | | | | *D | | | | SUM | CR |
|------|---------|---|----|----|--|--|--|----|--|--|--|----|--|--|--|------|----|
| \$1B | F | M | | | | | | | | | | | | | | \$0D | |

[Settings]

| | | | |
|----|--------------|---|--|
| *S | BCD 1 digit | SUM value | |
| | 0 | OFF | |
| | 1 | ON | |
| *A | 0000 to 7FFF | First address number (hexadecimal 4 digits) | |
| *B | 0000 to 7FFF | Last address number (hexadecimal 4 digits) | |
| *D | 0 to FFFF | Word data (zero suppressed hexadecimal 1 to 4 digits) | |

- Normal completion response format (only when response under communications conditions is ON).

| ESC | command | | *D | | SUM | | CR |
|------|---------|---|----|---|-----|---|------|
| \$1B | F | M | 0 | 0 | 0 | E | \$0D |

[Settings]

| | |
|----|--|
| *D | 00 fixed. Indicates normal completion. |
|----|--|

| | |
|----|----------------------|
| FB | Fill PT memory (\$B) |
|----|----------------------|

Fills PT memory \$B with the same bit data. Range: first to last address number.

- Command format

| ESC | command | | *S | *A | | | | *B | | | | *D | SUM | CR |
|------|---------|---|----|----|--|--|--|----|--|--|--|----|-----|------|
| \$1B | F | B | | | | | | | | | | | | \$0D |

[Settings]

| | | | |
|----|-----------------|---|--|
| *S | BCD 1 digit | SUM value | |
| | 0 | OFF | |
| | 1 | ON | |
| *A | 0000 to 7FFF | Initial address number (hexadecimal 4 digits) | |
| *B | 0000 to 7FFF | Last address number (hexadecimal 4 digits) | |
| *D | 0: OFF 1: ON | Bit data (hexadecimal 1 digit) | |

- Normal completion response format (only when response under communications conditions is ON).

| ESC | command | | *D | | SUM | CR |
|------|---------|---|----|---|-----|------|
| \$1B | F | B | 0 | 0 | | \$0D |

[Settings]

| | |
|----|--|
| *D | 00 fixed. Indicates normal completion. |
|----|--|

| | |
|----|-------------------------------|
| SM | PT memory (\$W) change notice |
|----|-------------------------------|

When PT memory \$W changed as a result of PT operation and when this \$W address is higher than the address designated with Notice start \$W in the communications settings menu, this command is sent from PT to host.

Response from host to PT is not needed.

When sent from host to PT, illegal command error occurs.

- Command format

| ESC | command | | *A | | | | *L | | *D | SUM | | CR |
|------|---------|---|----|--|--|--|----|--|-----------------|-----|--|------|
| \$1B | S | M | | | | | | | Variable length | | | \$0D |

[Settings]

| | | |
|----|-----------------------|--|
| *A | 0000 to 7FFF | Changed address number (hexadecimal 4 digits) |
| *L | 01 to 50 | Number of changed words (BCD 2 digits) |
| *D | 0000 to FFFF “ , ” | Word data (zero suppressed hexadecimal 1 to 4 digits) Divide multiple word data by comma [,] (\$2C). Data ending with comma cause error. |

| | |
|----|-------------------------------|
| SB | PT memory (\$B) change notice |
|----|-------------------------------|

When PT memory \$B changed as a result of PT operation and when this \$B address is higher than the address designated with Notice start \$B in the communications settings menu, this command is sent from PT to host.

Response from host to PT is not needed.

When sent from host to PT, illegal command error occurs.

- Command format

| ESC | command | | *A | | | | *B | | *D | SUM | | CR |
|------|---------|---|----|--|--|--|----|---|----|-----|--|------|
| \$1B | S | B | | | | | 0 | 1 | | | | \$0D |

[Settings]

| | | |
|----|-----------------|---|
| *A | 0000 to 7FFF | Changed address number (hexadecimal 4 digits) |
| *B | 01 fixed | Number of changed bits (hexadecimal 2 digits) |
| *D | 0: OFF 1: ON | Bit data (hexadecimal 1 digit) |

| | |
|----|----------------|
| ER | Error response |
|----|----------------|

- Command format

| | | | | |
|------|---------|----|-----|------|
| ESC | command | *D | SUM | CR |
| \$1B | E | R | | \$0D |

[Settings]

| | |
|----|---|
| *D | Error codes listed below (hexadecimal 2 digits) |
|----|---|

| Error code | Error contents | cause |
|------------|-------------------------|---|
| 01 | Illegal command | Command contents lie outside the supported range |
| 02 | Command length error | Length of received command is illegal for that command. |
| 03 | Boundary value error | <ul style="list-style-type: none"> • Value set to parameter lies outside the supported range. • Parameter in BCD format includes others than 0 to 9 |
| 04 | Illegal operand | Sum information Set value lies outside the effective range. |
| 05 | Command format error | \$W/\$B command; Data section includes characters other than 0 to F and “,”. \$W command; data section ends with “,”. |
| 10 | SUM value error | Command with sum value ON. Computed sum value and the one in the command do not match. |
| 12 | Reception timeout error | After the initial ESC was received, the interval in between receiving one byte after the other until command end [CR] exceeded timeout monitoring time. |

These commands are sent from NS to host when the host sent an invalid command and when a communications error occurred.

3-4 What has changed

3-4-1 Memory Link Commands

This summarizes the points that need to be given attention when switching over from NT31/631 series to NS series Memory Link.

Memory structure inside PT differs, so the structure of Memory Link commands has changed as well.

■ Memory structure inside PT

| | NT31/631 series | | NS series | |
|----------------|--|------------------------|------------------|---------------|
| PT memory | Contact point | common 0000 to 9999 | Contact point | \$B0 to 65535 |
| | channel | | channel | \$W0 to 65535 |
| Memory table | Number memory table Character string memory table bit memory table | | none | |
| Battery backup | Is performed | | Is not performed | |

■ Memory Link command

| | NT31/631 series | NS series |
|----|--|-------------------------------|
| RM | Read-out PT memory | Read-out PT memory (\$W) |
| RB | Read-out bit memory table | Read-out PT memory (\$B) |
| RN | Read-out number memory table | - |
| RS | Read-out character string memory table | - |
| WM | Write to PT memory | Write to PT memory (\$W) |
| WB | Write to bit memory table | Write to PT memory (\$B) |
| FR | Read-out display data comment | - |
| PT | Read-out system conditions | - |
| WN | Write to number memory table | - |
| WS | Write to character string memory table | - |
| FM | Fill PT memory | Fill PT memory (\$W) |
| FB | - | Fill PT memory (\$B) |
| CN | Clear number memory table | - |
| CS | Clear character string memory table | - |
| CB | Clear bit memory table | - |
| ST | Touch switch input notice | - |
| SN | Number input notice | - |
| SS | Character string input notice | - |
| PM | Direct area change notice | - |
| SM | PT memory change notice | PT memory (\$W) change notice |
| SB | - | PT memory (\$B) change notice |
| MC | Switch PT operating mode | - |
| RR | Request resend | - |
| ER | Error response | Error response |

■ Execution of contact notice to \$W

While NT31/631 performs contact point change notice and channel change notice in the same PT memory, the NS splits it into \$B and \$W

There, the use of a macro, enables the contact point notice to \$W.

E.g. Momentary switch sending notice to 5th bit in \$W1000

- Create ON/OFF button
- Designate \$B address that is not specified for any other purpose.
Destination address may be blank, but in that case the button does not light when it is being pressed down.
- Edit macro (touch ON)
`$W1000 = $W1000 | H10;`
- Edit macro (touch OFF)
`$W1000 = $W1000 & to H10;`

■ PT memory hold

Battery backup in NT31/631 ensures that PT memory and memory table values are kept as they were when the power goes off.

Contrary to NT31/631, NS has no battery backup and consequently values are cleared when the power is turned off.

NS cannot react to an unexpected power fall out, but there is a possibility to store values before the power is turned OFF.

You can save a copy of PT memory \$W by saving the contents of this memory as a file on a compact flash card. Then removes this card.

As it is a file reading/writing operation to a compact flash card, it cannot be done frequently. In addition, you cannot save a copy of the PT memory \$B.

E.g. Manually save the PT memory \$W contents.

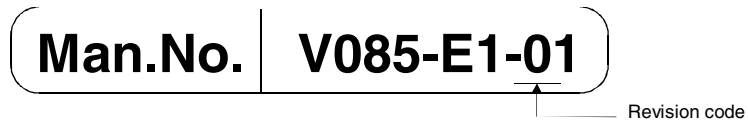
- Create a command button
- Set function selection to No processing
- Edit macro (touch ON)
`WRITECF($W16384,16384,"PTMEM.DAT",0);`

E.g. Recover PT memory \$W contents from saved file when PT is started up.

- Edit macro when project is started up
`READCF($W16384,16384,"PTMEM.DAT",0);`

Revision History

A manual revision code appears as a suffix to the catalog number on the cover of the manual.



The following table outlines the changes made to the manual during each revision. Page numbers refer to the previous version.

| Revision code | Date | Revised content |
|---------------|--------------|---------------------|
| 01 | October 2003 | Original production |

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