Cat. No. W342-E1-11

Communications Commands

REFERENCE MANUAL

OMRON

SYSMAC CS/CJ/CP Series

CS1G/H-CPU☐☐H
CS1G/H-CPU☐☐-EV1
CS1D-CPU☐☐H
CS1D-CPU☐☐S
CS1W-SCB☐☐-V1
CS1W-SCU☐☐-V1
CJ1G/H-CPU☐☐H
CJ1G-CPU☐☐P
CJ1G-CPU☐☐
CJ1M-CPU☐☐
CJ1W-SCU☐☐-V1
CP1H-X☐☐☐☐-☐
CP1H-XA☐☐☐☐-☐
CP1H-Y☐☐☐☐-☐

SYSMAC One NSJ Series

NSJ☐-☐☐☐☐-G5D
NSJ☐-☐☐☐☐-M3D

Communications Commands

Reference Manual

Revised October 2006

Notice:

OMRON products are manufactured for use according to proper procedures by a qualified operator and only for the purposes described in this manual.

The following conventions are used to indicate and classify precautions in this manual. Always heed the information provided with them. Failure to heed precautions can result in injury to people or damage to property.

⚠ **DANGER** Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury. Additionally, there may be severe property damage.

⚠ **WARNING** Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury. Additionally, there may be severe property damage.

⚠ **Caution** Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or property damage.

OMRON Product References

All OMRON products are capitalized in this manual. The word "Unit" is also capitalized when it refers to an OMRON product, regardless of whether or not it appears in the proper name of the product.

The abbreviation "Ch," which appears in some displays and on some OMRON products, often means "word" and is abbreviated "Wd" in documentation in this sense.

The abbreviation "PLC" means Programmable Controller. "PC" is used, however, in some Programming Device displays to mean Programmable Controller.

Visual Aids

The following headings appear in the left column of the manual to help you locate different types of information.

Note Indicates information of particular interest for efficient and convenient operation of the product.

1,2,3... 1. Indicates lists of one sort or another, such as procedures, checklists, etc.
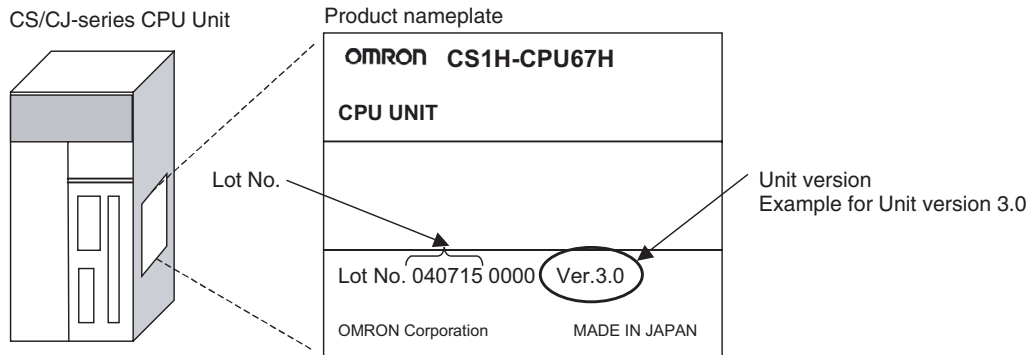
Unit Versions of CS/CJ/CP-series CPU Units and NSJ Controllers

Unit Versions

A "unit version" has been introduced to manage CPU Units in the CS/CJ Series and CP Series, as well as NSJ Controllers, according to differences in functionality accompanying Unit upgrades. The CS/CJ Series includes the CS1-H, CJ1-H, CJ1M, and CS1D CPU Units.

Notation of Unit Versions on Products

The unit version is given to the right of the lot number on the nameplate of the products for which unit versions are being managed, as shown below.

CS/CJ-series CPU Unit

Product nameplate

OMRON CS1H-CPU67H

CPU UNIT

Lot No.

Lot No. 040715 0000   Ver.3.0

OMRON Corporation   MADE IN JAPAN

Unit version
Example for Unit version 3.0

- CS1-H, CJ1-H, and CJ1M CPU Units (except for low-end models) manufactured on or before November 4, 2003 do not have a unit version given on the CPU Unit (i.e., the location for the unit version shown above is blank).
- The unit version of the CS1-H, CJ1-H, and CJ1M CPU Units, as well as the CS1D CPU Units for Single-CPU Systems, begins at version 2.0.
- The unit version of the CS1D CPU Units for Duplex-CPU Systems, begins at version 1.1.
- Unit versions for CP1H PLCs start at version 1.0.
- Unit versions for NSJ Controllers start at version 3.0.
- CPU Units for which a unit version is not given are called *Pre-Ver. □.□ CPU Units, such as Pre-Ver. 2.0 CPU Units and Pre-Ver. 1.1 CPU Units*.

Confirming Unit Versions with Support Software

CX-Programmer version 4.0 or later can be used to confirm the unit version using one of the following two methods.

- Using the **PLC Information**
- Using the **Unit Manufacturing Information** (This method can be used for Special I/O Units and CPU Bus Units as well.)

Note CX-Programmer version 3.3 or lower cannot be used to confirm unit versions.

PLC Information

- If you know the device type and CPU type, select them in the *Change PLC* Dialog Box, go online, and select **PLC - Edit - Information** from the menus.
- If you don't know the device type and CPU type, but are connected directly to the CPU Unit on a serial line, select **PLC - Auto Online** to go online, and then select **PLC - Edit - Information** from the menus.

In either case, the following *PLC Information* Dialog Box will be displayed.
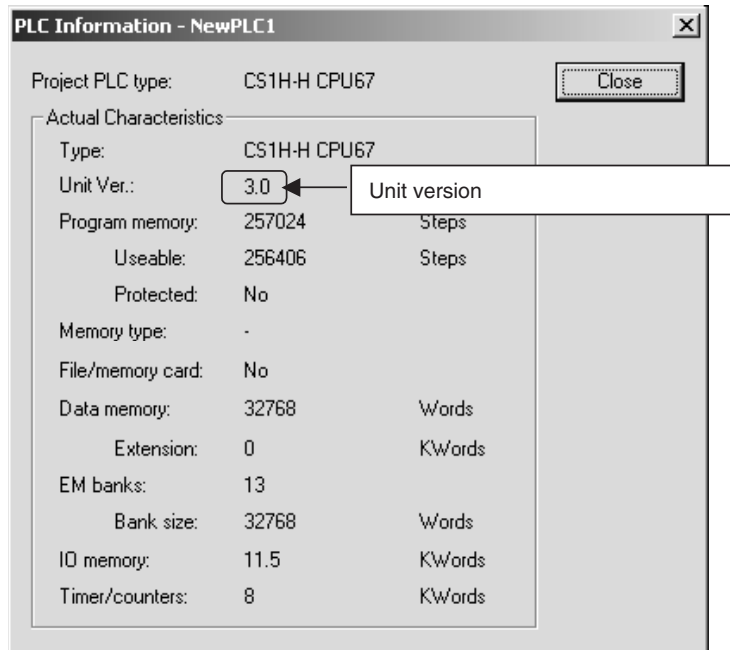
Use the above display to confirm the unit version of the CPU Unit.

<u>**Unit Manufacturing Information**</u>

In the IO Table Window, right-click and select **Unit Manufacturing information - CPU Unit.**
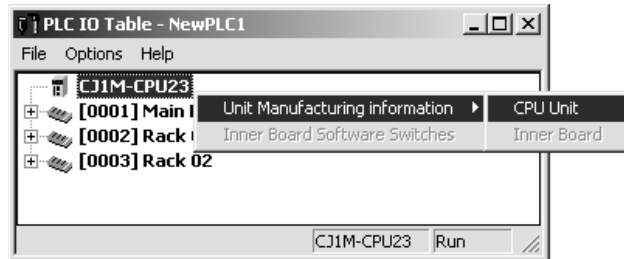
The following *Unit Manufacturing information* Dialog Box will be displayed.
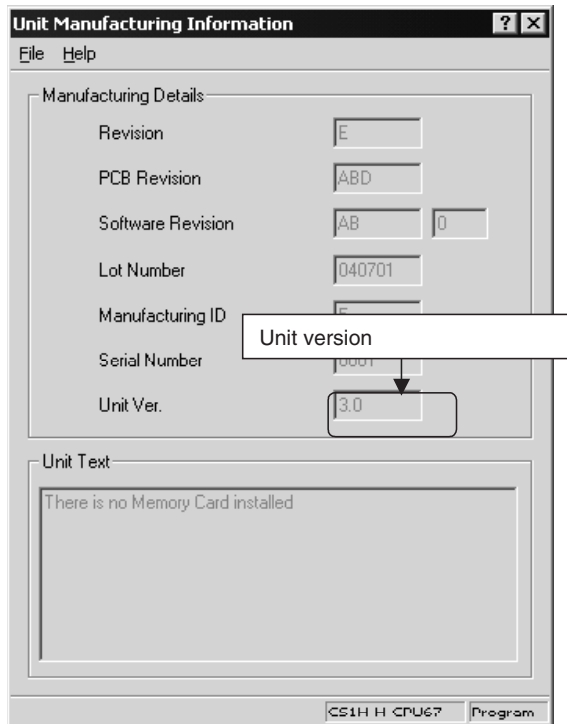
Use the above display to confirm the unit version of the CPU Unit connected online.

Using the Unit Version Labels
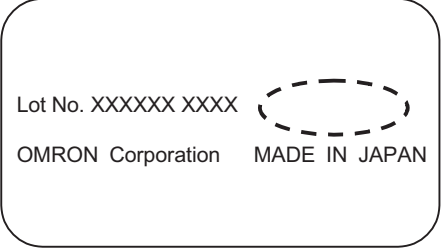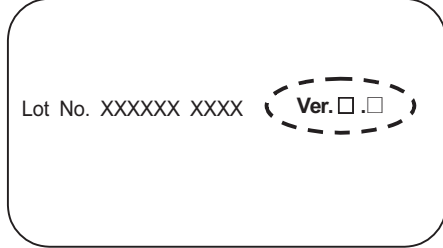
The following unit version labels are provided with the CPU Unit.
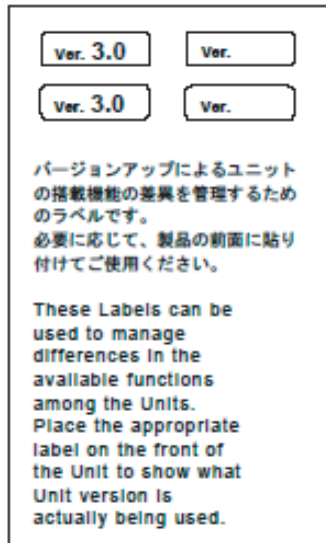
These labels can be attached to the front of previous CPU Units to differentiate between CPU Units of different unit versions.

Unit Version Notation

In this manual, the unit version of a CPU Unit is given as shown in the following table.

Product nameplate Meaning	CPU Units on which no unit version is given Lot No. XXXXXX XXXX OMRON Corporation MADE IN JAPAN	Units on which a version is given (Ver. □.□) Lot No. XXXXXX XXXX **Ver.□.□**
Designating individual CPU Units (e.g., the CS1H-CPU67H)	Pre-Ver. 2.0 CS1-H CPU Units	CS1H-CPU67H CPU Unit with unit version □.□
Designating groups of CPU Units (e.g., the CS1-H CPU Units)	Pre-Ver. 2.0 CS1-H CPU Units	CS1-H CPU Units with unit version □.□
Designating an entire series of CPU Units (e.g., the CS-series CPU Units)	Pre-Ver. 2.0 CS-series CPU Units	CS-series CPU Units with unit version □.□

Unit Versions

CS-series CPU Units

Unit	Model	Unit version
CS1-H CPU Units	CS1□-CPU□□H	Unit version 4.0
		Unit version 3.0
		Unit version 2.0
		Pre-Ver. 2.0
CS1D CPU Units	CS1D-CPU□□H for Duplex-CPU System	Unit version 1.2
		Unit version 1.1
		Pre-Ver. 1.1
	CS1D-CPU□□S for Simplex-CPU System	Unit version 2.0
CS1 CPU Units	CS1□-CPU□□	No unit version
CS1-V1CPU Units	CS1□-CPU□□-V1	No unit version

CJ-series CPU Units

Unit	Model	Unit version
CJ1-H CPU Units	CJ1□-CPU□□H CJ1□-CPU□□P	Unit version 4.0
		Unit version 3.0
		Unit version 2.0
		Pre-Ver. 2.0
CJ1M CPU Units	CJ1M-CPU12/13 CJ1M-CPU22/23	Unit version 4.0
		Unit version 3.0
		Unit version 2.0
		Pre-Ver. 2.0
	CJ1M-CPU11/21	Unit version 4.0
		Unit version 3.0
		Unit version 2.0

CP-series CPU Units

Unit	Model	Unit version
CP1H CPU Units	CP1H-X□□□□-□ CP1H-XA□□□□-□ CP1H-**Y**□□□□-□	Unit version 1.1
		Unit version 1.0

NSJ Controllers

Unit	Unit version
NSJ□-□□□□**(B)-G5D** NSJ□-□□□□**(B)-M3D**	Unit version 3.0

CS/CJ-series Function Support According to Unit Versions

Functions Supported by Unit Version 4.0 or Later

CX-Programmer version 7.0 or higher must be used to enable using functions added for unit version 4.0.

CS1-H CPU Units (CS1□-CPU□□H)

Function		Unit version	
		Ver. 4.0 or later	Other unit versions
Online editing of function blocks **Note** This function cannot be used for simulations on the CX-Simulator.		OK	---
Using input-output variables in function blocks		OK	---
Using text strings (STRING data type) in function blocks		OK	---
New Application Instructions	Number-Text String Conversion Instructions: NUM4, NUM8, NUM16, STR4, STR8, and STR16	OK	---
	TEXT FILE WRITE (TWRIT)	OK	---

CS1D CPU Units

Unit version 4.0 is not supported.

CJ1-H/CJ1M CPU Units (CJ1□-CPU□□H, CJ1G-CPU□□P, CJ1M-CPU□□)

Function		Unit version	
		Ver. 4.0 or later	Other unit versions
Online editing of function blocks **Note** This function cannot be used for simulations on the CX-Simulator.		OK	---
Using input-output variables in function blocks		OK	---
Using text strings (STRING data type) in function blocks		OK	---
New Application Instructions	Number-Text String Conversion Instructions: NUM4, NUM8, NUM16, STR4, STR8, and STR16	OK	---
	TEXT FILE WRITE (TWRIT)	OK	---

Functions Supported by Unit Version 3.0 or Later

CX-Programmer version 5.0 or higher must be used to enable using functions added for unit version 3.0.

CS1-H CPU Units (CS1☐-CPU☐☐H)

Function		Unit version	
		Ver. 3.0 or later	Other unit versions
Function blocks (supported for CX-Programmer Ver. 5.0 or higher)		OK	---
Serial Gateway (converting FINS commands to CompoWay/F commands at the built-in serial port)		OK	---
Comment memory (in internal flash memory)		OK	---
Expanded simple backup data		OK	---
New Application Instructions	TXDU(256), RXDU(255) (support no-protocol communications with Serial Communications Units with unit version 1.2 or later)	OK	---
	Model conversion instructions: XFERC(565), DISTC(566), COLLC(567), MOVBC(568), BCNTC(621)	OK	---
	Special function block instructions: GETID(286)	OK	---
Additional instruction functions	TXD(235) and RXD(236) instructions (support no-protocol communications with Serial Communications Boards with unit version 1.2 or later)	OK	---

CS1D CPU Units   Unit version 3.0 is not supported.

CJ1-H/CJ1M CPU Units (CJ1☐-CPU☐☐H, CJ1G-CPU☐☐P, CJ1M-CPU☐☐)

Function		Unit version	
		Ver. 3.0 or later	Other unit versions
Function blocks (supported for CX-Programmer Ver. 5.0 or higher)		OK	---
Serial Gateway (converting FINS commands to CompoWay/F commands at the built-in serial port)		OK	---
Comment memory (in internal flash memory)		OK	---
Expanded simple backup data		OK	---
New Application Instructions	TXDU(256), RXDU(255) (support no-protocol communications with Serial Communications Units with unit version 1.2 or later)	OK	---
	Model conversion instructions: XFERC(565), DISTC(566), COLLC(567), MOVBC(568), BCNTC(621)	OK	---
	Special function block instructions: GETID(286)	OK	---
Additional instruction functions	PRV(881) and PRV2(883) instructions: Added high-frequency calculation methods for calculating pulse frequency. (CJ1M CPU Units only)	OK	---

Functions Supported by Unit Version 2.0 or Later

CX-Programmer version 4.0 or higher must be used to enable using functions added for unit version 2.0.

CS1-H CPU Units (CS1□-CPU□□H)

Function		Unit version	
		CPU Unit with unit version 2.0 or later	**Other unit versions**
Downloading and Uploading Individual Tasks		OK	OK
Improved Read Protection Using Passwords		OK	OK
Write Protection from FINS Commands Sent to CPU Units via Networks		OK	OK
Online Network Connections without I/O Tables		OK	OK
Communications through a Maximum of 8 Network Levels		OK	OK
Connecting Online to PLCs via NS-series PTs		OK	OK from lot number 030201
Setting First Slot Words		OK for up to 64 groups	OK for up to 8 groups
Automatic Transfers at Power ON without a Parameter File		OK	---
Automatic Detection of I/O Allocation Method for Automatic Transfer at Power ON		---	---
Operation Start/End Times		OK	---
New Application Instructions	MILH, MILR, MILC	OK	---
	=DT, <>DT, <DT, <=DT, >DT, >=DT	OK	---
	BCMP2	OK	---
	GRY	OK	OK from lot number 030201
	TPO	OK	---
	DSW, TKY, HKY, MTR, 7SEG	OK	---
	EXPLT, EGATR, ESATR, ECHRD, ECHWR	OK	---
	Reading/Writing CPU Bus Units with IORD/IOWR	OK	OK from lot number 030418
	PRV2	---	---

CS1D CPU Units

Function		CS1D CPU Units for Single-CPU Systems (CS1D-CPU□□S)	CS1D CPU Units for Duplex-CPU Systems (CS1D-CPU□□H)	
		CPU Unit with unit version 2.0 or later	Ver. 1.1 CPU Units or later	Other unit versions
Functions unique to CS1D CPU Units	Duplex CPU Units	OK	OK	OK
	Online Unit Replacement	OK	OK	OK
	Duplex Power Supply Units	OK	OK	OK
	Duplex Controller Link Units	OK	OK	OK
	Duplex Ethernet Units	OK	OK	---
	Replacing Units without Programming Device	---	OK (Unit version 1.2 or later only)	---
Downloading and Uploading Individual Tasks		OK	---	---
Improved Read Protection Using Passwords		OK	---	---
Write Protection from FINS Commands Sent to CPU Units via Networks		OK	---	---
Online Network Connections without I/O Tables		OK	---	---
Communications through a Maximum of 8 Network Levels		OK	---	---
Connecting Online to PLCs via NS-series PTs		OK	---	---
Setting First Slot Words		OK for up to 64 groups	---	---
Automatic Transfers at Power ON without a Parameter File		OK	---	---
Automatic Detection of I/O Allocation Method for Automatic Transfer at Power ON		---	---	---
Operation Start/End Times		OK	OK	---
New Application Instructions	MILH, MILR, MILC	OK	---	---
	=DT, <>DT, <DT, <=DT, >DT, >=DT	OK	---	---
	BCMP2	OK	---	---
	GRY	OK	---	---
	TPO	OK	---	---
	DSW, TKY, HKY, MTR, 7SEG	OK	---	---
	EXPLT, EGATR, ESATR, ECHRD, ECHWR	OK	---	---
	Reading/writing CPU Bus Units with IORD/IOWR	OK	---	---
	PRV2	---	---	---

CJ1-H/CJ1M CPU Units

Function		CJ1-H CPU Units (CJ1☐-CPU☐☐H, CJ1G-CPU☐☐P)		CJ1M CPU Units (CJ1M-CPU12/13/22/23)		CJ1M CPU Units (CJ1M-CPU11/21)
		CPU Units with unit version 2.0 or later	Other unit versions	CPU Units with unit version 2.0 or later	Other unit versions	CPU Units with unit version 2.0 or later
Downloading and Uploading Individual Tasks		OK	---	OK	---	OK
Improved Read Protection Using Passwords		OK	---	OK	---	OK
Write Protection from FINS Commands Sent to CPU Units via Networks		OK	---	OK	---	OK
Online Network Connections without I/O Tables		OK	OK, but only if I/O table allocation at power ON is set	OK	OK, but only if I/O table allocation at power ON is set	OK
Communications through a Maximum of 8 Network Levels		OK	---	OK	---	OK
Connecting Online to PLCs via NS-series PTs		OK	OK from lot number 030201	OK	OK from lot number 030201	OK
Setting First Slot Words		OK for up to 64 groups	OK for up to 8 groups	OK for up to 64 groups	OK for up to 8 groups	OK for up to 64 groups
Automatic Transfers at Power ON without a Parameter File		OK	---	OK	---	OK
Automatic Detection of I/O Allocation Method for Automatic Transfer at Power ON		OK	---	OK	---	OK
Operation Start/End Times		OK	---	OK	---	OK
New Application Instructions	MILH, MILR, MILC	OK	---	OK	---	OK
	=DT, <>DT, <DT, <=DT, >DT, >=DT	OK	---	OK	---	OK
	BCMP2	OK	---	OK	OK	OK
	GRY	OK	OK from lot number 030201	OK	OK from lot number 030201	OK
	TPO	OK	---	OK	---	OK
	DSW, TKY, HKY, MTR, 7SEG	OK	---	OK	---	OK
	EXPLT, EGATR, ESATR, ECHRD, ECHWR	OK	---	OK	---	OK
	Reading/Writing CPU Bus Units with IORD/IOWR	OK	---	OK	---	OK
	PRV2	---	---	OK, but only for models with built-in I/O	---	OK, but only for models with built-in I/O

CP-series Function Support According to Unit Versions

CP1H CPU Units

Function		Unit version	
		CPU Unit with unit version 1.1	**CPU Unit with unit version 1.0**
Pulse outputs	Four axes, 100 kHz	OK	---
	Two axes at 100 kHz and two axes as 30 kHz	---	OK

Unit Versions and Programming Devices

The following tables show the relationship between unit versions and CX-Programmer versions.

CS/CJ-series CPU Units

CPU Unit	Functions		CX-Programmer				Programming Console
			Ver. 3.3	**Ver. 4.0**	**Ver. 5.0 Ver. 6.0**	**Ver. 7.0 or higher**	
CS/CJ-series CPU Unit with unit version 4.0	Functions added for unit version 4.0	Using new functions	---	---	---	OK	No restrictions
		Not using new functions	OK	OK	OK	OK	
CS/CJ-series CPU Unit with unit version 3.0	Functions added for unit version 3.0	Using new functions	---	---	OK	OK	
		Not using new functions	OK	OK	OK	OK	
CS/CJ-series CPU Unit with unit version 2.0	Functions added for unit version 2.0	Using new functions	---	OK	OK	OK	
		Not using new functions	OK	OK	OK	OK	
CS1D CPU Units for Single-CPU Systems with unit version 2.0	Functions added for unit version 2.0	Using new functions	---	OK	OK	OK	
		Not using new functions					
CS1D CPU Units for Duplex-CPU Systems with unit version 1.1	Functions added for unit version 1.1	Using new functions	---	OK	OK	OK	
		Not using new functions	OK	OK	OK	OK	

Note If the functions added for a new version are not used, there is no need to using the new version of the CX-Programmer.

CP Series CX-Programmer version 6.1 or higher must be used for CP-series CPU Units with either unit version 1.0 or 1.1.

NSJ Series CX-Programmer version 6.1 or higher must be used for NSJ Controllers with model numbers ending in -G5D and CX-Programmer version 7.0 or higher must be used for NSJ Controllers with model numbers ending in -M3D.

Device Type Settings   The unit version does not have to be considered when setting the *Device Type* in the Change PLC Dialog Box in CX-Programmer. Set the device type as shown in the following table, ignoring the unit version.

Series	CPU Unit group	CPU Unit model	*Device Type* setting in Change PLC Dialog Box in CX-Programmer version 4.0 or higher
CS Series	CS1-H CPU Units	CS1G-CPU☐☐H	CS1G-H
		CS1H-CPU☐☐H	CS1H-H
	CS1D CPU Units for Duplex-CPU Systems	CS1D-CPU☐☐H	CS1D-H (or CS1H-H)
	CS1D CPU Units for Single-CPU Systems	CS1D-CPU☐☐S	CS1D-S
CJ Series	CJ1-H CPU Units	CJ1G-CPU☐☐H	CJ1G-H
		CJ1H-CPU☐☐H	CJ1H-H
	CJ1M CPU Units	CJ1M-CPU☐☐	CJ1M
CP Series	CP1H CPU Units	CP1H-X☐☐☐☐-☐	CP1H (CPU type: X)
		CP1H-XA☐☐☐☐-☐	CP1H (CPU type: XA)
		CP1H-Y☐☐☐☐-☐	CP1H (CPU type: Y)
NSJ Series	NSJ Controllers	NSJ☐-☐☐☐☐ (B)-G5D	NSJ (CPU type: G5D)
		NSJ☐-☐☐☐☐ (B)-M3D	NSJ (CPU type: M3D)

Troubleshooting Problems with Unit Versions on the CX-Programmer

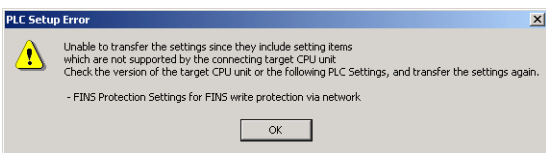| Problem	Cause	Solution
After the above message is displayed, a compiling error will be displayed on the *Compile* Tab Page in the Output Window.	An attempt was made to download instructions supported only by later unit versions to a CPU Unit with an earlier unit version.	Check the program or change the CPU Unit being downloaded to a later unit version.
	An attempt was made to download PLC Setup settings supported only by later unit versions to a CPU Unit with an earlier unit version. (New settings can be downloaded, however, if they are set to their default values.)	Check the settings in the PLC Setup or change the CPU Unit being downloaded to a later unit version.
"????" is displayed in a program transferred from the PLC to the CX-Programmer.	An attempt was made to upload instructions supported only by a higher version of CX-Programmer to a lower version of CX-Programmer.	Uploading unsupported instructions is not possible. Use a higher version of CX-Programmer.

TABLE OF CONTENTS

About this Manual:

This manual describes the C-series (Host Link) and FINS communications commands used with CS/CJ-series and CP-series Programmable Controllers (PLCs) and NSJ Controllers, and includes the sections described below.

Please read this manual and all related manuals listed in the following table and be sure you understand information provided before attempting to design or implement communications for CS/CJ-series or CP-series Programmable Controllers (PLCs) or NSJ Controllers.

Name	Cat. No.	Contents
SYSMAC CS/CJ/CP/NSJ Series CS1G/H-CPU□□-EV1, CS1G/H-CPU□□H, CS1D-CPU□□H, CS1D-CPU□□S, CJ1G-CPU□□, CJ1M-CPU□□, CJ1G-CPU□□P, CJ1G/H-CPU□□H, CS1W-SCU□□-V1, CS1W-SCB□□-V1, CJ1W-SCU□□-V1, CP1H-X□□□□-□, CP1H-XA□□□□-□, CP1H-Y□□□□-□, NSJ□-□□□□(B)-G5D, NSJ□-□□□□(B)-M3D Communications Commands Reference Manual	W342	Describes the communications commands used with CS-series, CJ-series, and CP-series PLCs and NSJ Controllers. (This manual)
SYSMAC CS/CJ/NSJ Series CS1G/H-CPU□□-EV1, CS1G/H-CPU□□H, CS1D-CPU□□H, CS1D-CPU□□S, CJ1G-CPU□□, CJ1M-CPU□□, CJ1G-CPU□□P, CJ1G/H-CPU□□H, NSJ□-□□□□(B)-G5D, NSJ□-□□□□(B)-M3D Programmable Controllers Instructions Reference Manual	W340	Describes the ladder diagram programming instructions supported by CS/CJ-series PLCs and NSJ Controllers.
SYSMAC CS/CJ/NSJ Series CS1G/H-CPU□□-EV1, CS1G/H-CPU□□H, CS1D-CPU□□H, CS1D-CPU□□S, CJ1G-CPU□□, CJ1M-CPU□□, CJ1G-CPU□□P, CJ1G/H-CPU□□H, NSJ□-□□□□(B)-G5D, NSJ□-□□□□(B)-M3D Programmable Controllers Programming Manual	W394	This manual describes programming and other methods to use the functions of the CS/CJ-series PLCs and NSJ Controllers.
SYSMAC CS Series CS1D-CPU□□H CPU Units CS1D-CPU□□S CPU Units CS1D-DPL01 Duplex Unit CS1D-PA207R Power Supply Unit Duplex System Operation Manual	W405	Provides an outline of and describes the design, installation, maintenance, and other basic operations for a Duplex System based on CS1D CPU Units.
SYSMAC CS Series CS1G/H-CPU□□-EV1, CS1G/H-CPU□□H Programmable Controllers Operation Manual	W339	Provides an outlines of and describes the design, installation, maintenance, and other basic operations for the CS-series PLCs.
SYSMAC CJ Series CJ1G-CPU□□, CJ1M-CPU□□, CJ1G-CPU□□P, CJ1G/H-CPU□□H Programmable Controllers Operation Manual	W393	Provides an outlines of and describes the design, installation, maintenance, and other basic operations for the CJ-series PLCs.
SYSMAC CJ Series CJ1M-CPU□□ Built-in I/O Operation Manual	W395	Describes the functions of the built-in I/O for CJ1M CPU Units.
SYSMAC One NSJ Series NSJ5-TQ□□(B)-G5D, NSJ5-SQ□□(B)-G5D, NSJ8-TV□□(B)-G5D, NSJ10-TV□□(B)-G5D, NSJ12-TS□□(B)-G5D, NSJ5-TQ□□(B)-M3D, NSJ5-SQ□□(B)-M3D, NSJ8-TV□□(B)-M3D, NSJW-ETN21, NSJW-CLK21-V1, NSJW-IC101 NSJ Controllers Operation Manual	W452	Provides basic specifications on NSJ Controllers, including an overview, designing, installation, and maintenance.

Name	Cat. No.	Contents
SYSMAC CP Series CP1H-X☐☐☐☐-☐, CP1H-XA☐☐☐☐-☐, CP1H-Y☐☐☐☐-☐ CP1H CPU Unit Operation Manual	W450	Provides basic specifications on CP-series PLCs, including an overview, designing, installation, and maintenance.
SYSMAC CP Series CP1H-X☐☐☐☐-☐, CP1H-XA☐☐☐☐-☐, CP1H-Y☐☐☐☐-☐ CP1H CPU Unit Programming Manual	W451	Provides information on programming CP-series PLCs.
SYSMAC CXONE-AL☐☐C-EV2/AL☐☐D-EV2 CX-One Ver. 2.0 FA Integrated Tool Package Setup Manual	W463	Provides an overview of the CX-One FA Integrated Tool Package and CX-One installation procedures.
SYSMAC CXONE-AL☐☐C-EV2/, CXONE-AL☐☐D-EV2, CS/CJ/CP/ NSJ Series CX-Integrator Ver. 2.0 Operation Manual	W464	Describes setting and monitoring networks.
SYSMAC WS02-CXPC1-E-V70 CX-Programmer Ver. 7.0 Operation Manual	W446	Describes operating procedures for the CX-Programmer Support Software running on a Windows computer.
SYSMAC CX-Programmer Ver. 7.0 WS02-CXPC1-E-V7, CS1-H, CJ1-H, CJ1M, CP1H CPU Units, NSJ, FQM1 Operation Manual: Function Blocks	W447	Describes specifications and procedures required to use function blocks.

Section 1 introduces the C-mode commands and FINS commands, and explains the relationship between them.

Section 2 provides an overview of C-mode commands.

Section 3 provides an overview of FINS commands.

Section 4 provides detailed descriptions of the C-mode commands.

Section 5 provides detailed descriptions of the FINS commands.

⚠ **WARNING** Failure to read and understand the information provided in this manual may result in personal injury or death, damage to the product, or product failure. Please read each section in its entirety and be sure you understand the information provided in the section and related sections before attempting any of the procedures or operations given.

Read and Understand this Manual

Please read and understand this manual before using the product. Please consult your OMRON representative if you have any questions or comments.

Warranty and Limitations of Liability

WARRANTY

OMRON's exclusive warranty is that the products are free from defects in materials and workmanship for a period of one year (or other period if specified) from date of sale by OMRON.

OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, REGARDING NON-INFRINGEMENT, MERCHANTABILITY, OR FITNESS FOR PARTICULAR PURPOSE OF THE PRODUCTS. ANY BUYER OR USER ACKNOWLEDGES THAT THE BUYER OR USER ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. OMRON DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED.

LIMITATIONS OF LIABILITY

OMRON SHALL NOT BE RESPONSIBLE FOR SPECIAL, INDIRECT, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED ON CONTRACT, WARRANTY, NEGLIGENCE, OR STRICT LIABILITY.

In no event shall the responsibility of OMRON for any act exceed the individual price of the product on which liability is asserted.

IN NO EVENT SHALL OMRON BE RESPONSIBLE FOR WARRANTY, REPAIR, OR OTHER CLAIMS REGARDING THE PRODUCTS UNLESS OMRON'S ANALYSIS CONFIRMS THAT THE PRODUCTS WERE PROPERLY HANDLED, STORED, INSTALLED, AND MAINTAINED AND NOT SUBJECT TO CONTAMINATION, ABUSE, MISUSE, OR INAPPROPRIATE MODIFICATION OR REPAIR.

Application Considerations

SUITABILITY FOR USE

OMRON shall not be responsible for conformity with any standards, codes, or regulations that apply to the combination of products in the customer's application or use of the products.

At the customer's request, OMRON will provide applicable third party certification documents identifying ratings and limitations of use that apply to the products. This information by itself is not sufficient for a complete determination of the suitability of the products in combination with the end product, machine, system, or other application or use.

The following are some examples of applications for which particular attention must be given. This is not intended to be an exhaustive list of all possible uses of the products, nor is it intended to imply that the uses listed may be suitable for the products:

- Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this manual.
- Nuclear energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equipment, and installations subject to separate industry or government regulations.
- Systems, machines, and equipment that could present a risk to life or property.

Please know and observe all prohibitions of use applicable to the products.

NEVER USE THE PRODUCTS FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCTS ARE PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

PROGRAMMABLE PRODUCTS

OMRON shall not be responsible for the user's programming of a programmable product, or any consequence thereof.

Disclaimers

CHANGE IN SPECIFICATIONS

Product specifications and accessories may be changed at any time based on improvements and other reasons.

It is our practice to change model numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the products may be changed without any notice. When in doubt, special model numbers may be assigned to fix or establish key specifications for your application on your request. Please consult with your OMRON representative at any time to confirm actual specifications of purchased products.

DIMENSIONS AND WEIGHTS

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

PERFORMANCE DATA

Performance data given in this manual is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of OMRON's test conditions, and the users must correlate it to actual application requirements. Actual performance is subject to the OMRON Warranty and Limitations of Liability.

ERRORS AND OMISSIONS

The information in this manual has been carefully checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical, or proofreading errors, or omissions.

PRECAUTIONS

This section provides general precautions for using the CS/CJ-series Programmable Controllers (PLCs) and related devices.

The information contained in this section is important for the safe and reliable application of Programmable Controllers. You must read this section and understand the information contained before attempting to set up or operate a PLC system.

1 Intended Audience

This manual is intended for the following personnel, who must also have knowledge of electrical systems (an electrical engineer or the equivalent).

- Personnel in charge of installing FA systems.
- Personnel in charge of designing FA systems.
- Personnel in charge of managing FA systems and facilities.

2 General Precautions

The user must operate the product according to the performance specifications described in the operation manuals.

Before using the product under conditions which are not described in the manual or applying the product to nuclear control systems, railroad systems, aviation systems, vehicles, combustion systems, medical equipment, amusement machines, safety equipment, and other systems, machines, and equipment that may have a serious influence on lives and property if used improperly, consult your OMRON representative.

Make sure that the ratings and performance characteristics of the product are sufficient for the systems, machines, and equipment, and be sure to provide the systems, machines, and equipment with double safety mechanisms.

This manual provides information for programming and operating the Unit. Be sure to read this manual before attempting to use the Unit and keep this manual close at hand for reference during operation.

⚠ **WARNING** It is extremely important that a PLC and all PLC Units be used for the specified purpose and under the specified conditions, especially in applications that can directly or indirectly affect human life. You must consult with your OMRON representative before applying a PLC System to the above-mentioned applications.

3 Safety Precautions

⚠ **WARNING** The CPU Unit refreshes I/O even when the program is stopped (i.e., even in PROGRAM mode). Confirm safety thoroughly in advance before changing the status of any part of memory allocated to I/O Units, Special I/O Units, or CPU Bus Units. Any changes to the data allocated to any Unit may result in unexpected operation of the loads connected to the Unit. Any of the following operation may result in changes to memory status.

- Transferring I/O memory data to the CPU Unit from a Programming Device.
- Changing present values in memory from a Programming Device.
- Force-setting/-resetting bits from a Programming Device.
- Transferring I/O memory files from a Memory Card or EM file memory to the CPU Unit.
- Transferring I/O memory from a host computer or from another PLC on a network.

⚠ **WARNING** Do not attempt to take any Unit apart while the power is being supplied. Doing so may result in electric shock.

⚠ **WARNING** Do not touch any of the terminals or terminal blocks while the power is being supplied. Doing so may result in electric shock.

⚠ **WARNING** Do not attempt to disassemble, repair, or modify any Units. Any attempt to do so may result in malfunction, fire, or electric shock.

⚠ **WARNING** Provide safety measures in external circuits (i.e., not in the Programmable Controller), including the following items, to ensure safety in the system if an abnormality occurs due to malfunction of the PLC or another external factor affecting the PLC operation. Not doing so may result in serious accidents.

- Emergency stop circuits, interlock circuits, limit circuits, and similar safety measures must be provided in external control circuits.
- The PLC will turn OFF all outputs when its self-diagnosis function detects any error or when a severe failure alarm (FALS) instruction is executed. As a countermeasure for such errors, external safety measures must be provided to ensure safety in the system.
- The PLC outputs may remain ON or OFF due to deposition or burning of the output relays or destruction of the output transistors. As a countermeasure for such problems, external safety measures must be provided to ensure safety in the system.
- When the 24-V-DC output (service power supply to the PLC) is overloaded or short-circuited, the voltage may drop and result in the outputs being turned OFF. As a countermeasure for such problems, external safety measures must be provided to ensure safety in the system.

⚠ **Caution** Confirm safety before transferring data files stored in the file memory (Memory Card or EM file memory) to the I/O area (CIO) of the CPU Unit using a peripheral tool. Otherwise, the devices connected to the output unit may malfunction regardless of the operation mode of the CPU Unit.

⚠ **Caution** Fail-safe measures must be taken by the customer to ensure safety in the event of incorrect, missing, or abnormal signals caused by broken signal lines, momentary power interruptions, or other causes. Serious accidents may result from abnormal operation if proper measures are not provided.

⚠ **Caution** Execute online edit only after confirming that no adverse effects will be caused by extending the cycle time. Otherwise, the input signals may not be readable.

⚠ **Caution** The CS1-H, CJ1-H, CJ1M, or CS1D CPU Unit automatically backs up the user program and parameter data to flash memory when these are written to the CPU Unit. I/O memory (including the DM, EM, and HR Areas), however, is not written to flash memory. The DM, EM, and HR Areas can be held during power interruptions with a battery. If there is a battery error, the contents of these areas may not be accurate after a power interruption. If the contents of the DM, EM, and HR Areas are used to control external outputs, prevent inappropriate outputs from being made whenever the Battery Error Flag (A40204) is ON.

⚠ **Caution** Confirm safety at the destination node before transferring a program to another node or changing contents of the I/O memory area. Doing either of these without confirming safety may result in injury.

⚠ **Caution** Tighten the screws on the terminal block of the AC Power Supply Unit to the torque specified in the operation manual. Loose screws may result in burning or malfunction.

⚠ **Caution** Do not touch the Power Supply Unit when power is being supplied or immediately after the power supply is turned OFF. The Power Supply Unit will be hot and you may be burned.

⚠ **Caution** Be careful when connecting personal computers or other peripheral devices to a PLC to which is mounted a non-insulated Unit (CS1W-CLK12/52(-V1) or CS1W-ETN01) connected to an external power supply. A short-circuit will be created if the 24 V side of the external power supply is grounded and the 0 V side of the peripheral device is grounded. When connecting a peripheral device to this type of PLC, either ground the 0 V side of the external power supply or do not ground the external power supply at all.

4 Operating Environment Precautions

⚠ **Caution** Do not operate the control system in the following places:

- Locations subject to direct sunlight.
- Locations subject to temperatures or humidity outside the range specified in the specifications.
- Locations subject to condensation as the result of severe changes in temperature.
- Locations subject to corrosive or flammable gases.
- Locations subject to dust (especially iron dust) or salts.
- Locations subject to exposure to water, oil, or chemicals.
- Locations subject to shock or vibration.

⚠ **Caution** Take appropriate and sufficient countermeasures when installing systems in the following locations:

- Locations subject to static electricity or other forms of noise.
- Locations subject to strong electromagnetic fields.
- Locations subject to possible exposure to radioactivity.
- Locations close to power supplies.

⚠ **Caution** The operating environment of the PLC System can have a large effect on the longevity and reliability of the system. Improper operating environments can lead to malfunction, failure, and other unforeseeable problems with the PLC System. Be sure that the operating environment is within the specified conditions at installation and remains within the specified conditions during the life of the system.

5   Application Precautions

Observe the following precautions when using the PLC System.

- You must use the CX-Programmer (programming software that runs on Windows) if you need to program more than one task. A Programming Console can be used to program only one cyclic task plus interrupt tasks. A Programming Console can, however, be used to edit multitask programs originally created with the CX-Programmer.

⚠ **WARNING** Always heed these precautions. Failure to abide by the following precautions could lead to serious or possibly fatal injury.

- Always connect to a class-3 ground (to 100 Ω or less) when installing the Units. Not connecting to a class-3 ground may result in electric shock.
- A class-3 ground (to 100 Ω or less) must be installed when shorting the GR and LG terminals on the Power Supply Unit.
- Always turn OFF the power supply to the PLC before attempting any of the following. Not turning OFF the power supply may result in malfunction or electric shock.
  - Mounting or dismounting Power Supply Units, I/O Units, CPU Units, Inner Boards, or any other Units.
  - Assembling the Units.
  - Setting DIP switches or rotary switches.
  - Connecting cables or wiring the system.
  - Connecting or disconnecting the connectors.

⚠ **Caution** Failure to abide by the following precautions could lead to faulty operation of the PLC or the system, or could damage the PLC or PLC Units. Always heed these precautions.

- The user program and parameter area data in the CS1-H, CS1D, CJ1-H, and CJ1M CPU Units are backed up in the built-in flash memory. The BKUP indicator will light on the front of the CPU Unit when the backup operation is in progress. Do not turn OFF the power supply to the CPU Unit when the BKUP indicator is lit. The data will not be backed up if power is turned OFF.
- When using a CS-series CS1 CPU Unit for the first time, install the CS1W-BAT01 Battery provided with the Unit and clear all memory areas from a Programming Device before starting to program. (Not required for CS1-H, CJ1, CJ1-H, CJ1M, or CS1D CPU Units.)
- When using the internal clock for a CS-series CS1 CPU Unit, turn ON power after installing the battery and set the clock from a Programming Device or using the DATE(735) instruction. The clock will not start until the time has been set. (Not required for CS1-H, CJ1, CJ1-H, CJ1M, or CS1D CPU Units.)
- When using a CS1-H, CJ1, CJ1-H, CJ1M, or CS1D CPU Unit, the PLC Setup is set to specify using the mode set on the Programming Console, and a Programming Console is not connected, the CPU Unit will start in RUN mode. This is the default setting in the PLC Setup. A CS1 CPU Unit will start in PROGRAM mode under the same conditions.

- When creating an AUTOEXEC.IOM file from a Programming Device (a Programming Console or the CX-Programmer) to automatically transfer data at startup, set the first write address to D20000 and be sure that the size of data written does not exceed the size of the DM Area. When the data file is read from the Memory Card at startup, data will be written in the CPU Unit starting at D20000 even if another address was set when the AUTOEXEC.IOM file was created. Also, if the DM Area is exceeded (which is possible when the CX-Programmer is used), the remaining data will be written to the EM Area.

- Always turn ON power to the PLC before turning ON power to the control system. If the PLC power supply is turned ON after the control power supply, temporary errors may result in control system signals because the output terminals on DC Output Units and other Units will momentarily turn ON when power is turned ON to the PLC.

- Fail-safe measures must be taken by the customer to ensure safety in the event that outputs from Output Units remain ON as a result of internal circuit failures, which can occur in relays, transistors, and other elements.

- Fail-safe measures must be taken by the customer to ensure safety in the event of incorrect, missing, or abnormal signals caused by broken signal lines, momentary power interruptions, or other causes.

- Interlock circuits, limit circuits, and similar safety measures in external circuits (i.e., not in the Programmable Controller) must be provided by the customer.

- Do not turn OFF the power supply to the PLC when data is being transferred. In particular, do not turn OFF the power supply when reading or writing a Memory Card. Also, do not remove the Memory Card when the BUSY indicator is lit. To remove a Memory Card, first press the memory card power supply switch and then wait for the BUSY indicator to go out before removing the Memory Card.

- If the I/O Hold Bit is turned ON, the outputs from the PLC will not be turned OFF and will maintain their previous status when the PLC is switched from RUN or MONITOR mode to PROGRAM mode. Make sure that the external loads will not produce dangerous conditions when this occurs. (When operation stops for a fatal error, including those produced with the FALS(007) instruction, all outputs from Output Unit will be turned OFF and only the internal output status will be maintained.)

- The contents of the DM, EM, and HR Areas in the CPU Unit are backed up by a Battery. If the Battery voltage drops, this data may be lost. Provide countermeasures in the program using the Battery Error Flag (A40204) to re-initialize data or take other actions if the Battery voltage drops.

- When supplying power at 200 to 240 VAC for CS-series PLCs, always remove the metal jumper from the voltage selector terminals. The product will be destroyed if 200 to 240 VAC is supplied while the metal jumper is attached.

- Always use the power supply voltages specified in the operation manuals. An incorrect voltage may result in malfunction or burning.

- Take appropriate measures to ensure that the specified power with the rated voltage and frequency is supplied. Be particularly careful in places where the power supply is unstable. An incorrect power supply may result in malfunction.

- Install external breakers and take other safety measures against short-circuiting in external wiring. Insufficient safety measures against short-circuiting may result in burning.

- Do not apply voltages to the Input Units in excess of the rated input voltage. Excess voltages may result in burning.

- Do not apply voltages or connect loads to the Output Units in excess of the maximum switching capacity. Excess voltage or loads may result in burning.

- Separate the line ground terminal (LG) from the functional ground terminal (GR) on the Power Supply Unit before performing withstand voltage tests or insulation resistance tests. Not doing so may result in burning.

- Install the Units properly as specified in the operation manuals. Improper installation of the Units may result in malfunction.

- With CS-series PLCs, be sure that all the Unit and Backplane mounting screws are tightened to the torque specified in the relevant manuals. Incorrect tightening torque may result in malfunction.

- Be sure that all the mounting screws, terminal screws, and cable connector screws are tightened to the torque specified in the relevant manuals. Incorrect tightening torque may result in malfunction.

- Leave the label attached to the Unit when wiring. Removing the label may result in malfunction if foreign matter enters the Unit.

- Remove the label after the completion of wiring to ensure proper heat dissipation. Leaving the label attached may result in malfunction.

- Use crimp terminals for wiring. Do not connect bare stranded wires directly to terminals. Connection of bare stranded wires may result in burning.

- Wire all connections correctly.

- Double-check all wiring and switch settings before turning ON the power supply. Incorrect wiring may result in burning.

- Mount Units only after checking terminal blocks and connectors completely.

- Be sure that the terminal blocks, Memory Units, expansion cables, and other items with locking devices are properly locked into place. Improper locking may result in malfunction.

- Check switch settings, the contents of the DM Area, and other preparations before starting operation. Starting operation without the proper settings or data may result in an unexpected operation.

- Check the user program for proper execution before actually running it on the Unit. Not checking the program may result in an unexpected operation.

- Confirm that no adverse effect will occur in the system before attempting any of the following. Not doing so may result in an unexpected operation.
    - Changing the operating mode of the PLC (including the setting of the startup operating mode).
    - Force-setting/force-resetting any bit in memory.
    - Changing the present value of any word or any set value in memory.

- Do not pull on the cables or bend the cables beyond their natural limit. Doing either of these may break the cables.

- Do not place objects on top of the cables or other wiring lines. Doing so may break the cables.

- Do not use commercially available RS-232C personal computer cables. Always use the special cables listed in this manual or make cables

according to manual specifications. Using commercially available cables may damage the external devices or CPU Unit.

- Never connect pin 6 (5-V power supply) on the RS-232C port on the CPU Unit to any device other than an NT-AL001 or CJ1W-CIF11 Adapter. The external device or the CPU Unit may be damaged.

- When replacing parts, be sure to confirm that the rating of a new part is correct. Not doing so may result in malfunction or burning.

- Before touching a Unit, be sure to first touch a grounded metallic object in order to discharge any static built-up. Not doing so may result in malfunction or damage.

- When transporting or storing circuit boards, cover them in antistatic material to protect them from static electricity and maintain the proper storage temperature to protect the LSIs, ICs, and other components.

- Do not touch circuit boards or the components mounted to them with your bare hands. There are sharp leads and other parts on the boards that may cause injury if handled improperly.

- Do not short the battery terminals or charge, disassemble, heat, or incinerate the battery. Do not subject the battery to strong shocks. Doing any of these may result in leakage, rupture, heat generation, or ignition of the battery. Dispose of any battery that has been dropped on the floor or otherwise subjected to excessive shock. Batteries that have been subjected to shock may leak if they are used.

- UL standards required that batteries be replaced only by experienced technicians. Do not allow unqualified persons to replace batteries.

- Dispose of the product and batteries according to local ordinances as they apply. Have qualified specialists properly dispose of used batteries as industrial waste.

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- With a CJ-series PLC, the sliders on the tops and bottoms of the Power Supply Unit, CPU Unit, I/O Units, Special I/O Units, and CPU Bus Units must be completely locked (until they click into place). The Unit may not operate properly if the sliders are not locked in place.

- With a CJ-series PLC, always connect the End Plate to the Unit on the right end of the PLC. The PLC will not operate properly without the End Plate.

- Unexpected operation may result if inappropriate data link tables or parameters are set. Even if appropriate data link tables and parameters have been set, confirm that the controlled system will not be adversely affected before starting or stopping data links.

- CPU Bus Units will be restarted when routing tables are transferred from a Programming Device to the CPU Unit. Restarting these Units is required to read and enable the new routing tables. Confirm that the system will not be adversely affected before allowing the CPU Bus Units to be reset.

SECTION 1
Introduction

This section introduces the C-mode commands and FINS commands, and explains the relationship between them.

1-1 Overview of Communications Commands

Communications Commands Addressed to CS/CJ/CP/NSJ-series Units

A CS/CJ/CP-series CPU Unit or NSJ Controller can receive the following communications commands.

```
                            ┌─ C-mode commands via Host Link
Communications commands ────┤
                            │                     ┌── Via CMND(490)/SEND(090)/RECV(098)
                            └─ FINS commands ──────┤
                                                  └── Via Host Link
```
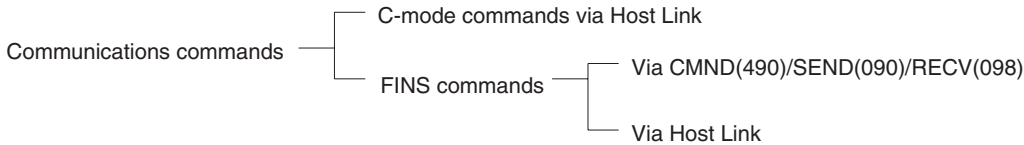
C-mode Commands

C-mode commands are specialized Host Link communications commands. They are issued by a host computer and sent to a CPU Unit. The devices that can be connected for serial communications are the CPU Unit, a Serial Communications Unit, and a Serial Communications Board.

FINS Commands

FINS commands are message service communications commands. They do not depend on a particular transmission path. They can be used for communications on various networks (Controller Link, Ethernet, etc.) and for serial communications (Host Link). They can be issued from a CPU Unit, Special I/O Unit, or host computer, and they can also be sent to any of these. The specific commands that can be sent depend on the destination.

This manual explains commands sent to CS/CJ/CP-series CPU Units and NSJ Controllers, when the commands are issued from a CPU Unit or a host computer connected by Host Link.

Note When the source of the commands is a CPU Unit, the FINS commands are sent by means of CMND(490)/SEND(090)/RECV(098). When the source is a host computer, the FINS commands are issued using Host Link protocol.

1-2 C-mode Commands

The following table lists the C-mode (Host Link) commands. For details, refer to *SECTION 4 C-mode Commands*.

Type	Header code	Name	Function
I/O memory reading	RR	CIO AREA READ	Reads the specified number of words beginning with the designated CIO word.
	RL	LR AREA READ	Reads the specified number of words beginning with the designated LR word.
	RH	HR AREA READ	Reads the specified number of words beginning with the designated HR word.
	RC	TIMER/COUNTER PV READ	Reads the specified number of words of the timer/counter PV beginning with the designated word.
	RG	TIMER/COUNTER STATUS READ	Reads the specified number of words of the timer/counter status beginning with the designated word.
	RD	DM AREA READ	Reads the specified number of words beginning with the designated DM word.
	RJ	AR AREA READ	Reads the specified number of words beginning with the designated AR word.
	RE	EM AREA READ	Reads the specified number of words beginning with the designated EM word.

Type	Header code	Name	Function
I/O memory writing	WR	CIO AREA WRITE	Writes the specified data in word units beginning with the designated CIO word.
	WL	LR AREA WRITE	Writes the specified data in word units beginning with the designated LR word.
	WH	HR AREA WRITE	Writes the specified data in word units beginning with the designated HR word.
	WC	TIMER/COUNTER PV WRITE	Writes the specified timer/counter PV data in word units beginning with the designated word.
	WD	DM AREA WRITE	Writes the specified data in word units beginning with the designated DM word.
	WJ	AR AREA WRITE	Writes the specified data in word units beginning with the designated AR word.
	WE	EM AREA WRITE	Writes the specified data in word units beginning with the designated EM word.
Timer/counter SV reading	R#	TIMER/COUNTER SV READ 1	Reads in four digits BCD the constant SV that is written as an operand of the designated timer/counter instruction.
	R$	TIMER/COUNTER SV READ 2	Finds the specified timer/counter instruction, beginning with the designated program address, and reads the constant SV in four digits or the word in which the SV is stored.
	R%	TIMER/COUNTER SV READ 3	Finds the specified timer/counter instruction, beginning with the designated program address, and reads the constant SV in four digits (BCD) or the word in which the SV is stored.
Timer/counter SV changing	W#	TIMER/COUNTER SV CHANGE 1	Changes the SV of the specified timer/counter instruction to a new constant SV.
	W$	TIMER/COUNTER SV CHANGE 2	Finds the specified timer/counter instruction, beginning with the designated program address in the user program, and changes the constant SV in four digits (BCD) or the word in which the SV is stored to a new constant SV or storage word.
	W%	TIMER/COUNTER SV CHANGE 3	Finds the specified timer/counter instruction, beginning with the designated program address in the user program, and changes the constant SV in four digits (BCD) or the word in which the SV is stored to a new constant SV or storage word.
CPU Unit status	MS	STATUS READ	Reads the CPU Unit's operating conditions (operating mode, forced set/reset status, and fatal errors).
	SC	STATUS CHANGE	Changes the CPU Unit's operating mode.
	MF	ERROR READ	Reads the CPU Unit's error information (i.e., all fatal or non-fatal errors currently in effect).
Forced set/reset	KS	FORCED SET	Forcibly sets one designated bit.
	KR	FORCED RESET	Forcibly resets one designated bit.
	FK	MULTIPLE FORCED SET/RESET	Forcibly sets/resets/cancels multiple designated bits.
	KC	FORCED SET/RESET CANCEL	Cancels all forced set/reset status.
PLC model code reading	MM	PLC MODEL READ	Reads the model code of the CPU Unit.
Testing	TS	TEST	Returns, just as it is, a single block that was sent from the host computer.
Program area accessing	RP	PROGRAM READ	Reads, in one batch, the contents of the CPU Unit's user program at the machine language (object) level.
	WP	PROGRAM WRITE	Writes into the CPU Unit's user program area the machine language (object) sent from the host computer.

Type	Header code	Name	Function
I/O table creation	MI	I/O TABLE CREATE	Creates an I/O table with the contents of the actual I/O configuration.
I/O memory area registration and reading	QQMR	REGISTER I/O MEMORY	Registers the I/O memory words or bits that are to be read.
	QQIR	READ I/O MEMORY	Reads the registered I/O memory words/bits all at once.
Host Link communications processing	XZ	ABORT (command only)	Aborts the operation being performed by a Host Link command, and then returns to the initial status.
	∗∗	INITIALIZE (command only)	Initializes the transfer control procedures for all Host Link Units.
	IC	Undefined command (response only)	This is the response when the command header code cannot be decoded.

1-3   FINS Commands

The following table lists the FINS commands. For details, refer to *SECTION 5 FINS Commands*.

Type	Command code		Name	Function
	MR	SR		
I/O memory area access	01	01	MEMORY AREA READ	Reads the contents of consecutive I/O memory area words.
	01	02	MEMORY AREA WRITE (See note.)	Writes the contents of consecutive I/O memory area words.
	01	03	MEMORY AREA FILL (See note.)	Writes the same data to the specified range of I/O memory area words.
	01	04	MULTIPLE MEMORY AREA READ	Reads the contents of specified non-consecutive I/O memory area words.
	01	05	MEMORY AREA TRANSFER (See note.)	Copies the contents of consecutive I/O memory area words to another I/O memory area.
Parameter area access	02	01	PARAMETER AREA READ	Reads the contents of consecutive parameter area words.
	02	02	PARAMETER AREA WRITE (See note.)	Writes the contents of consecutive parameter area words.
	02	03	PARAMETER AREA FILL (CLEAR) (See note.)	Clears the specified range of parameter area words.
Program area access	03	06	PROGRAM AREA READ	Reads the UM (User Memory) area.
	03	07	PROGRAM AREA WRITE (See note.)	Writes to the UM (User Memory) area.
	03	08	PROGRAM AREA CLEAR (See note.)	Clears a specified range of the UM (User Memory) area.
Operating mode changes	04	01	RUN (See note.)	Changes the CPU Unit's operating mode to RUN or MONITOR.
	04	02	STOP (See note.)	Changes the CPU Unit's operating mode to PROGRAM.
Machine configuration reading	05	01	CPU UNIT DATA READ	Reads CPU Unit data.
	05	02	CONNECTION DATA READ	Reads the model numbers of the device corresponding to addresses.
Status reading	06	01	CPU UNIT STATUS READ	Reads the status of the CPU Unit.
	06	20	CYCLE TIME READ	Reads the maximum, minimum, and average cycle time.
Time data access	07	01	CLOCK READ	Reads the present year, month, date, minute, second, and day of the week.
	07	02	CLOCK WRITE (See note.)	Changes the present year, month, date, minute, second, or day of the week.

Type	Command code		Name	Function
	MR	SR		
Message display	09	20	MESSAGE READ/CLEAR	Reads and clears messages, and reads FAL/FALS messages.
Access rights	0C	01	ACCESS RIGHT ACQUIRE (See note.)	Acquires the access right as long as no other device holds it.
	0C	02	ACCESS RIGHT FORCED ACQUIRE	Acquires the access right even if another device already holds it.
	0C	03	ACCESS RIGHT RELEASE	Releases the access right that has been acquire.
Error log	21	01	ERROR CLEAR (See note.)	Clears errors or error messages.
	21	02	ERROR LOG READ	Reads the error log.
	21	03	ERROR LOG CLEAR (See note.)	Clears all error log records.
FINS write access log	21	40	FINS WRITE ACCESS LOG READ	The CPU Unit automatically keeps a log of any access for FINS write commands. This command reads this log.
	21	41	FINS WRITE ACCESS LOG CLEAR (See note.)	Clears the FINS write access log.
File memory	22	01	FILE NAME READ	Reads file device data.
	22	02	SINGLE FILE READ	Reads a specified length of file data from a specified position within a single file.
	22	03	SINGLE FILE WRITE (See note.)	Writes a specified length of file data from a specified position within a single file.
	22	04	FILE MEMORY FORMAT (See note.)	Formats (initializes) the file device.
	22	05	FILE DELETE (See note.)	Deletes specified files stored in the file device.
	22	07	FILE COPY (See note.)	Copies files from one file device to another file device in the same system.
	22	08	FILE NAME CHANGE (See note.)	Changes a file name.
	22	0A	MEMORY AREA–FILE TRANSFER (See note.)	Transfers or compares data between the I/O memory area and the file device.
	22	0B	PARAMETER AREA–FILE TRANS-FER (See note.)	Transfers or compares data between the parameter area and the file device.
	22	0C	PROGRAM AREA–FILE TRANS-FER (See note.)	Transfers or compares data between the UM (User Memory) area and the file device.
	22	15	DIRECTORY CREATE/DELETE (See note.)	Creates or deletes a directory.
	22	20	MEMORY CASSETTE TRANS-FER (CP-series CPU Units only)	Transfers and verifies data between a Memory Cassette and the CPU Unit.
Debugging	23	01	FORCED SET/RESET (See note.)	Force-sets or force-resets bits, or releases force-set status.
	23	02	FORCED SET/RESET CANCEL (See note.)	Cancels all bits that have been force-set or force-reset.

Note These commands will not be accepted and an end code of 2102 hex (cannot write due to protection) will be returned if the *Write Protection from FINS Commands Sent to CPU Units via Networks* option is selected in the PLC Setup for a CS/CJ-series CPU Unit with unit version 2.0 or later, for a CP-series CPU Unit, or for an NSJ Controller.

SECTION 2
Overview of C-mode Commands

This section provides an overview of C-mode (Host Link) commands.

2-1   C-mode Commands

C-mode (Host Link) commands form a command/response system for serial communications (Host Link Mode) to perform various control operations between a CPU Unit and a host computer directly connected to it. These operations include reading from and writing to I/O memory, changing operating modes, executing forced set and forced reset operations, and so on.
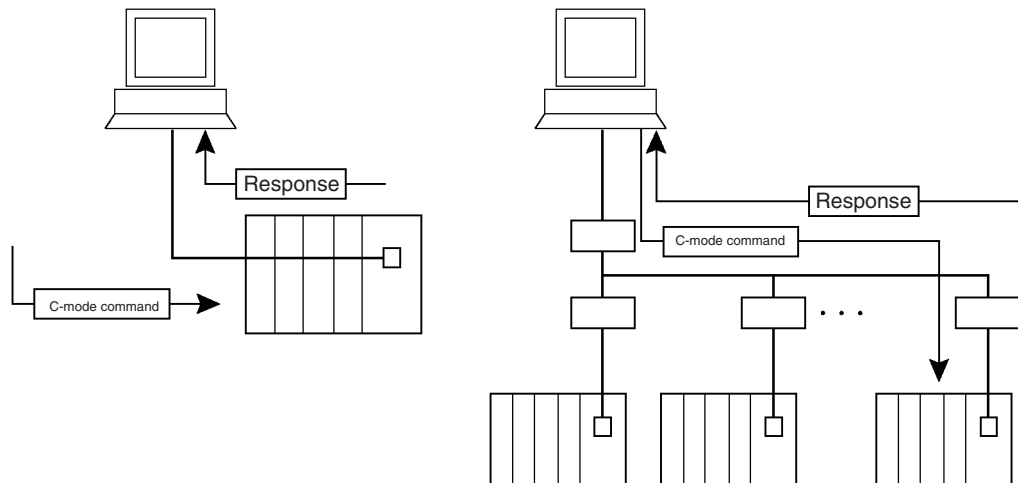
Note 1.   There are two Host Link formats: the 1:N Host Link (with $N \geq 1$) and the 1:1 Host Link.

- The 1:1 Host Link is the earlier Host Link format supported by C-series PLCs, such as the C200H, C1000H, and C2000H.

- The built-in peripheral and RS-232C ports of CS/CJ-series CPU Units, serial port C on NSJ Controllers, and serial ports 1 and 2 on the Option Board for CP-series CPU Units support only the 1:N Host Link format. When a Serial Communications Board or Unit (version 1.2 or later) is being used, a 1:1 Host Link program created for a C-series PLC (C200H/C1000H/C2000H) can be reused by selecting the Host Link 1:1 format.

In this manual, the term "Host Link" generally indicates the 1:N Host Link.

2.   Unlike FINS commands, C-mode commands can only be addressed to a CPU Unit, and they cannot be used for message service outside of the local network. They cannot be used for functions such as file operations.

C-mode (Host Link) commands can be sent from a host computer connected to a CS/CJ-series Host Link Unit. Up to 32 PLCs (Host Link Units) can be connected to a single host computer. For identification, each Host Link Unit is assigned a unit number from 0 to 31.

The length of a single unit of a command or response exchange is called a "frame." A single frame contains a maximum of 131 characters of data. Characters are sent and received as ASCII.

Note For a CS/CJ-series PLC, a "Host Link Unit" can be the CPU Unit, a Serial Communications Unit, or a Serial Communications Board.

A maximum of 30 words of data can be transferred for the first command frame and a maximum of 31 words of data can be transferred for other command frames when reading or writing word data in I/O memory. When reading/writing more than 30 words of data, the data transfer will be processed in multiple transmissions, with 30 words in the first and up to 31 words in each of

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the following transmissions until the number of words set in the command has been processed.

The frame formats for Host Link commands sent from a host computer and responses returned by the PLC receiving the commands are explained in the following section.

2-2   Command/Response Formats

Single-frame Commands   If a command is not more than 131 characters long, communications can be completed by sending a single command frame. This is called a "single-frame command."

Command Frame Format

@	10^1	10^0						*	CR

- Text
- Terminator
- Header code
- FCS
- Unit number (BCD)
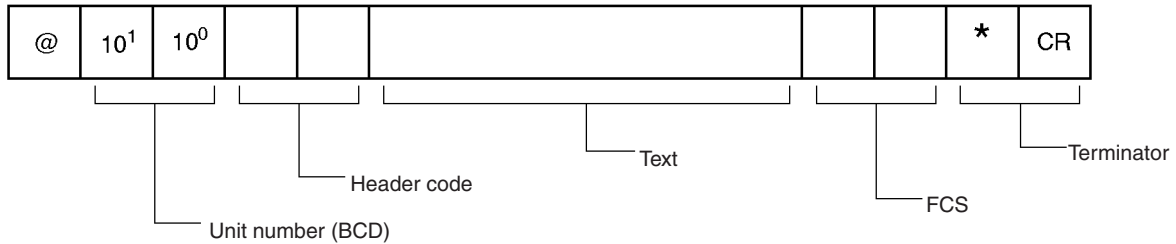
- **@:**   Must be attached at the beginning of the command.
- **Unit number:** Set in BCD from 0 to 31 for each Host Link Unit.
- **Header code:** Specified in two characters.
- **Text:**   Set parameters corresponding to command code.
- **FCS:**   Calculate 2-character FCS (frame check sequence) at host computer. For details on calculating FCS, refer to *FCS Calculations* later in this section.
- **Terminator:** Set "*" and CR (CHR$(13)) as two characters to indicate the end of the command.

Single-frame Response   If a response is not more than 131 characters long, the communications can be completed by returning one response frame. This is called a "single-frame response."

Response Frame Format

@	10^1	10^0			16^1	16^0				*	CR

- Text
- Terminator
- End code (hexadecimal)
- FCS
- Header code
- Unit number (BCD)
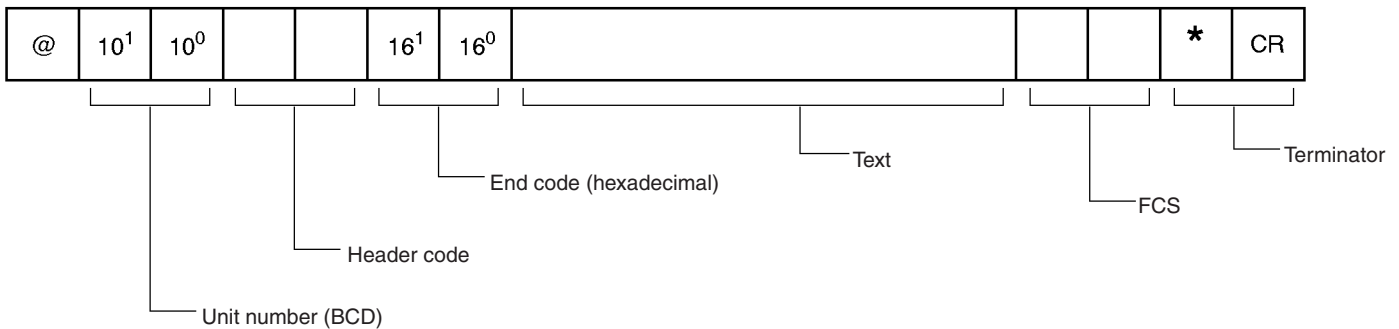
- **@:**   Must be attached at the beginning of the response.
- **Unit number:** Set in BCD from 0 to 31 for each Host Link Unit.
- **Header code:** The command code that was received is returned.
- **End code:**   The results (error status, etc.) of command execution is returned.
- **Text:**   Returned only if there is read data.

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- FCS: The 2-character FCS (frame check sequence) is returned.
- Terminator: Two characters indicating the end of the command, "*" and CR (CHR$(13)), are returned.

Error Response Formant

If a reception error or an error in executing the command occurs, a response is returned with no text.
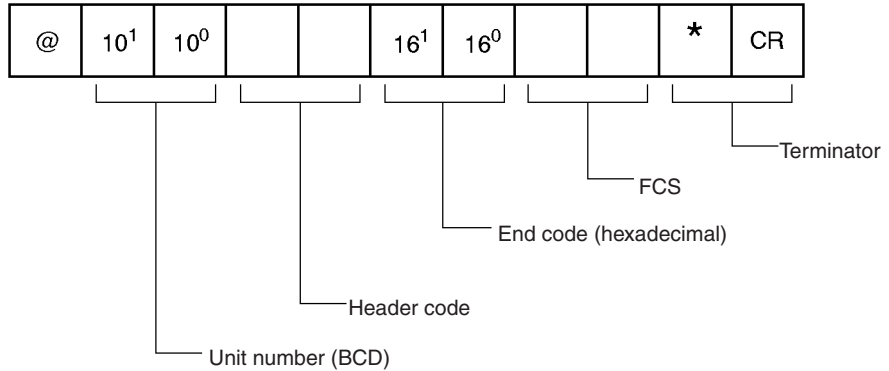
Partitioned Commands

If a command is longer than 131 characters, the command's text is partitioned by sending a delimiter [CR code, CHR$(13)] instead of a terminator at the end of each command frame until the last one. A terminator is sent at the end of the last frame. The procedure is given below for three command frames.

Note When sending command frames for writing (WR, WL, WC, WD, etc.), be careful not to partition into separate frames data that is to be written into the same word.

1,2,3...

1. From the host computer, attach a delimiter (CR) at the end of command frame 1 and send the frame.
2. When the PLC receives this delimiter (CR), it will return only a delimiter (CR) to the host computer.
3. From the host computer, attach a delimiter (CR) at the end of command frame 2 and send the frame.
4. When the PLC receives this delimiter (CR), it will return only a delimiter (CR) to the host computer.
5. From the host computer, attach a terminator (*CR) at the end of command frame 3 and send the frame.
6. When the PLC receives this terminator (*CR), it will return the response format with a terminator (*CR) attached to the end.

The following diagram shows the command format when there are more than 131 characters.
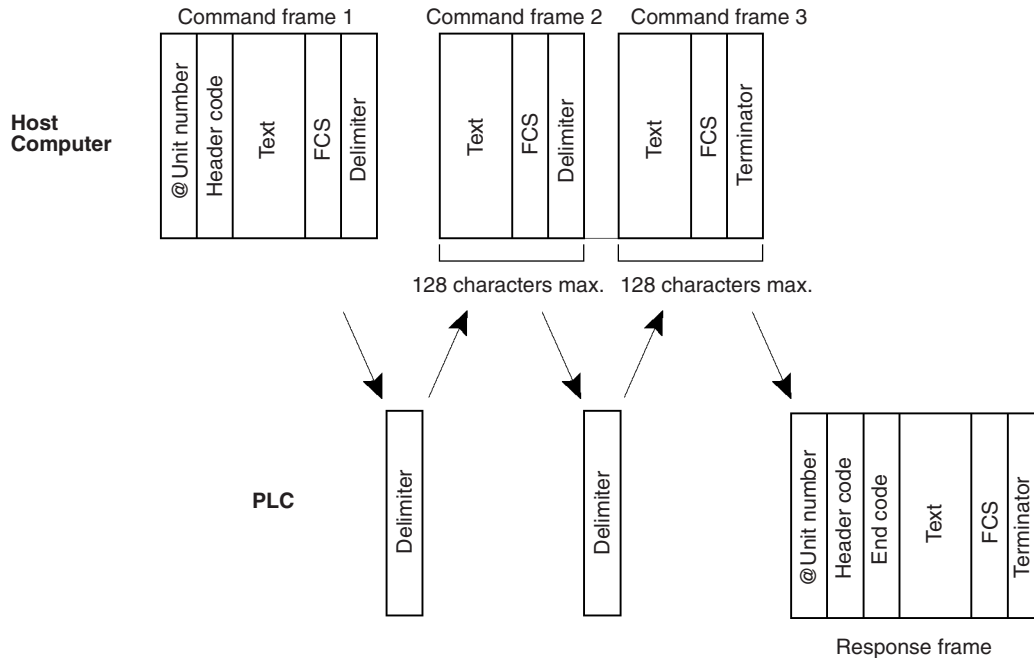
Note A "delimiter" is a CR code [CHR$(13)] sent as a single character to indicate the middle of a command or response.

Partitioned Responses
If a response is more than 131 characters long, the response from the PLC is partitioned by returning a delimiter (CR code, CHR$(13)) instead of a terminator at the end of each frame until the last one. A terminator is returned at the end of the last frame.

In the following example procedure, the response is partitioned into three frames.

1,2,3...
1. When the PLC receives the command frame from the host computer, it returns response frame 1 with a delimiter (CR) at the end to the host computer.

2. Only a delimiter (CR) is sent from the host computer to the PLC.

3. When the PLC receives this delimiter (CR), it returns response frame 2 with a delimiter (CR) at the end to the host computer.

4. Only a delimiter (CR) is sent from the host computer to the PLC.

5. When the PLC receives this delimiter (CR), it returns response frame 3 with a terminator (*CR) at the end to the host computer.

The following diagram shows the response format when there are more than 131 characters.
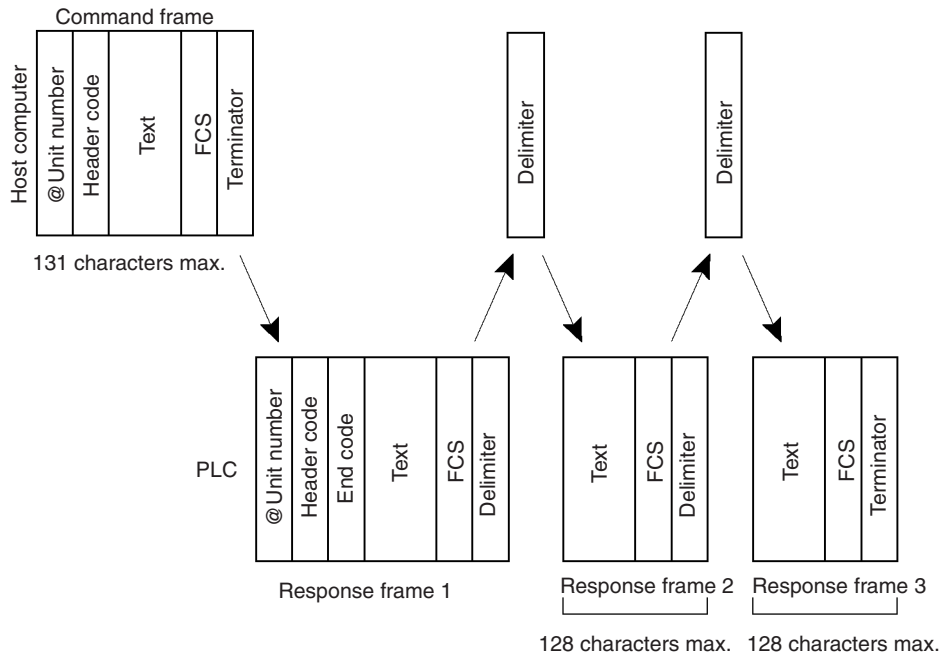
Note 1. Frames in partitioned commands or responses must have not more than 128 characters including the delimiter/terminator.

2. Delimiters from the host computer are detected by the presence of a CR code. The delimiter will be detected even if there is data in front of it.

FCS Calculations   The PLC calculates the FCS (Frame Check Sequence) value for each command frame it receives, and it checks for errors by comparing that value with the FCS value sent with the command frame. The host computer must calculate the FCS value when sending a command frame.

Also, when checking for errors in response frames, the host computer must calculate the FCS value for each response frame it receives and compare that value to the FCS value sent in the response frame.
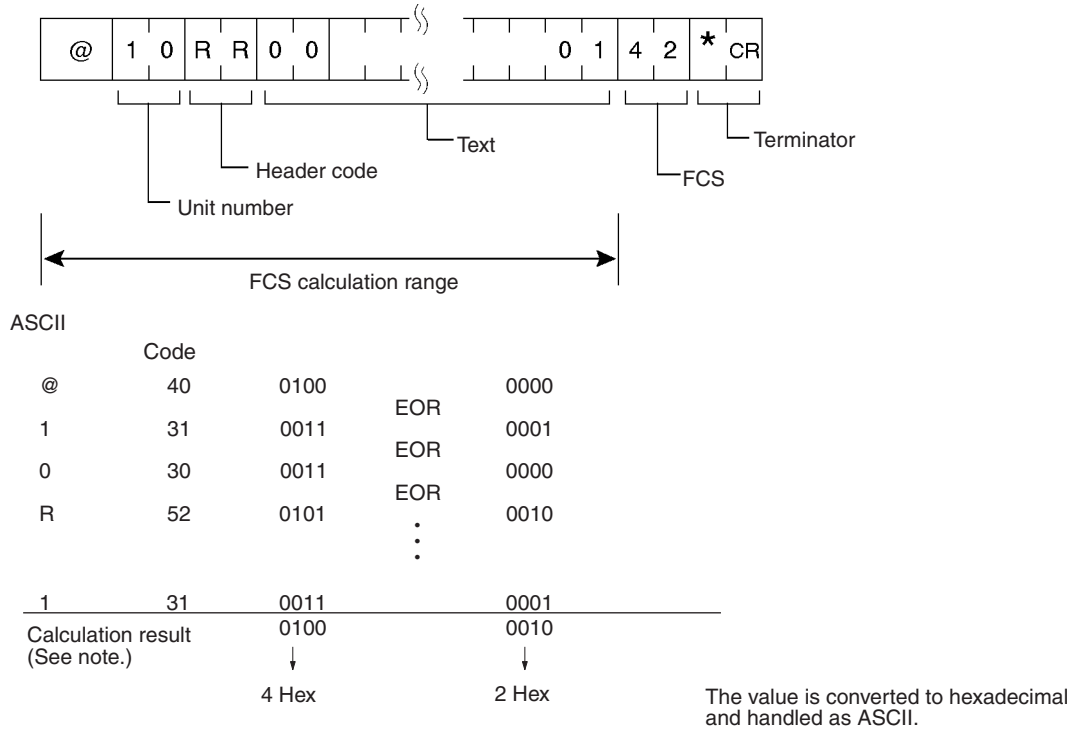
Note The FCS is an 8-bit value converted into two ASCII characters. The 8-bit value is the result of an exclusive OR sequentially performed between each character in a transmission, from the first character in the frame to the last character of the text in that frame. Non-ASCII data, however, may sometimes be sent in the text data. If the data length is 7 bits, the leftmost bit of each character is masked before the FCS is calculated.

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2-3   Application Example

Sending a Host Link Command from a Host Computer

In this example program, a Host Link command is sent from a host computer and a response is received.

```
10 'CS1 SAMPLE PROGRAM FOR EXCEPTION
20 CLOSE
30 CLS
40 OPEN "COM:E73"AS#1
50 *KEYIIN
60 INPUT "DATA-",S
70 IF S$=""THEN GOTO 190
80 PRINT "SEND DATA=";S$
90 ST$=S$
100 INPUT "SEND OK? Y or N?=",BS
110 IF B$="Y" THEN GOTO 130 ELSE GOTO *KEYIN
120 S$=ST$
130 PRINT #T,S$                          Sends command to PLC.
140 INPUT #1,R$                          Receives command from PLC.
150 PRINT "RECV DATA=";R$
160 IF MID$(R$,4,2)="EX"THEN GOTO 210    Identifies command.
170 IF RIGHT$(R$,1)<>"*"THEN S$="":GOTO 130
180 GOTO *KEYIN
190 CLOSE 1
200 END
210 PRINT "EXCEPTION!!DATA"
220 GOTO 140
```

Explanation

1,2,3...   1.   The host computer's transmission/reception program is started up, and the Host Link command is input.

2.   The Host Link command that was input is sent to the PLC, and the data that is received is displayed on the screen.

Note   The example program up to this point does not include an error processing routine in case reception is not normal (e.g., if there is no FCS). Include error processing routines when creating an actual program.

```
400 *FCSCHCK
410 L=LEN(RESPONSE$)                     Transmission/reception data
420 Q=0:FCSCK$=""
430 A$=RIGHT$(RESPONSE$,1)
440 PRINT RESPONSE$,A$,L
450 IF A$="*"THEN LENGS=LEN(RESPONSE$)-3
    ELSE LENGS=LEN(RESPONSE$)-2
460 FCSP$=MID$(RESPONSE$,LENGS+1,2)       FCS data that is received
470 FOR I=1 TO LENGS           Number of characters in FCS calculation
480 Q=ASC(MID$(RESPONSE$1,1))XOR Q
490 NEXT 1
500 FCSD$=HEX$(Q)
510 IF LEN(FCSD$) =1 THEN FCSD$="0"+FCSD$          FCS calculation result
520 IF FCSD$<>FCSP$ THEN FCSCK$="ERR"
530 PRINT "FCSD$=";FCSD$,"FCSP$=";FCSP$,"FCSCK$=";FCSCK$
    Normal FCS reception: " " (space); abnormal FCS reception: "ERR"
540 RETURN
```

2-4 Precautions when Reusing Programs from Earlier Models

Observe the following precautions when reusing host computer programs created for communications with C-series Host Link Units.

2-4-1 C-series Host Link Units with 1:N Host Link Format Selected

Using the CPU Unit's Built-in Peripheral Port or RS-232C Port

Number of Data Words per Frame

When I/O memory data is read with the following commands, the number of data words in each response frame is different for a C-series Host Link Unit compared to the built-in peripheral and RS-232C ports on CS/CJ-series CPU Units, serial port C on NSJ Controllers, and serial ports 1 and 2 on the Option Board for CP-series CPU Units.

With a C-series Host Link Unit, the first frame can contain up to 29 words of data (text) and the following frames can contain up to 30 words of data (text). With the built-in peripheral and RS-232C ports on CS/CJ-series CPU Units, serial port C on NSJ Controllers, and serial ports 1 and 2 on the Option Board for CP-series CPU Units, the first frame can contain up to 30 words of data (text) and the following frames can contain up to 31 words of data (text).

Header code	Name
RR	CIO AREA READ
RL	LR AREA READ
RH	HR AREA READ
RC	TIMER/COUNTER PV READ
RG	TIMER/COUNTER STATUS READ
	Note: The number of data words per response frame is different for the RG command than for the other C-mode commands. For details, see the table *Words per Frame for C-mode RG Command* below.
RD	DM AREA READ
RJ	AR AREA READ

Because the Units do not have the same number of words per response frame, the data may not be read properly if a host computer program originally used with a C-series Host Link Unit is reused with a CS-series CPU Unit, CJ-series CPU Unit, CP-series CPU Unit, or NSJ Controller. In this case, be sure to edit the host computer program so that it is compatible with the frame format.

Note Serial Communications Boards and Units with version numbers 1.2 and later are equipped with a Host Link model compatibility selection function that changes the Host Link function's specifications to match the frame format of other Units in the Host Link. It is not necessary to edit an existing program if the Host Link model compatibility selection function is set to match the Host Link format used in the program. For details, see *Using a Serial Communications Board or Unit with Version Number 1.2 or Later* below.

Words per Frame for C-mode Commands (Except RG Command)

Units	C Series	CS/CJ Series	CVM1 and CV Series	Data words per frame	
				1st frame	Other frames
C-series Host Link Units	C200H-LK101/LK201/LK202 Host Link Units C500-LK103/LK203 Host Link Units 3G2A5-LK101/LK201 Host Link Units 3G2A6-LK101/LK201/LK202 Host Link Units	---	---	29 words	30 words
Other Boards and Units	SRM1 built-in ports CPM1 built-in ports CPM1A built-in ports CQM1-CPU☐☐ built-in ports C200HS-CPU☐☐ built-in ports C200HX/HG/HE-CPU☐☐ built-in ports C200HW-COM☐☐ Communications Board ports	CS1G/H-CPU☐☐H built-in ports CS1G/H-CPU☐☐-EV1 built-in ports CS1D-CPU☐☐H built-in ports CJ1G/H-CPU☐☐H built-in ports CJ1G-CPU☐☐ built-in ports CJ1M-CPU☐☐ built-in ports CS1W-SCB21-V1/41-V1 (unit version: Pre-Ver. 1.2) Serial Communications Board ports CS1W-SCU21-V1 (unit version: Pre-Ver. 1.2) Serial Communications Unit ports CJ1W-SCU21/41 (unit version: Pre-Ver. 1.2) Serial Communications Unit ports	CVM1-CPU☐☐ built-in ports CV-CPU☐☐ built-in ports CV500-LK201 Host Link Unit	30 words	31 words

Words per Frame for C-mode RG Command

Units	C Series	CS/CJ Series	CVM1 and CV Series	Data words per frame	
				1st frame	Other frames
C-series Host Link Units	C200H-LK101/LK201/LK202 Host Link Units	---	---	89 words	89 words
	C500-LK103/LK203 Host Link Units 3G2A5-LK101/LK201 Host Link Units 3G2A6-LK101/LK201/LK202 Host Link Units	---	---	89 words	60 words
Other Boards and Units	SRM1 built-in ports CPM1 built-in ports CPM1A built-in ports CQM1-CPU☐☐ built-in ports CQM1H-CPU☐☐ built-in ports CQM1H-SCB☐☐ built-in ports C200HX/HG/HE-CPU☐☐ built-in ports C200HW-COM☐☐ Communications Board ports	CS1G/H-CPU☐☐H built-in ports CS1G/H-CPU☐☐-EV1 built-in ports CS1D-CPU☐☐H built-in ports CJ1G/H-CPU☐☐H built-in ports CJ1G-CPU☐☐ built-in ports CJ1M-CPU☐☐ built-in ports CS1W-SCB21-V1/41-V1 (unit version: Pre-Ver. 1.2) Serial Communications Board ports CS1W-SCU21-V1 (unit version: Pre-Ver. 1.2) Serial Communications Unit ports CJ1W-SCU21/41 (unit version: Pre-Ver. 1.2) Serial Communications Unit ports	CVM1-CPU☐☐ built-in ports CV-CPU☐☐ built-in ports CV500-LK201 Host Link Unit	121 words	125 words

Note There are several exceptions to the number of words per frame values shown in the table above:

The following responses are returned when reading 246 words of Timer/Counter Completion Flags through CS/CJ-series CPU Unit built-in ports, CS/CJ-series Serial Communications Units/Boards, C200HX/HG/HE CPU Unit built-in ports, or C200HS CPU Unit built-in ports.

1st frame	2nd frame	3rd frame
121 words	124 words	1 word

The second-to-last frame contains 124 data words and the last frame contains 1 word. This also applies when the number of words is 246 + a multiple of 125 (i.e., 371 words, 496 words, 621 words, etc.).

The following responses are returned when reading 121 words of Timer/Counter Completion Flags through CS/CJ-series Unit built-in ports.

1st frame	2nd frame
120 words	1 word

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The following responses are returned when reading 121 words or 246 words through CVM1 and CV-series CPU Unit built-in ports or CVM1/CV-series Host Link Units.

Number of Words = 121

1st frame	2nd frame
121 words	0 words (terminator only)

Number of Words = 246

1st frame	2nd frame	3rd frame
121 words	125 words	0 words (terminator only)

The second-to-last frame contains 125 data words and the last frame contains the terminator only. This also applies when the number of words is 246 + a multiple of 125 (i.e., 371 words, 496 words, 621 words, etc.). For responses containing the terminator only, "00*CR" (00 = FCS, CR = carriage return) is returned.

Response Format for MS Command

With the MS command (STATUS READ), the response data format when using CVM1 or CV-series built-in ports or Host Link Units, is different from the response data format when using other Units.

When a CVM1/CV CPU Unit's built-in Host Link port or CVM1/CV Series Host Link Unit is used and an FAL or FALS instruction has not been executed, spaces (ASCII code 20 hex) will be included in the response data for the FAL/FALS message. With all other Host Link Units, the FAL/FALS message data is included in the response only when an FAL or FALS instruction has been executed.

Using a Pre-Ver. 1.2 Serial Communications Board or Unit

The response formats are the same as described above under the heading *Using the CPU Unit's Built-in Peripheral Port or RS-232C Port*.

Using a Serial Communications Board or Unit with Version Number 1.2 or Later

The Serial Communications Board or Unit's Host Link function can be made completely compatible with the existing PLC's Host Link function by setting the appropriate Host Link mode (1:N or 1:1 Host Link) and the Host Link model compatibility mode.

Host Link Model Compatibility Selection Function

Serial Communications Boards and Units with version Ver. 1.2 and later are equipped with a Host Link model compatibility selection function. This function switches the Board or Unit's Host Link specifications to match the specifications of an existing Host Link program that is being reused. The following specifications can be switched by the Host Link model compatibility function.

- Words per Response Frame

    Sets the number of data words per response frame when receiving the following I/O memory read commands (RR, RL, RH, RC, RD, RJ, or RG).

- Sets the response frame format for the STATUS READ command (MS), which varies when an FAL or FALS instruction has not been executed.

Host Link Model Compatibility Modes

Host link model compatibility mode	Host link model (Model used as basis for host computer's program)	RR, RL, RH, RC, RD, and RJ commands		RG command		MS command (see note)
		Data words per response frame				Response data format
		1st frame	2nd frame	1st frame	2nd frame	
A mode (CS, CJ, and C)	C Series 　SRM1 built-in ports 　CPM1 built-in ports 　CPM1A built-in ports 　CQM1-CPU☐☐ built-in ports 　C200HS-CPU☐☐ built-in ports 　C200HX/HG/HE-CPU☐☐ built-in ports 　C200HW-COM☐☐ Communications Board ports CS/CJ Series 　CS1G/H-CPU☐☐H built-in ports 　CS1G/H-CPU☐☐-EV1 built-in ports 　CS1D-CPU☐☐H built-in ports 　CJ1G/H-CPU☐☐H built-in ports 　CJ1G-CPU☐☐ built-in ports 　CJ1M-CPU☐☐ built-in ports 　CS1W-SCB21-V1/41-V1 (unit version: Pre-Ver. 1.2) Serial Communications Board ports 　CS1W-SCU21-V1 (unit version: Pre-Ver. 1.2) Serial Communications Unit ports 　CJ1W-SCU21/41 (unit version: Pre-Ver. 1.2) Serial Communications Unit ports	30 words	31 words	121 words	125 words	Variable length
B mode (CVM1/CV)	CVM1-CPU☐☐ built-in ports CV-CPU☐☐ built-in ports CV500-LK201 Host Link Unit					Fixed length
C mode (C200H)	C200H-LK101/LK201/LK202 Host Link Units	29 words	30 words	89 words	89 words	Variable length
D mode (C500/C120)	C500-LK103/LK203 Host Link Units 3G2A5-LK101/LK201 Host Link Units 3G2A6-LK101/LK201/LK202 Host Link Units			89 words	60 words	

Note When the MS command reads the CPU Unit's status data and an FAL or FALS instruction has not been executed, spaces (ASCII code 20 hex) are included as the FAL/FALS message in the response frame for some models (fixed length response in the table above). In the other models, no data is included as the FAL/FALS message in the response frame (variable length response frame) if an FAL or FALS instruction has not been executed.

<u>**Relationship to the 1:N Host Link/1:1 Host Link Setting**</u>

The following table shows the allowed Host Link format (1:N Host Link/1:1 Host Link) settings for each Host Link model compatibility setting.

Host link model compatibility mode	Host link format
A mode (CS, CJ, and C) and B mode (CVM1/CV)	Only the 1:N Host Link format can be used.
C mode (C500/C120) and D mode (C200H)	Either the 1:N Host Link format or 1:1 Host Link format can be selected.

<u>**Settings for an Example Unit Replacement**</u>

Use the following settings when the existing host computer was created for a system with C500-LK103/LK203 Host Link Units and/or 3G2A5-LK101/LK201 Host Link Units, a new Serial Communications Board or Unit (Ver. 1.2 or later) is being used, and the Host Link format is 1:1 Host Link.

- Host link 1:N format/1:1 format setting: 1 (1:1 Host Link format)
- Host link model compatibility mode setting: 3 (C mode (C500/C120))

2-4-2   C-series Host Link Units with 1:1 Host Link Format Selected

Using the CPU Unit's Built-in Peripheral Port or RS-232C Port

Only the 1:N Host Link format is supported by the CPU Unit's built-in peripheral port and RS-232C port. A host computer program cannot be used if it was developed for a 1:1 Host Link.

Using a Pre-Ver. 1.2 Serial Communications Board or Unit

Only the 1:N Host Link format is supported by Pre-Ver. 1.2 Serial Communications Boards and Units. A host computer program cannot be used if it was developed for a 1:1 Host Link.

Using a Serial Communications Board or Unit with Version Number 1.2 or Later

The Serial Communications Boards and Units with version number 1.2 or later can be set to operate in 1:1 Host Link mode, so a host computer program developed for a 1:1 Host Link with C-series PLCs (C200H, C1000H, and C2000H) can be reused in a CS/CJ Series Host Link. (The 1:1 Host Link for-

mat can be selected with the 1:N format/1:1 format setting in the allocated DM Area settings.)

Host link format	Usage	Applicable PLC models	Remarks

1:N format	With this Host Link format, the connection configuration (host: PLC) can be either 1:1 or 1:N. Earlier versions of these Boards/Units supported only the 1:N format.	C Series
		  SRM1 built-in ports
		  CPM1 built-in ports
		  CPM1A built-in ports
		  CQM1-CPU□□ built-in ports
		  C200HS-CPU□□ built-in ports
		  C200HX/HG/HE-CPU□□ built-in ports
		  C200HW-COM□□ Communications Board ports
		CS/CJ Series
		  CS1G/H-CPU□□H built-in ports
		  CS1G/H-CPU□□-EV1 built-in ports
		  CS1D-CPU□□H built-in ports
		  CJ1G/H-CPU□□H built-in ports
		  CJ1G-CPU□□ built-in ports
		  CJ1M-CPU□□ built-in ports
			Only the 1:N Host Link format is supported by the built-in ports on CPU Units of CS/CJ, C200HS, C200HX/HG/HE, CPM□, and CQM1□ PLCs as well as the ports on Host Link Units and Serial Communications Boards.

		Earlier versions (unit version: Pre-Ver. 1.2)
		  CS1W-SCB21-V1/41-V1 Serial Communications Board ports
		  CS1W-SCU21-V1 Serial Communications Unit ports
		  CJ1W-SCU21/41 Serial Communications Unit ports
			Earlier versions of the Serial Communications Boards/Units support only the 1:N Host Link format.

		CVM1/CV Series
		  CVM1-CPU□□ built-in ports
		  CV-CPU□□ built-in ports
		  CV500-LK201 Host Link Unit
			Only the 1:N Host Link format is supported by the built-in ports on CPU Units of CVM1/CV Series PLCs as well as the ports on Host Link Units and Serial Communications Units/Boards.

		C Series
		  C500-LK103/LK203 Host Link Units
		  3G2A5-LK101/LK201 Host Link Units
		  3G2A6-LK101/LK201/LK202 Host Link Units
			Either the 1:N Host Link or 1:1 Host Link format can be selected with these C-series Host Link Units.

		C Series C200H-LK101/LK201/LK202 Host Link Units	

1:1 format	With this Host Link format, the connection configuration (host: PLC) can be 1:1 only.	C Series
		  C500-LK103/LK203 Host Link Units
		  3G2A5-LK101/LK201 Host Link Units
		  3G2A6-LK101/LK201/LK202 Host Link Units
			Either the 1:N Host Link or 1:1 Host Link format can be selected with these C-series Host Link Units.

		C Series C200H-LK101/LK201/LK202 Host Link Units	

Note The following diagrams show the differences in the command and response frames with the 1:N Host Link format and 1:1 Host Link format.

1:N Format

- Command

Unit number in host link   Header code   FCS   Terminator

- Response

Unit number in host link   Header code   End code   FCS   Terminator
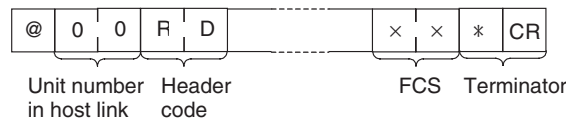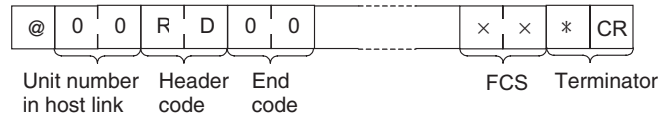
1:1 Format

As shown in the following diagrams, the 1:1 format is equivalent to the 1:N format without the @ character, Host Link unit number, and FCS byte.

- Command format

Header code   Terminator

- Response format

Header code   End code   Terminator
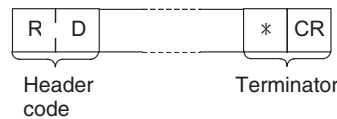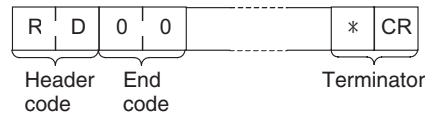
2-4-3   C-mode Command Support

Use the following table as reference when reusing programs for host computers developed for earlier Host Link models.

- If a command is not supported for the new model of PLC, consider using another C-mode or FINS command.
- Even if the command is supported, differences may exist in the data sizes that can be processed or in the meaning of the values if the models or Series vary.
- Refer to the applicable operation manuals for details.

Note Refer to information on the previous page for commands with "Caution" in the *Frame data size* column.

Frame data size	Header code	Name	CS/CJ Series CPU Unit or Serial Communications Board or Unit	C Series C200HE/HG/HX CPU Unit or Communications Board	C200HS CPU Unit	C120 (3G2A6) Host Link Unit	C200H C200HS C200HE/HG/HX C200H Host Link Unit	C500 (3G2A5) Host Link Unit	C1000H C2000H	C500F	C1000HF	CQM1 CPU Unit	SRM1 CPM1 CPM1A CPU Unit	CVM1/CV CPU Unit (None or V1)	CVM1/CV CPU Unit (V2)	CV500 Host Link Unit
Caution	RR	CIO AREA READ	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Caution	RL	LR AREA READ	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No	Yes	No
Caution	RH	HR AREA READ	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No	Yes	No
Caution	RC	TIMER/COUNTER PV READ	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Caution	RG	TIMER/COUNTER STATUS READ	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Caution	RD	DM AREA READ	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Caution	RJ	AR AREA READ	Yes	Yes	Yes	No	Yes	No	Yes	No	Yes	Yes	Yes	Yes	Yes	Yes
OK	RE	EM AREA READ	Yes	Yes	No	No	No	No	No	No	No	No	No	No	No	No
NA	RX	FILE MEMORY DELUXE READ	No	No	No	No	No	No	Yes	No	Yes	No	No	No	No	No
NA	RF	FILE MEMORY READ	No	No	No	No	No	No	Yes	No	Yes	No	No	No	No	No
NA	CR	DM AREA READ (FIXED)	No	No	No	No	No	No	Yes	No	Yes	No	No	No	Yes	No
NA	GM	DM SIZE CHANGE	No	No	No	No	No	No	No	Yes	Yes	No	No	No	No	No
Caution	WR	CIO AREA WRITE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Caution	WL	LR AREA WRITE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No	Yes	No
Caution	WH	HR AREA WRITE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No	Yes	No
Caution	WC	TIMER/COUNTER PV WRITE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Caution	WD	DM AREA WRITE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Caution	WJ	AR AREA WRITE	Yes	Yes	Yes	No	No	No	Yes	No	Yes	Yes	Yes	Yes	Yes	Yes
OK	WE	EM AREA WRITE	Yes	Yes	No	No	No	No	No	No	No	No	No	No	No	No
NA	R#	TIMER/COUNTER SV READ 1	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No	Yes	No
NA	R$	TIMER/COUNTER SV READ 2	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No	Yes	No
NA	R%	TIMER/COUNTER SV READ 3	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No	No	Yes	No
NA	W#	TIMER/COUNTER SV CHANGE 1	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No	Yes	No

Frame data size	Header code	Name	CS/CJ Series	C Series										CVM1 and CV Series		
				C200HE /HG/HX	C200HS	C120	C200H C200HS C200HE/ HG/HX	C500	C1000H C2000H	C500F	C1000HF	CQM1	SRM1 CPM1 CPM1A			
			CPU Unit or Serial Communications Board or Unit	CPU Unit or Communications Board	CPU Unit	C120 (3G2A6) Host Link Unit	C200H Host Link Unit	C500 (3G2A5) Host Link Unit				CPU Unit	CPU Unit	CPU Unit	CPU Unit	CV500 Host Link Unit
			---	---	---	---	---	---				---	---	None or V1	V2	---
NA	W$	TIMER/ COUNTER SV CHANGE 2	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No	Yes	No
NA	W%	TIMER/ COUNTER SV CHANGE 3	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No	No	Yes	No
NA	MS	STATUS READ	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	SC	STATUS CHANGE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	MF	ERROR READ	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	KS	FORCED SET	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	KR	FORCED RESET	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	FK	MULTIPLE FORCED SET/ RESET	Yes	Yes	Yes	No	Yes	No	No	No	No	Yes	Yes	No	Yes	No
NA	FR	MULTIPLE FORCED SET/ RESET STA-TUS READ	No	Yes	Yes	No	Yes	No	No	No	No	No	No	No	No	No
NA	KC	FORCED SET/ RESET CAN-CEL	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	MM	PLC MODEL READ	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	TS	TEST	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	RP	PROGRAM READ	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	WP	PROGRAM WRITE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	MI	I/O TABLE CREATE	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No	No	Yes	Yes	Yes
NA	QQMR/ QQIR	REGISTER/ READ I/O MEMORY	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	XZ	ABORT (com-mand only)	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	**	INITIALIZE (command only)	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	IC	Undefined command (response only)	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
NA	EX	TXD RESPONSE (response only)	No	Yes	No	No	No	No	No	No	No	No	No	No	No	No
NA	FA	FINS MES-SAGE	Yes	No	No	No	No	No	No	No	No	No	No	Yes	Yes	Yes
NA	OF	FINS MES-SAGE (slave-initiated)	Yes	No	No	No	No	No	No	No	No	No	No	Yes	Yes	Yes

Note   When using CVM1 or CV-series built-in ports or Host Link Units, the response data format for the MS command (STATUS READ) is different from the format for other Units. For details, refer to *4-3-23 STATUS READ – – MS*.

Manuals for Host Link Operations

PLC	Product		Model (suffixes omitted)	Manual type	Catalog No.
CS/CJ Series	Communications commands (C-mode and FINS)	CPU Unit	CS1G/H-CPU□□H CS1G/H-CPU□□-EV1 CS1D-CPU□□H CJ1M-CPU□□ CJ1G/H-CPU□□H CJ1G-CPU□□	Reference Manual	W342-E1
		Serial Communications Unit/Board	CS1W-SCB21-V1/41-V1 CS1W-SCU21-V1 CJ1W-SCU21/41		
	Serial Communications Unit/Board		CS1W-SCB21-V1/41-V1 CS1W-SCU21-V1 CJ1W-SCU21/41	Operation Manual	W336-E1
C200HX/HG/HE	CPU Unit		C200HX/HG/HE-CPU□□	Operation Manual	W303-E1
			C200HX/HG/HE-CPU□□-Z	Operation Manual	W322-E1
C200HS	CPU Unit		C200HS-CPU□□	Operation Manual	W235-E1
C Series	Host Link Units		C200H-LK101/201/202 C500-LK201/203 3G2A5-LK101/103 3G2A6-LK101/201/202	System Manual	W143-E1
CQM1	CPU Unit		CQM1-CPU□□	Programming Manual	W228-E1
CPM1	CPU Unit		CPM1-□□□□□	Operation Manual	W262-E1
CPM1A	CPU Unit		CPM1A-□□□□□	Operation Manual	W317-E1
SRM1	CPU Unit		SRM1-C□□	Operation Manual	W318-E1
CVM1 and CV Series	CPU Unit		CVM1/CV-CPU□□	Operation Manual	W205-E1
	Host Link Unit		CV500-LK201		

SECTION 3
Overview of FINS Commands

This section provides an overview of FINS commands.

3-1   FINS Commands

FINS commands form a command system for message services across different OMRON networks. They can be used for various control operations, such as sending and receiving data, changing operating modes, executing forced set and forced reset operations, performing file operations, and so on. FINS commands make it possible to freely communicate with Units in various networks and on CPU Racks by simply specifying the network, node, and unit.

FINS commands have the following features:

1,2,3...   1. They are defined in the application level and do not depend on lower levels (i.e., the physical and data link levels). This allows them to be used across a variety of networks and CPU buses. Specifically, they can be used with Ethernet, Controller Link, and Host Link networks, and between CPU Units and CPU Bus Units.

Note FINS commands can be sent with UDP/IP headers when using Ethernet and with Host Link command headers when using Host Link.

2. FINS commands can be used to access various kinds of devices besides CPU Units. Devices such as CPU Units, CPU Bus Units, personal computers (boards), and Inner Boards can be identified and specified by their unit addresses.
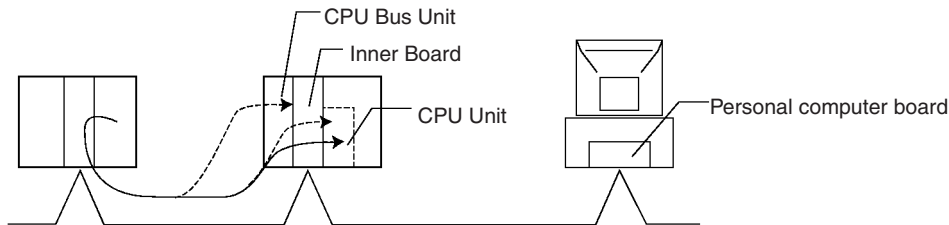
3. FINS commands support network relay operations, so they can pass through a network hierarchy to access devices on up to three network levels (including the local network).
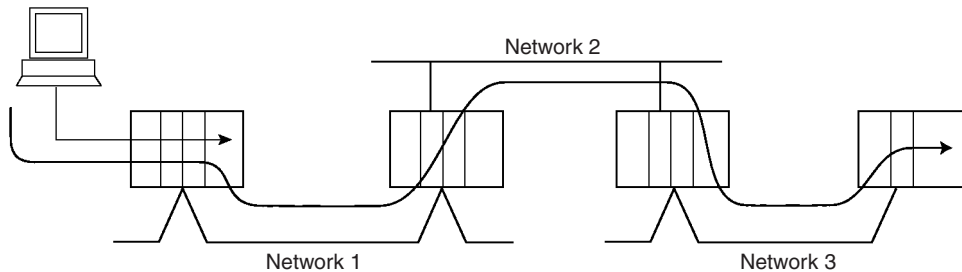
Note With CS/CJ-series CPU Units with unit version 2.0 or later, CP-series CPU Units, or NSJ Controllers, devices can be accessed on up to 8 network levels. When the destination of a FINS command is a CPU Unit, the command can be sent through as many as 8 network levels. When the destination of a FINS command is a node other than a CPU Unit, the command can be sent through a maximum of 3 network levels.

- The following table shows the maximum number of network levels that can be crossed by various PLC models.

PLC model	Network levels (Gateway counter setting)
CS/CJ-series CPU Unit with unit version 3.0 CP-series CPU Unit, NSJ Controller	It is possible to select a maximum of either 8 levels or 3 levels. (Set with CX-Programmer Ver. 5.0.)
CS/CJ-series CPU Unit with unit version 2.0	Setting fixed at 8 levels max.
Pre-Ver. 20. CS/CJ-series CPU Units and CVM1/CV-series CPU Units	Setting fixed at 3 levels max.

- When crossing up to 3 network levels, the CS/CJ-series CPU Units with unit version 2.0 and later, CP-series CPU Units, and NSJ Controllers can be combined with other models. When crossing 4 to 8 network levels, configure the system with only unit version 2.0 and later CS/CJ-series CPU Units, CP-series CPU Units, and NSJ Controllers. (Other models cannot be combined in the network with CS/CJ-series CPU Units with unit version 2.0 and later, CP-series CPU Units, and NSJ Controllers.) If earlier models are used, a routing error (end codes 0501 to 0504) will occur and the response may not be returned to the node that sent the command.

For details, refer to *1-4-2 Communications through a Maximum of 8 Network Levels* in the *CS Series PLC Operation Manual* or the *CJ Series PLC Operation Manual*.

Types of FINS Commands

There are basically two kinds of FINS commands: Those addressed to CPU Units and those addressed to CPU Bus Units. Among FINS commands for CPU Units, there are commands addressed to the various models of CPU Unit, such as the CS/CJ/CP-series CPU Units, NSJ Controllers, CV-series CPU Units, C200HX/HG/HE CPU Units, and so on. The basic code system is the same, but the detailed specifications vary according to the CPU Unit.

Among FINS commands for CPU Bus Units, there are commands addressed to Controller Link Units, to DeviceNet Master Units, to Ethernet Units, and so on.

FINS Commands Addressed to CS/CJ/CP-series CPU Units and NSJ Controllers

CS/CJ/CP-series CPU Units and NSJ Controllers can receive FINS commands from a PLC (CS/CJ, CVM1/CV, or C200HX/HG/HE(-Z) CPU Unit) or computer on another network or from a host computer connected directly to the local network.
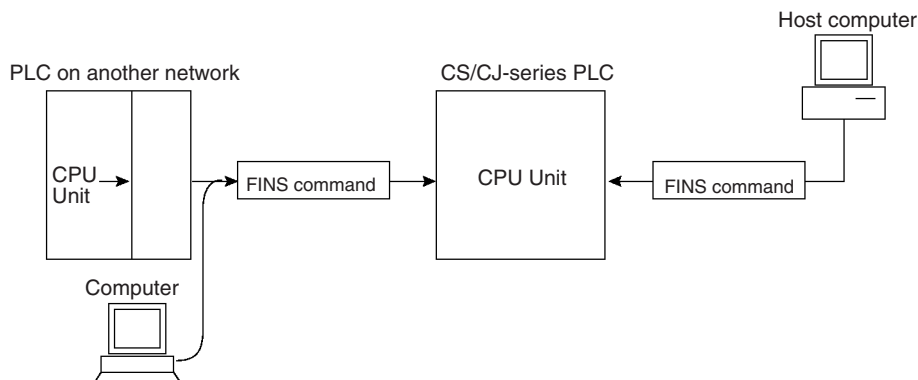
1,2,3... 1. A FINS command sent from a PLC or computer on another network is transmitted to the CPU Unit from the Backplane of the CPU Rack, via a Communications Unit (Controller Link Unit, Ethernet Unit, etc.)

2. FINS commands sent from a host computer to a CPU Unit are sent with a Host Link header code and a terminator (as in the Host Link communications mode).
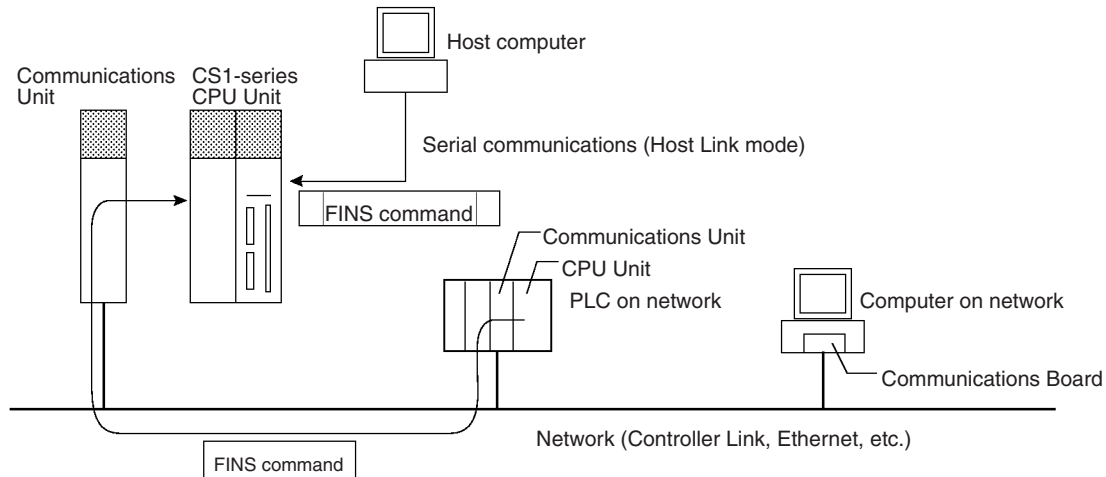
The FINS commands available for CS/CJ/CP-series CPU Units and NSJ Controllers fall into the following broad categories. (Refer to the relative operation manuals for FINS commands addressed to other Units and Boards.)

- I/O memory area reading and writing
- Parameter area reading and writing
- Program area reading and writing
- Operating mode changes
- Machine configuration reading
- CPU Unit status reading
- Time data access
- Message reading and clearing
- Access rights acquisition and release
- Error log reading and clearing
- File operations
- Forced set/reset

3-2 Using FINS Commands

FINS commands for CPU Units can be used by means of either CMND(490) or Host Link communications.

3-2-1 CMND(490)

FINS commands can be sent to a CS/CJ/CP-series CPU Unit or NSJ Controller by executing CMND(490) in the program of another PLC (CPU Unit) on the network. The basic procedure is as follows:

1,2,3... 1. Store the command format of the FINS command (i.e., the command data) in an I/O memory area, such as the DM area.

2. In the same way, store the control data (number of bytes of transmission data, destination address, etc.) in an I/O memory area, such as the DM area.

3. Designate S (first command word), D (first response word), and C (first control word) for the CMND(490) operands, and execute the instruction.

4. When the FINS response is returned from the destination node (a CS/CJ/CP-series CPU Unit or an NSJ Controller), the data will be stored according to the response format beginning at the first response word.
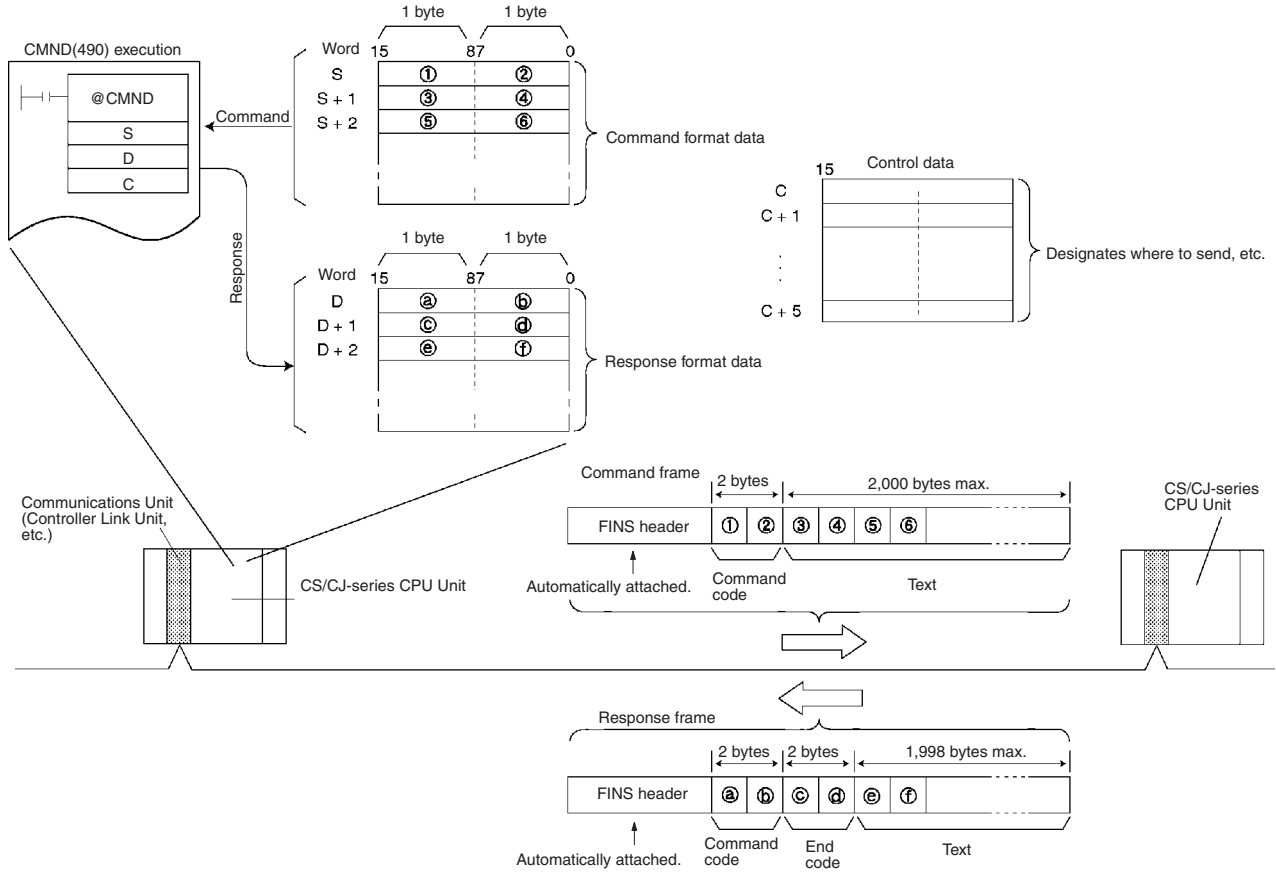
Note FINS commands and responses are handled as binary data, and data is sent and received in binary format. (Host Link communications, however, are basically in ASCII.)

3-2-2 Host Link Communications

With Host Link communications, a FINS command frame with a Host Link header and a terminator is sent from a host computer to a CS/CJ/CP-series CPU Unit or NSJ Controller. The basic frame formats are shown below.

Note Host Link communications handle ASCII data, so data is sent and received in ASCII. For that reason, FINS command and response frames must also be sent and received in ASCII when they are handled using Host Link communications.

Command Frame
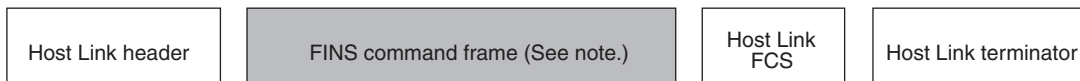
Note A FINS command frame also consists of the destination node address, the source node address, and other FINS command format data.

The CS/CJ/CP-series CPU Unit or NSJ Controller that receives the command will return the following response frame to the host computer.

Response Frame

Host Link header	FINS response frame (See note.)	Host Link FCS	Host Link terminator
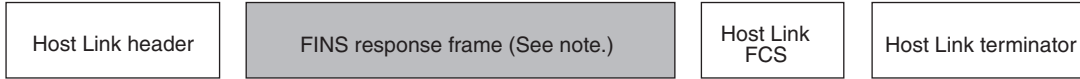
Note A FINS response frame also consists of the contents set (e.g., requested) at the time of transmission and the FINS command response format data.

It is also possible to send a FINS command frame with a Host Link header and terminator from a CS/CJ/CP-series CPU Unit or NSJ Controller to a host computer connected by Host Link System (unsolicited communications initiated by a slave).

3-3 FINS Command and Response Frames

If the data from the command code onwards is set in the words specified with S when a FINS command is sent by means of CMND(490), a FINS header will be generated automatically and attached, and the FINS command frame will be sent. When the FINS response frame is received, the FINS header will be automatically removed and the response data from the command code onwards will be stored as specified in the words specified with operand D.

When a FINS command is sent by Host Link communications, the header is attached before the FINS frame, and the FCS and terminator are attached after it.

3-3-1 FINS Command Frame Configuration

	00	02									

ICF RSV GCT DNA DA1 DA2 SNA SA1 SA2 SID Command code Text

FINS header (automatically attached for CMND(490))   *Set in word specified for CMND(490) operand S onwards.
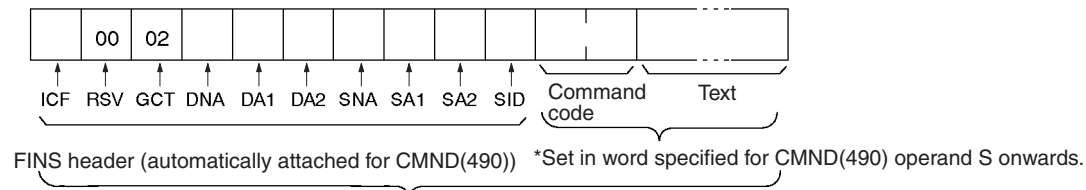
*With Host Link communications, the header, FCS, and terminator are attached before and after the frame.

3-3-2 FINS Response Frame Configuration

	00	02									

ICF RSV GCT DNA DA1 DA2 SNA SA1 SA2 SID Command code End code Text

FINS header (deleted automatically for CMND(490))   *Set in word specified for CMND(490) operand D onwards.
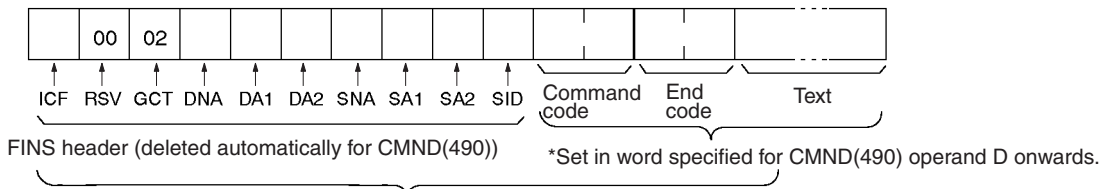
*With Host Link communications, the header, FCS, and terminator are added before and after the frame.

3-3-3 Individual Items in Command/Response Frames

ICF
The ICF (Information Control Field) is configured as shown in the following diagram.

Bit

7	6	5	4	3	2	1	0
1		0	0	0	0	0	

Always 0. (See note.)
Response (0: Required; 1: Not required)
Data classification (0: Command; 1: Response)
Bridges (0: Not used; 1: Used)
Always 1.
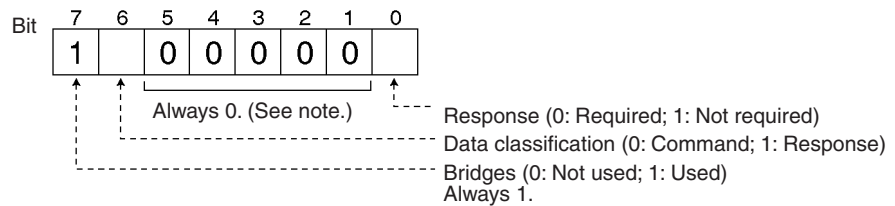
Note Set bits 01 to 05 to 0 when sending a FINS command. Do not access these bits when receiving a FINS response.

RSV

RSV (Reserved) is always 00 hex. These bits are used by the system. Do not access them in the response.

GCT

When communicating across up to 8 network layers with CPU Unit with unit version 2.0 or later, set the GCT (Gateway Count: Number of Bridges Passed Through) to 07 hex when sending a FINS command. Otherwise, set the GCT to 02 hex (see note) when sending. When receiving a FINS response, GCT is decremented one for each bridge (network) that is passed through and the resulting value is received. This value is for system use; do not access it.

Note For a CS/CJ-series CPU Unit with unit version 2.0 or later, CP-series CPU Unit, or NSJ Controller, CX-Programmer version 4.0 or higher can be used to set routing tables that start the GCT at 07 hex. For a CS/CJ-series CPU Unit with unit version 3.0 or later, CX-Programmer (CX-Net) Ver. 5.0 or higher can be used to set routing tables that start the GCT at either 07 Hex or 02 Hex. For details, refer to *1-4-2 Communications through a Maximum of 8 Network Levels* in the *CS Series PLC Operation Manual* or the *CJ Series PLC Operation Manual*.

DNA

Destination network address. Specify within the following ranges (hex).
00:        Local network
01 to 7F: Remote network address (decimal: 1 to 127)

DA1

Destination node address. Specify within the following ranges (hex).
00:        Internal communications in PLC
01 to 20:   Node address in Controller Link Network (1 to 32 decimal)

01 to FE: Ethernet (1 to 254 decimal,
           for Ethernet Units with model numbers ending in ETN21)
FF: Broadcast transmission

DA2

Destination unit address. Specify within the following ranges (hex).
00:        CPU Unit
FE: Controller Link Unit or Ethernet Unit connected to network
10 to 1F: CPU Bus Unit
E1:   Inner Board

SNA

Source network address. Specify within the following ranges (hex).
00:        Local network
01 to 7F: Remote network (1 to 127 decimal)

SA1

Source node address. Specify within the following ranges (hex).
00:        Internal communications in PLC
01 to 20:   Node address in Controller Link Network (1 to 32 decimal)

01 to FE: Ethernet (1 to 254 decimal,
            for Ethernet Units with model numbers ending in ETN21)

SA2
Source unit address. Specify within the following ranges (hex).
00:         CPU Unit
10 to 1F: CPU Bus Unit

SID
Service ID. Used to identify the process generating the transmission. Set the SID to any number between 00 and FF

Note   1.   The unit address for a CPU Bus Unit is 10 (hexadecimal) plus the unit number set on the front panel of the CPU Bus Unit.

2.   With a CS/CJ-series CPU Unit with unit version 2.0, CP-series CPU Unit, or NSJ Controller, the GCT (Gateway Count: Number of Bridges Passed Through) in FINS command/response frames is decremented from to 07 hex (variable). The GCT was previously decremented from 02 hex. For CS/CJ-series CPU Unit with unit version 3.0 or later, the GCT (Gateway Count: Number of Bridges Passed Through) in FINS command/response frames is decremented from to 02 hex by default. If the user specified CX-Net for this CPU Unit version, the GCT will be decremented from 07 hex. With a CS/CJ-series CPU Unit with unit version 3.0 or later, NSJ Controller, or CP-series CPU Unit, the GCT will be decremented from 02 hex by default and from 07 hex if the user selects CX-Net.

3.   The GCT (Gateway Count: Number of Bridges Passed Through) in the FINS header in FINS command/response frames should not be checked in the user applications, e.g., in the host computer. The GCT is for system use only and verification may fail if attempted from a user application. This is particularly important for CS/CJ-series CPU Unit with unit version 2.0 or later, CP-series CPU Unit, or NSJ Controller.

3-4   Settings for Sending FINS Commands
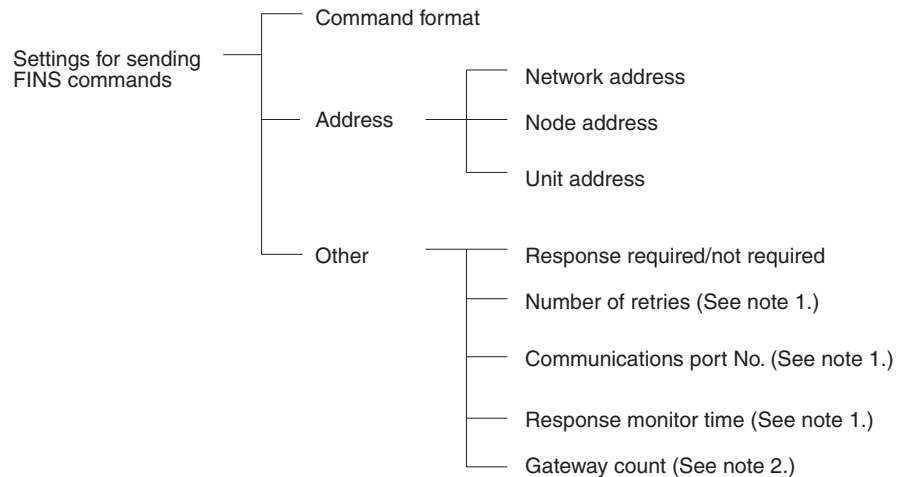
Note   1.   Set these as operands when executing CMND(490).

2.   Do not set the gateway count when using CMND(490).

3-4-1   FINS Command and Response Formats

Command Format

As shown below, the command format basically consists of the command code (four digits hexadecimal) and parameters (text).

Command code (See note.) 4 digits hexadecimal (2 bytes)	Text (Various kinds of data) The length depends on the command code.
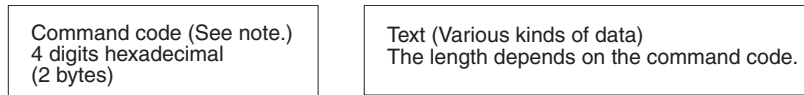
Note The command code is a 2-byte code that expresses the content of the command. A FINS command must begin with a 2-byte command code. If there is also text, it is added after the command code.

Example: Command for Reading I/O Memory
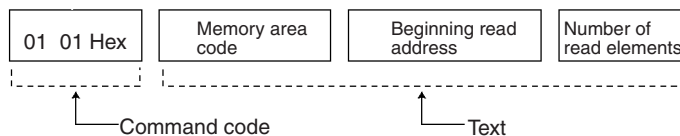
The following data would read 10 words starting from D00010.
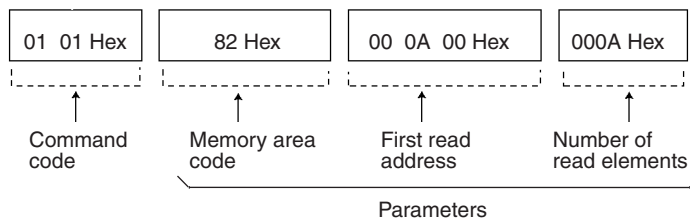
Response Format

As shown below, the response format basically consists of the command code (four digits hexadecimal), end code, and parameters (text).

Command code 4 digits hexadecimal (2 bytes)	End code (See note.)	Text (Various kinds of data) The length depends on the command code.
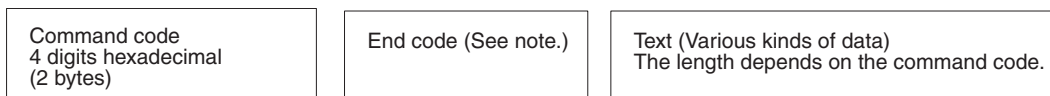
Note The end code is a 2-byte code that shows the command execution result. (The first byte shows the general category, and the second byte shows the detailed results.)

Example: Response from Reading I/O Memory
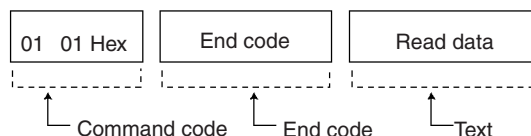
Actual response data would be as follows:
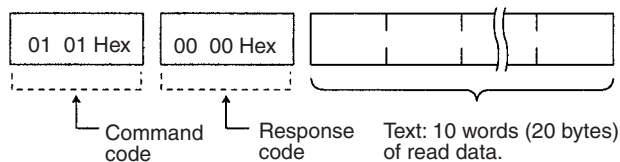
3-4-2 Addresses in FINS Commands

FINS commands are transmitted across networks and to various devices (via network nodes). Designate the addresses as follows:

- Designate the device from which the command is to be sent, the network that the device is on, and the node through which the command is to transit.
- Designate the device to which the command is to be sent, the network the device is on, and the node through which command is to transit.

Addresses must be provided for the network, node, and device (unit) to identify them. FINS commands include these addresses (the transmission source and destination addresses) in the command/response frames.

Addresses for FINS Commands

Address	Values	Designation method	
		CMND(490) operand designation	Designation in frame when frame is created
Network address	1 to 127 (01 to 7F Hex) Local node address: 00 Hex	Yes	Yes
Node address	1 to 254 (01 to FE Hex) (See note.) **Note** The node addresses differ for each network. Internal Communications in PLC: 00 Hex For Controller Link: 01 to 3E Hex (1 to 62) For Ethernet Units with model numbers ending in ETN21: 01 to FE Hex (1 to 254) For Ethernet Units with other model numbers: 01 to 7E Hex (1 to 126)	Yes	Yes
Unit address	•CPU Unit: 00 Hex •CPU Bus Unit: Unit No.+ 10 Hex •Special I/O Unit: Unit No.+ 20 Hex •Inner Board: E1 Hex •Computer: 01 Hex •Unit connected to network: FE Hex	Yes	Yes

Devices on the Same Network
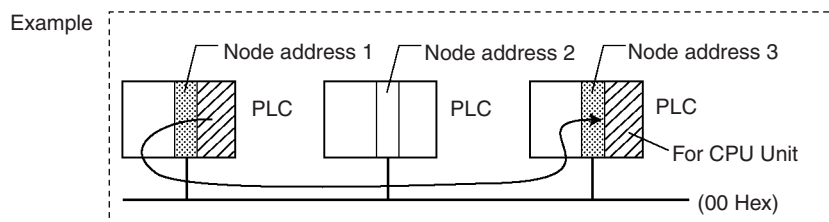
Address	Source address (See note 1.)		Destination address (See note 2.)	
	FINS command symbol	Example value	FINS command symbol	Example value
Network address	SNA	00 Hex	DNA	00 Hex
Node address	SA1	01 Hex	DA1	03 Hex
Unit address	SA2	00 Hex	DA2	00 Hex

Note 1. The transmission source address will be automatically incorporated into the frame if the FINS command is sent with CMND(490). If sending the

FINS command by Host Link communications, then put the source address in the message.

2. Set the transmission destination address in the control code (C) operand if sending the FINS command with CMND(490). If sending the FINS command by Host Link communications, then put the destination address in the message.

Devices on Different Networks
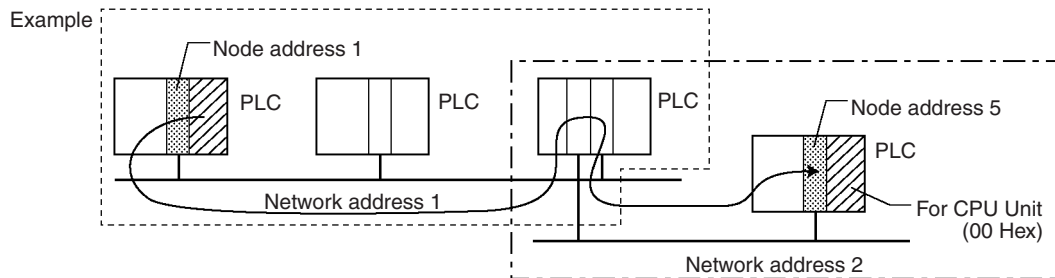
Address level	Source address (See note 1.)		Destination address (See note 2.)	
	FINS command symbol	Example value	FINS command symbol	Example value
Network address	SNA	01 Hex	DNA	02 Hex
Node address	SA1	01 Hex	DA1	05 Hex
Unit address	SA2	00 Hex	DA2	00 Hex

Note 1. The transmission source address will be automatically incorporated into the frame if the FINS command is sent with CMND(490). If sending the FINS command by Host Link communications, then put the source address in the message.

2. Set the transmission destination address in the control code (C) operand if sending the FINS command with CMND(490). If sending the FINS command by Host Link communications, then put the destination address in the message.

Unit Addresses
Set the unit address for the following purposes:

• To identify the Unit when there is more than one device connected at the same node on a network.

• To identify the type of device (CPU Unit, CPU Bus Unit, etc.) at the destination.

Note The meanings of FINS commands will vary depending on the Unit at the destination even when the commands have the same command code. This is why the Unit at the destination must be identified by the unit address.

Unit addresses are as follows:

• CPU Unit: 00 Hex

• CPU Bus Unit: Unit number + 10 hex

• Special I/O Unit:
                Unit number + 20 hex

• Inner Board: E1 Hex (CS Series only)

• Computer: 01 Hex

• Communications Unit with the specified node address connected to network with the specified network address (Controller Link or Ethernet):
                FE Hex

Unit address	00 Hex	Unit No. + 10 Hex	E1 Hex	01 Hex
Contents	Node address	Node address	Node address	Node address

Note It is also possible to set the serial port (No. 1 to 4) for the destination device.
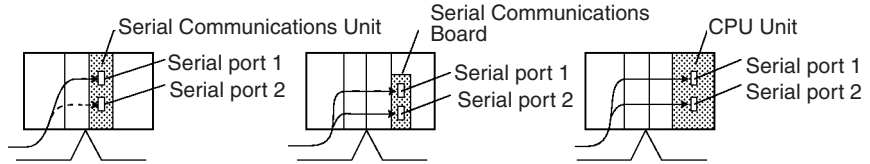
Unit Addresses for Computers Connected to Serial Ports

The unit addresses for host computers connected to a CS/CJ/CP/NSJ serial port (e.g., on a CPU Unit, Option Board, Serial Communications Unit, or Serial Communications Board) are shown in the following table.

Unit/Board	Peripheral port	RS-232C port
CS/CJ-series CPU Unit	FD Hex	FC Hex
NSJ Controller	---	FC Hex (Serial port C on Controller Section)

Unit/Board	Serial port 1	Serial port 2
CS/CJ -series Serial Communications Board	E4 Hex	E5 Hex
CS/CJ-series Serial Communications Unit	80 Hex + 04 Hex x unit number	81 Hex + 04 Hex x unit number
CP-series Option Board	FD Hex	FC Hex

For the SEND, RECV, and CMND instructions, the CPU Unit will add the proper unit address based on the unit address of the Unit/Board and the specified serial port. It is not necessary to consider these addresses in the ladder-diagram program.

Unit Addresses for Serial Ports on Serial Communications Boards and Units

The network address and serial port's unit address must be allocated and the routing table's local network table must be created for Several settings are required when making network settings (FINS command system settings) for serial communications through a serial port on a CS Series Serial Communications Board or CS/CJ Series Serial Communications Unit. The network address and the serial port's unit address must be allocated and the routing table's local network table must be created. The following diagrams show how to set the serial port's unit address.

• Example 1: Serial Communications Board
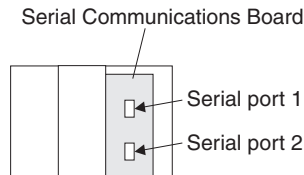
Serial port on Board	Serial port's unit address
Serial port 1	E4 hex (228 decimal)
Serial port 2	E5 hex (229 decimal)

• Example 2: Serial Communications Unit

Serial Communications Unit

Serial port 1
Serial port 2
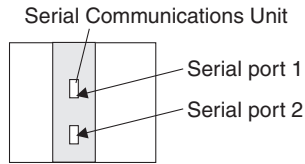
Serial port on Unit	Serial port's unit address	Example: Unit number 1
Serial port 1	80 hex + 04 hex × unit number	80 hex + 04 hex × 1 = 84 hex (132 decimal)
Serial port 2	81 hex + 04 hex × unit number	81 hex + 04 hex × 1 = 85 hex (132 decimal)

Unit addresses for serial port 1:

Unit number	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Hexadecimal	80	84	88	8C	90	94	98	9C	A0	A4	A8	AC	B0	B4	B8	BC
Decimal	128	132	136	140	144	148	152	156	160	164	168	172	176	180	184	188

Unit addresses for serial port 2:

Unit number	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Hexadecimal	81	85	89	8D	91	95	99	9D	A1	A5	A9	AD	B1	B5	B9	BD
Decimal	129	133	137	141	145	149	153	157	161	165	169	173	177	181	185	189

Summary of Addresses

The three addresses used in FINS commands can be summarized as follows (refer to the following diagram):

Network Address
An address that identifies the entire network. All nodes on the same network have the same network address.

Node Address
An address that identifies an individual node on a network, such as a PLC or host computer.

Unit Address

For a PLC, an address that identifies the specific Unit that is participating in the communication in the PLC. For a host computer, an address that identifies the specific application that is participating in the communication in the computer.
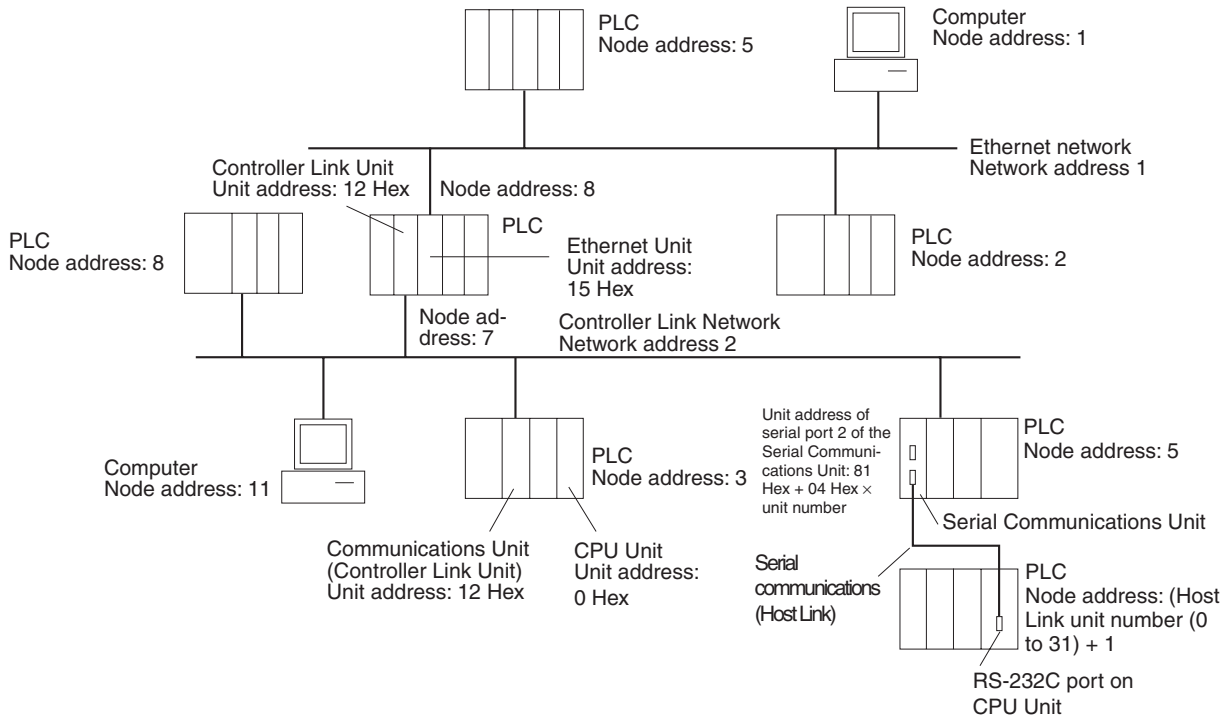
3-4-3 Other FINS Command Settings

Aside from the addresses, the following data must be set.

Setting	Content	Values	Designation method	
			CMND(490) operand designation	Designation in frame when frame is created
Number of retries	Number of times to retry sending the command.	0 to F Hex (0 to 15 times)	Yes	No
Port No.	Logical communications port. CS/CJ/CP-series CPU Units have 8 communications ports, so 8 communications commands can be executed simultaneously. To execute 9 or more commands, simultaneously, it is necessary to set up exclusive control.	0 to 7 Hex	Yes	No
Serial port No.	Specifies the number of the serial port of the Unit with Host Link capabilities.	0: Unit/Board 1: Serial port 1 for Serial Communications Board/Unit or Peripheral port for CPU Unit 2: Serial port 2 for Serial Communications Board/Unit or RS-232C port for CPU Unit	Yes	No
Response monitor time	Monitors the time it takes to return a response. If a response is not returned within the designated time, a response timeout is generated.	0001 to FFFF Hex (0.1 to 6,553.5 seconds)	Yes	No
Response required/ not required (ICF bit 0)	Designates whether or not a response is required.	0 or 1 (bit)	Yes	Yes
Gateway count	Designates the number of networks that can be accessed.	00 to 07 Hex	No	Yes

Note 1. Unit address are fixed for Units and Boards, as well as for serial ports. For the SEND(090), RECV(098), and CMND(490) instructions, the CPU Unit will add the proper unit address based on the unit address of the Unit/Board and the specified serial port. It is not necessary to consider these addresses in the ladder-diagram program.
Serial Port 1:
80 Hex + 04 Hex x unit number for Serial Communications Units, E4 Hex for Serial Communications Boards, and FC Hex (CPU Unit's RS-232C or serial port 2 on CP1H Option Board)
Serial Port 2:
81 Hex + 04 Hex x unit number for Serial Communications Units, E5 Hex for Serial Communications Boards, and FD Hex (CPU Units peripheral port or serial port 1 on CP1H Option Board)

2. The gateway count is decremented one for each bridge (network) that is passed through.

3-4-4   CMND(490) Setting Example

The designated number of bytes of FINS command data from the first command word designated by operand S is sent to the designated unit address via the node address on the network address designated by operand C, and the response is stored for the number of bytes of data received starting from D.

```
        ┌──────────────┐
────────│     CMND     │
        ├──────────────┤
        │      S       │   S: First command word
        ├──────────────┤
        │      D       │   D: First response word
        ├──────────────┤
        │      C       │   C: First control word
        └──────────────┘
```
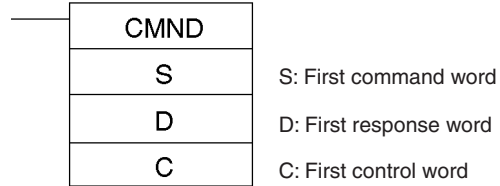
In this example, a command (MEMORY AREA READ: 0101 Hex) for reading D00010 to D00019 of the PLC at node 02 is sent using CMND(490).

D00010: Memory area code (82 Hex), address 000A00
Number of elements read: 10 = 0A Hex

S: First command word

S	01	01

Command code

S+1	82	00

Beginning read address
Memory area code

S+2	0A	00

Beginning read address

S+3	00	0A

Number of elements read

D: First response word

D	01	01

Control code

D+1	00	00

End code

D+2		

Read data

D+11		

Read data

C: First control word

C	00	08

Number of command data bytes

C+1	00	18

Number of response data bytes

C+2	00	00

Destination network address
Serial port No.

C+3	02	00

Destination unit address
Destination node address

C+4	00	03

Number of retries
Communications port number
Response required/not required

C+5	00	00

Response monitor time

3-5 FINS Commands with Host Link Protocol

FINS commands can be sent and received using the Host Link protocol between interconnected host computers and PLCs.

3-5-1 Connection Configurations

One of the following two methods can be used to send and receive FINS commands using the Host Link protocol.

Sending from a Computer to a CPU Unit

Note The host computer can be connected to the peripheral port or RS-232C port on the CPU Unit or to a serial ports on a Serial Communications Unit/Board. The Host Link protocol must be used regardless of the point of connection.

CPU Unit Directly Connected to Host Computer
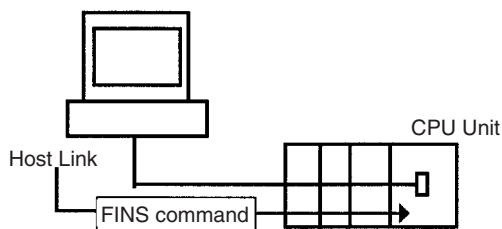
CPU Units on a Network
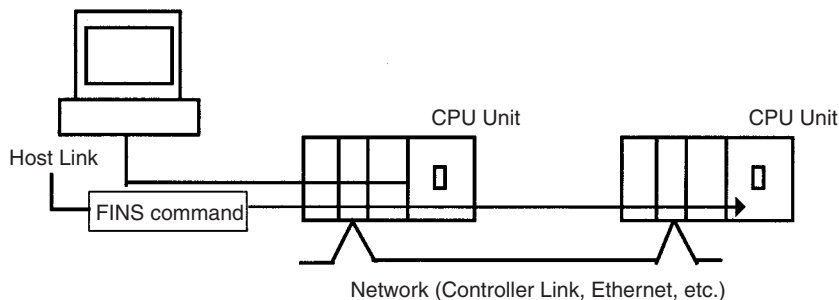
Sending from a CPU Unit to a Computer (Slave Initiation)

Note The host computer can be connected to the peripheral port or RS-232C port on the CPU Unit or to a serial ports on a Serial Communications Unit/Board. The Host Link protocol must be used regardless of the point of connection.

CPU Unit Directly Connected to Host Computer
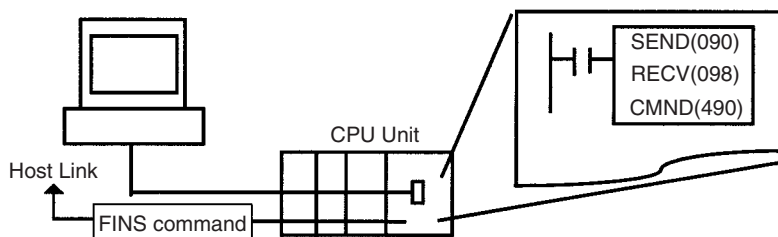
CPU Unit Directly Connected to Host Computer on a Network
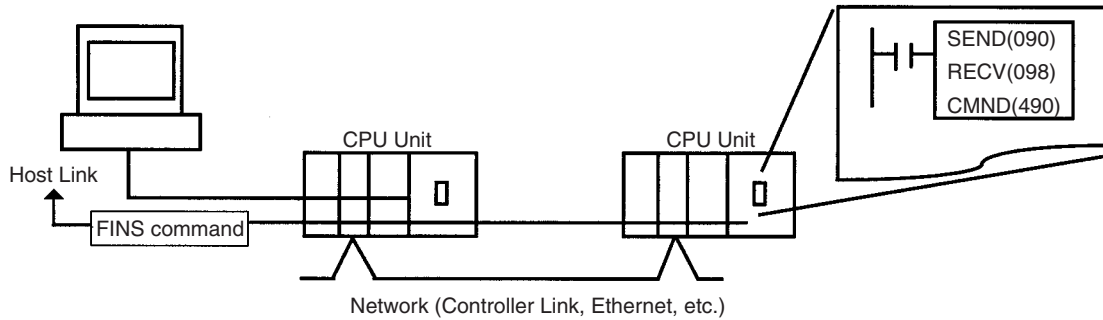
Note 1. Host Link communications handle ASCII data, so data is sent and received in ASCII. Hexadecimal values in FINS command and response frames must, therefore, also be sent and received in ASCII when they are handled using Host Link communications.

2. When a FINS command sent from a host computer or the CPU Unit (with the CMND instruction) is received by a Serial Communications Board or Unit with version number Ver. 1.2 or later, that PLC acts as the Host Link Master and it can send the FINS command to a Slave PLC through the Host Link system.
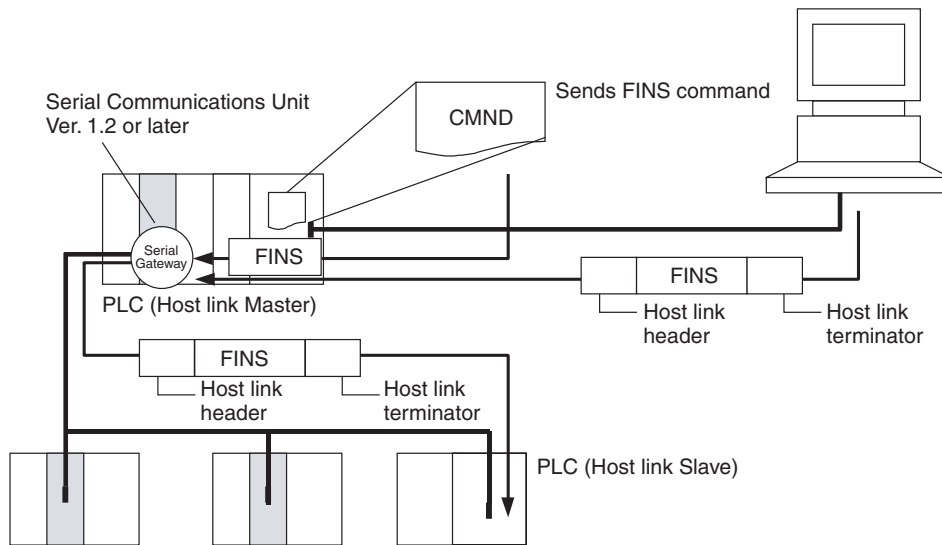
3-5-2 Overview of Command and Response Frames

When FINS commands and responses are sent or received using Host Link communications, the frame must be preceded by a Host Link header and followed by a Host Link FCS and terminator as shown below.

Command Frame   Use the following format to send FINS command frames.
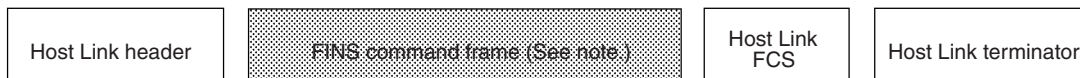
Note A FINS command frame also consists of the response wait time, the destination node address, the source node address, and other FINS command format data.

Response Frame   The CS/CJ/CP-series CPU Unit or NSJ Controller that receives the command will return the following response frame to the host computer.

Host Link header	FINS response frame (See note.)	Host Link FCS	Host Link terminator

Note A FINS response frame also consists of the contents set at the time of transmission and the FINS command response format data.

3-5-3   Sending Commands from the Computer to the CPU Unit

Command Format from Host Computer

Use the following command format to send FINS commands from the host computer to the CPU Unit.

Note The length of the command must be not more than 1,114 characters. FINS commands cannot be partitioned into separate frames for sending.

Sending Commands to a CPU Unit Directly Connected to the Host Computer

Note The following format is also applicable for a host computer connected to a Serial Communications Board or a Serial Communications Unit.
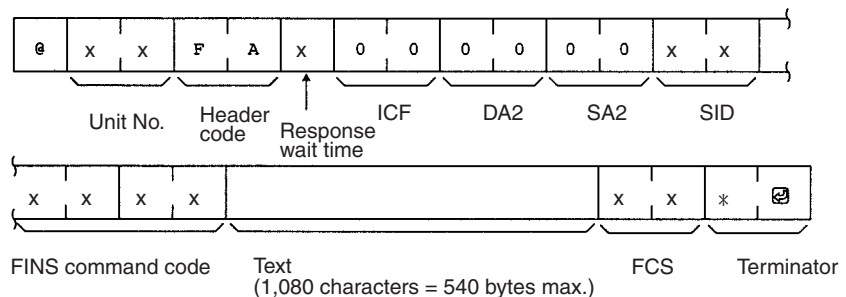
Sending Commands to a CPU Unit on a Network

Note The following format can also be used to send FINS commands to a CPU Unit connected to the host computer.
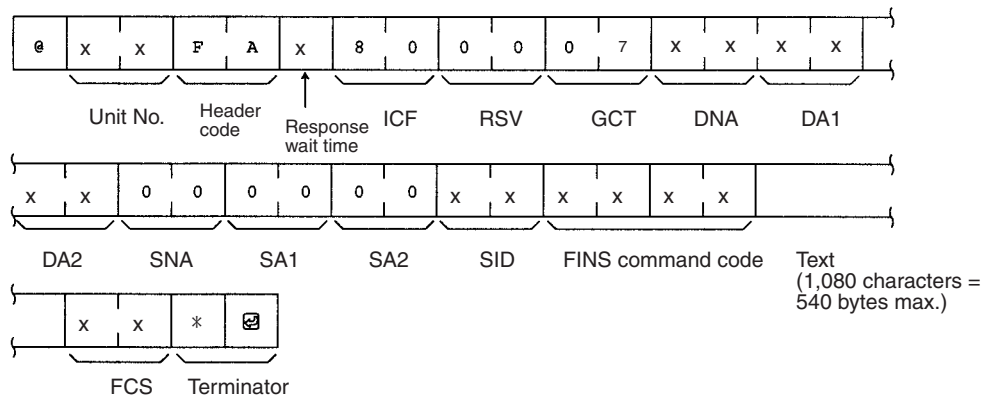
Host Link Settings   <u>@</u>
The @ symbol must be attached to the beginning of the command.
<u>Unit Number</u>
The unit number set is that of the destination CPU Unit connected to the host

computer. When the host computer is connected to a CPU Unit, the unit number is designated in the PLC Setup.

When the host computer is connected to a Serial Communications Board or a Serial Communications Unit, the unit number is the designated in the Setup for the Board or Unit.

Header Code

The header code distinguishes between different types of commands. Set "FA" (ASCII: 46, 41) when using FINS commands.

Response Wait Time

The response wait time sets the time from when the CPU Unit receives a command block until it starts to return a response. It can be set from 0 to F in hexadecimal, in units of 10 ms.

Example:

   If F(15) is set, the response will begin to be returned 150 ms (15×10 ms) after the command block was received.

ICF (Information Control Field)

Specifies whether or not there are network relays. Set "80" (ASCII: 38,30) when sending an FINS command to a CPU Unit on a network. Set "00" (ASCII: 30,30) when sending to a CPU Unit connected directly to the host computer.

RSV (Reserved)

Set "00" (ASCII: 30,30). Setting RSV is required only when sending to a CPU Unit on a network.

GCT (Gateway Count)

This is the number of networks through which the transmission can be relayed. Set "07" (ASCII: 30, 37). Setting GCT is required only when sending to a CPU Unit on a network.

DNA, DA1, DA2

Set the destination network, node, and unit addresses.

DNA (Destination Network Address)

   Set between 00 and 7F Hex (0 and 127 decimal). Setting DNA is required only when sending to a CPU Unit on a network.

DA1 (Destination Node Address)

   Set within the following ranges. Setting DA1 is required only when sending to a CPU Unit on a network.

   Ethernet Units with model numbers ending in ETN21:

                   01 to FE hex (1 to 254)

   Ethernet Units with other model numbers:

                   01 to 7E hex (1 to 126)

   Controller Link Unit: 01 to 20 hex (1 to 32 decimal)

   SYSMAC NET: 01 to 7E hex (1 to 126 decimal)

   SYSMAC LINK: 01 to 3E hex (1 to 62 decimal)

DA2 (Destination Unit Address)

   Refer to *3-4-2 Addresses in FINS Commands* for details on unit addresses.

   In Host Link mode, it is assumed that the destination unit is the CPU Unit, so set "00" (ASCII: 30, 30).

SNA (Source Network Address), SA1 (Source Node Address)

Set the source network and node addresses. Set both to "00" (ASCII: 30, 30) regardless of whether or not there is a network relay.

Setting SNA and SN1 is required only when sending to a CPU Unit on a network.

SA2 (Source Unit Address)

Set the unit address of the Unit physically connected to the host computer. The setting changes depending on the connected Unit.

When connected to the CPU Unit, Serial Communications Board, or a Serial Communications Unit, set "00" to indicate the CPU Unit (ASCII: 30, 30).

SID (Source ID)

The SID is used as a counter when resending. It should normally be set to "00" (ASCII: 30, 30).

Command Code, Text

Set the command code and text according to the FINS command and response formats.

FCS (Frame Check Sequence)

Set a 2-character FCS. Refer to *FCS Calculations* under *2-2 Command/ Response Formats* for the FCS calculation method.

Terminator

The terminator is a required delimiter at the end of a command. Set the terminator to ∗CR (ASCII: 2A, 0D).

Response Format from a CPU Unit

The following response format is used to return responses from the CPU Unit to the host computer.

Note The length of the response must be not more than 1,115 characters. Of this, the response data without the response code is 1,076 characters (538 bytes).

Responses from a CPU Unit Directly Connected to the Host Computer
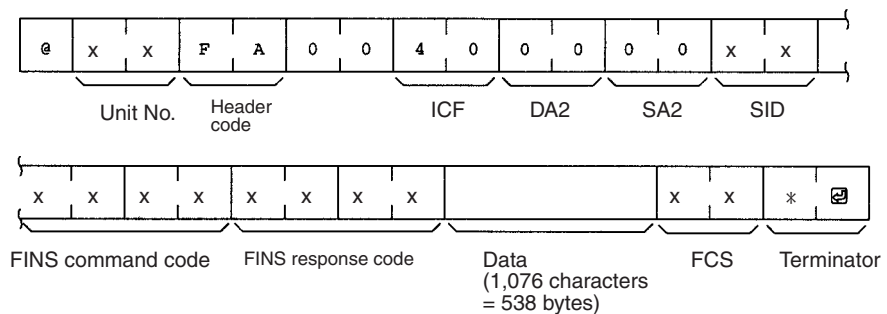
Responses from a CPU Unit on a Network
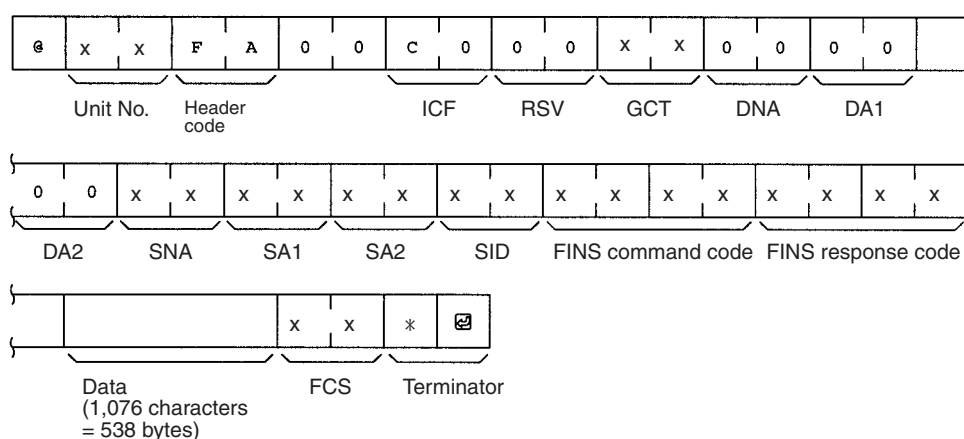
Host Link Settings

@

The @ symbol must be attached to the beginning of the response.

Unit Number and Header Code

The same unit number and header code specified in the FINS command that was received will be returned.

ICF (Information Control Field)

For a CPU Unit on a network, "C0" (ASCII: 43, 30) will be returned. For a CPU Unit connected directly to the host computer, "40" (ASCII: 34,30) will be returned.

RSV (Reserved)

This section is reserved for the system. Do not access the RSV.

GCT (Gateway Count)

This section is reserved for the system. Do not access the GCT. The same GCT that was specified in the command that was received will be returned. Setting GCT is required in the response format only from a CPU Unit on a network.

DNA (Destination Network Address), DA1 (Destination Node Address), DA2 (Destination Unit Address)

The same contents specified for SNA, SA1, and SA2 in the command that was received will be returned.

Setting DNA and DA1 is required for response formats only from a CPU Unit on a network.

SNA (Source Network Address), SA1 (Source Node Address), SA2 (Source Unit Address)

The same contents specified for DNA, DA1, and DA2 in the command that was received will be returned.

Setting SNA and SN1 is required for response formats only from a CPU Unit on a network.

SID (Source ID)

The SID that was specified in the command that was received will be returned.

Command Code, Response Code, Text

The command code, response code, and text corresponding to the FINS command and response formats will be returned.

FCS (Frame Check Sequence)

A 2-character FCS will be returned. Refer to *FCS Calculations* under *2-2 Command/Response Formats* for the FCS calculation method.

Terminator

The terminator is a required delimiter at the end of a command. The terminator ∗CR (ASCII: 2A, 0D) will be returned.

Example: FINS Command Settings for Sending to CPU Unit on a Network

With Host Link communications, FINS command transmissions and receptions are handled in ASCII, so hexadecimal values in FINS command frames must be sent as ASCII. For example, the hexadecimal value "0" would be "30 Hex" in ASCII, and the hexadecimal value "A" would be "41 Hex" in ASCII.

The destination network address, node address, and unit number address are explained using the following network as an example.
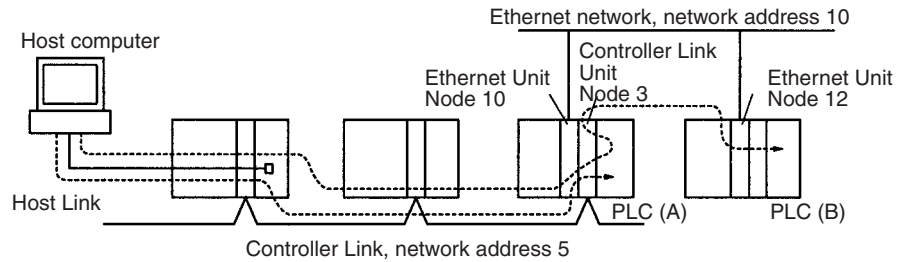
Sending a Command from a Host Computer to PLC (A)

The following addresses are specified to the CPU Unit at network address 5, node address 3:

Destination network address (DNA):	05 (30, 35)
Destination node address (DA1):	03 (30, 33)
Destination unit address (DA2):	00 (30, 30)
(Command addressed to CPU Unit)	

Sending a Command from a Host Computer to PLC (B)

The following addresses are specified to the CPU Unit at network address 10, node address 12:

Destination network address (DNA):	0A (30, 41)
Destination node address (DA1):	0C (30, 43)
Destination unit address (DA2):	00 (30, 30)
(Command addressed to CPU Unit)	

3-5-4 Sending FINS Commands to the Host Computer from the CPU Unit

With normal Host Link communications, FINS commands are sent from the host computer to the CPU Unit. Commands can also be sent, however, from the CPU Unit to the host computer. Any FINS command can be sent to the host computer using SEND(090), which sends CPU Unit data to the host computer, RECV(098), which receives data from the host computer, or CMND(490).

Slave-initiated communications allows the host computer to be notified (unsolicited communications) when an error is generated, for example, on a production line controlled by a CPU Unit. Since the host computer no longer needs to regularly communicate with the CPU Unit, the load on the host computer is reduced.

When an Ethernet Unit or Controller Link Unit are mounted to the Backplane of the CPU Unit, commands can be sent to the host computer from a CPU Unit on a network on another level (up to three network levels).

Note In principle, send commands to the host computer only when one host computer is connected to one CPU Unit. If more than one CPU Unit is connected to the host computer, the commands may collide with each other and prevent normal communications. Create a program that will exclusively control commands that are being sent to a host computer to which multiple CPU Units are connected.

Considerations when Sending Commands from a CPU Unit

Consider the following items when using instructions (SEND(090), RECV(098), and CMND (490)) to send commands from the CPU Unit.

1,2,3...   1. SEND(090), RECV(098), and CMND (490) executed by the CPU Unit are converted to the same format for FINS commands that are sent to CPU Units on networks.

2. A program must be created to process the commands received by the host computer.

3. When instructions (SEND(090), RECV(098), and CMND (490)) are executed in a CPU Unit, some of the control data settings will be different. Refer to the relevant instruction specifications.

3-5-5   Sending Commands from the CPU Unit

When controls are being implemented by sending commands from the local CPU Unit or another CPU Unit on a network to a host computer, three instructions can be used in the user program: SEND(090), RECV(098), and CMND(490).

Send(090)   Memory area data can be sent from the CPU Unit to the host computer by using SEND(090).

Command Format Received by the Host Computer

The FINS command transmitted to the host computer when SEND(090) is executed is MEMORY AREA WRITE (command code 0102). The command format received by the host computer is as shown in the following diagram. Refer to *MEMORY AREA WRITE: 0102* in *Section 5 FINS Commands* for details.
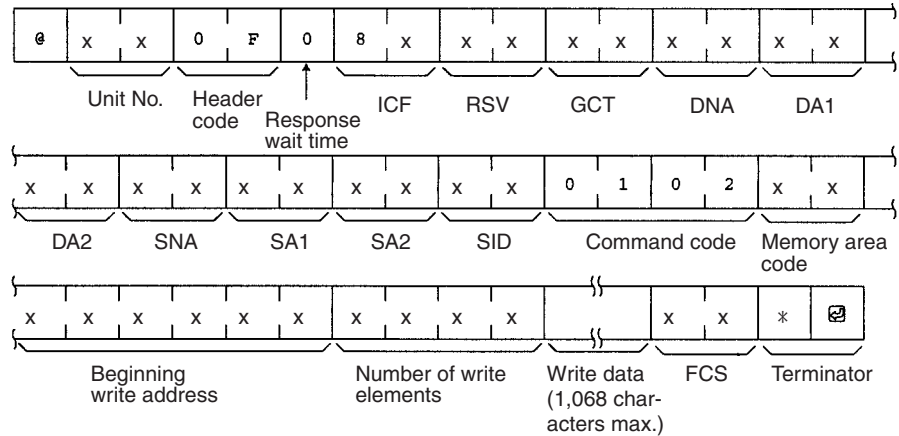
Control Words

Control data must be set before SEND(090) is executed. The control data is written in the following format, starting from the first control word.

Word	Bits 00 to 07	Bits 08 to 15
C	Number of send words	
C+1	Destination network address	Bits 08 to 10: Serial port number
C+2	Destination unit address	Destination node address
C+3	Bits 00 to 03: No. of retries	Bits 08 to 10: Comm. port number Bit 15: Response setting
C+4	Response monitor time (unit: 0.1 s)	

Number of Send Words

Set the total number of words of data to be transferred to the host computer.

Serial Port Number

Set the serial port number to which the host computer is connected.

Destination Network Address

Set the network address of the destination node. Set "00" to send communications within the local network.

Destination Node Address

Set the node address of the destination node. Set "00" when transmitting within the local PLC.

Destination Unit Address

Set the unit address of the Unit to which the host computer is connected.

Response Setting

Normally this bit is set to 0 to require a response. When a response is not required, set this bit to 1.

Communications Port Number

Set the port number in the CPU Unit which will transmit SEND(090).

Number of Retries

Set the maximum number of times SEND(090) is to be resent if no response is returned.

Response Monitor Time

If the Response Setting is set to require a response, set the response monitor time.

<u>**Control Word Settings**</u>

The setting range for each item is shown on the following table.

Item	Setting
Number of send words	0001 to 010B (1 to 267 words)
Serial port number	00: Do not set. 01: Port 1 02: Port 2
Destination network address	00: Local network 01 to 7F: Network address (1 to 127)
Destination node address	00: Internal communications in PLC 01 to FE: Node address of Ethernet Unit with model number ending in ETN21 (1 to 254) 01 to 7E: Node address of Ethernet Unit with other model number (1 to 126) 01 to 20: Node address (1 to 32) for Controller Link
Destination unit address	00: CPU Unit 10 to 1F: Serial Communications Unit (unit address 0 to 15) E1: Inner Board (Serial Communications Board)
Response setting	0: Required 1: Not required
Communications port number	0 to 7 (0 to 7)
Number of retries	0 to F (0 to 15)
Response monitor time	0000: Default 0001 to FFFF: 0.1 to 6,553.5 s (unit 0.1 s)

Note To execute SEND(090) normally, programming needs to be written to process the data received by the host computer and return the proper response.

RECV(098)   By using RECV(098), data from the host computer can be written to a memory area in the CPU Unit.

Command Format Received by the Host Computer

The FINS command transmitted to the host computer when RECV(098) is executed is MEMORY AREA READ (command code 0101). The command format received by the host computer is shown in the following diagram.

Refer to *MEMORY AREA READ: 0101* in *Section 5 FINS Commands* for details
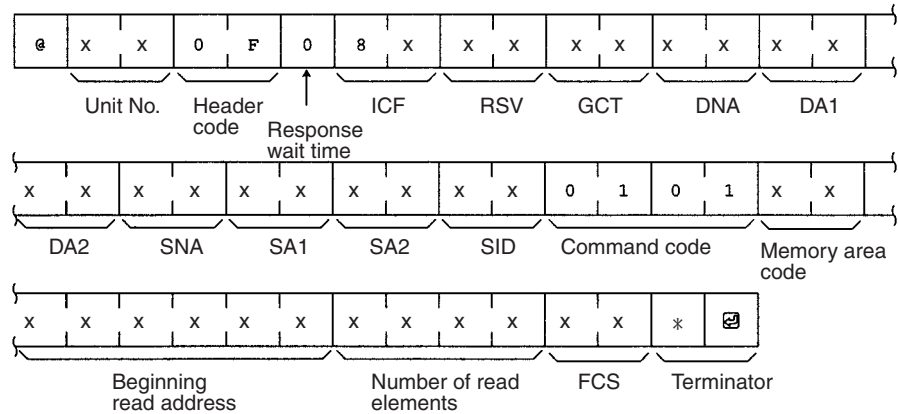
Control Words

Control data must be set before RECV(098) is executed. The control data is written in the following format, starting from the first control word.

Word	Bits 00 to 07	Bits 08 to 15
C	Number of read words	
C+1	Destination network address	Bits 08 to 10: Serial port number
C+2	Destination unit address	Destination node address
C+3	Bits 00 to 03: No. of retries	Bits 08 to 10: Comm. port number
C+4	Response monitor time (unit: 0.1 s)	

Number of Read Words

Set the total number of words of data to be read from the host computer.

Serial Port Number

Set the serial port number to which the host computer is connected.

Destination Network Address

Set the network address of the destination node (i.e., the computer). Set "00" to send communications within the local network.

Destination Node Address

Set the node address of the destination node (i.e., the computer). Set "00" when transmitting within the local PLC.

Destination Unit Address

Set the unit address of the Unit to which the host computer is connected.

Communications Port Number

Set the port number in the CPU Unit which will transmit RECV(098).

Number of Retries

Set the maximum number of times RECV(098) is to be resent if no response is returned.

Response Monitor Time

Set the time to wait for a response

<u>**Control Word Settings**</u>

The setting range for each item is shown on the following table.

Item	Setting
Number of read words	0001 to 010D (1 to 269 words)
Serial port number	00: CPU Unit, Inner Board, CPU Bus Unit 01: Port 1 02: Port 2
Destination network address	00: Local network 01 to 7F: Network address (1 to 127)
Destination node address	00: Internal communications in PLC 01 to FE: Node address of Ethernet Unit with model number ending in ETN21 (1 to 254) 01 to 7E: Node address of Ethernet Unit with other model number (1 to 126) 01 to 3E: Node address (1 to 62) for Controller Link
Destination unit address	00: CPU Unit 10 to 1F: Serial Communications Unit (unit address 0 to 15) E1: Inner Board (Serial Communications Board)
Response required/not required	0: Response required 1: Response not required
Communications port number	0 to 7 (0 to 7)
Number of retries	0 to F (0 to 15)
Response monitor time	0000: Default 0001 to FFFF: 0.1 to 6,553.5 s (unit 0.1 s)

Note To execute RECV(098) normally, programming needs to be written to process the command received by the host computer and return the proper data.

CMND(490) By using CMND(490), controls can be implemented by sending FINS commands to the host computer.

<u>**Command Format Received by the Host Computer**</u>

CMND(490) can be used to send any FINS command to the host computer The command format received by the host computer is shown in the following diagram.

| @ | x | x | O | F | 0 | 8 | x | 0 | x | 0 | x | x | x | x | x |

Unit No.　Header code　Response wait time　ICF　RSV　GCT　DNA　DA1

| x | x | x | x | x | x | x | x | x | x | x | x | x | x |

DA2　SNA　SA1　SA2　SID　Command code　Data (1,080 characters max.)

| x | x | * | ↵ |

FCS　Terminator

Control Words

Control data must be set before CMND(490) is executed. The control data is written in the following format, starting from the first control word.

Word	Bits 00 to 07	Bits 08 to 15
C	Number of bytes of command data	
C+1	Number of bytes of response data	
C+2	Destination network address	Bits 08 to 10: Serial port number
C+3	Destination unit address	Destination node address
C+4	Bits 00 to 03: No. of retries	Bits 08 to 10: Comm. port number Bits 15: Response setting
C+5	Response monitor time	

Number of Bytes of Command Data

Set the number of bytes of command data (including the command code) that are stored from the first command word

Number of Bytes of Response Data

Set the number of bytes of response data (including command code and end code) that are stored from the first response word.

Serial Port Number

Set the serial port number to which the host computer is connected.

Destination Network Address

Set the network address of the destination node (i.e., the computer). Set "00" to send communications within the local network.

Destination Node Address

Set the node address of the destination node (i.e., the computer). Set "00" when transmitting within the local PLC.

Destination Unit Address

Set the unit address of the Unit to which the host computer is connected.

Response Setting

Normally this bit is set to 0 to require a response. When a response is not required, set this bit to 1.

Communications Port Number

Set the port number in the CPU Unit which will transmit CMND(490).

Number of Retries

Set the maximum number of times CMND(490) is to be resent if no response is returned.

Response Monitor Time

If the Response Setting is set to require a response, set the response monitor time.

Note If response data longer than that set in the Number of Bytes of Response Data is returned, all extra response data will not be stored. If response data shorter than that set in the Number of Bytes of Response Data is returned, the response data will be stored, and the remaining area will stay at its previous values.

Control Word Settings

The setting range for each item is shown on the following table.

Item	Setting
Number of bytes of command data	0002 to 021E (2 to 542 bytes)
Number of bytes of response data	0002 to 021E (2 to 542 bytes)
Serial port number	00: CPU Unit, Inner Board, CPU Bus Unit 01: Port 1 02: Port 2
Destination network address	00: Local network 01 to 7F:Network address (1 to 127)
Destination node address	00: Internal communications in PLC 01 to FE: Node address of Ethernet Unit with model number ending in ETN21 (1 to 254) 01 to 7E: Node address of Ethernet Unit with other model number (1 to 126) 01 to 3E: Node address (1 to 62) for Controller Link
Destination unit address	10 to 1F: Serial Communications Unit (unit address 0 to 15)
Response setting	0: Required 1: Not required
Communications port number	0 to 7 (0 to 7)
Number of retries	0 to F (0 to 15)
Response monitor time	0000: Default (2 s) 0001 to FFFF: 0.1 to 6,553.5 s (unit: 0.1 s)

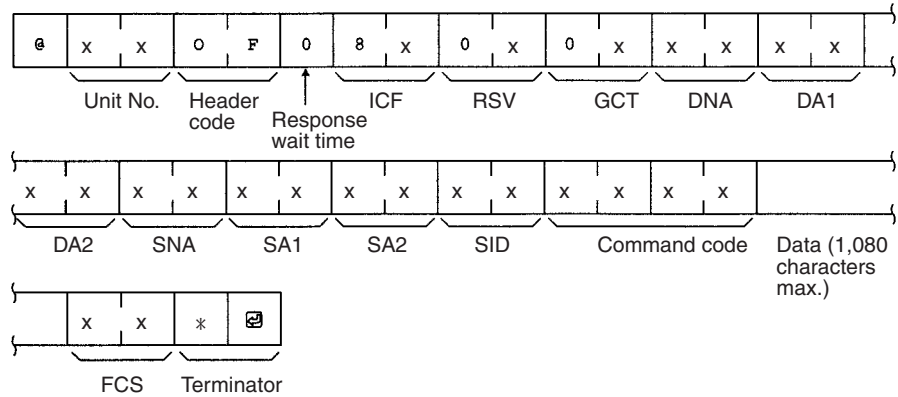**Note** To execute CMND(490) normally, programming needs to be written to process the command received by the host computer and return the proper response.

3-5-6 Command Format Received by the Host Computer

FINS commands sent to the host computer are received at the host computer in the format shown below.
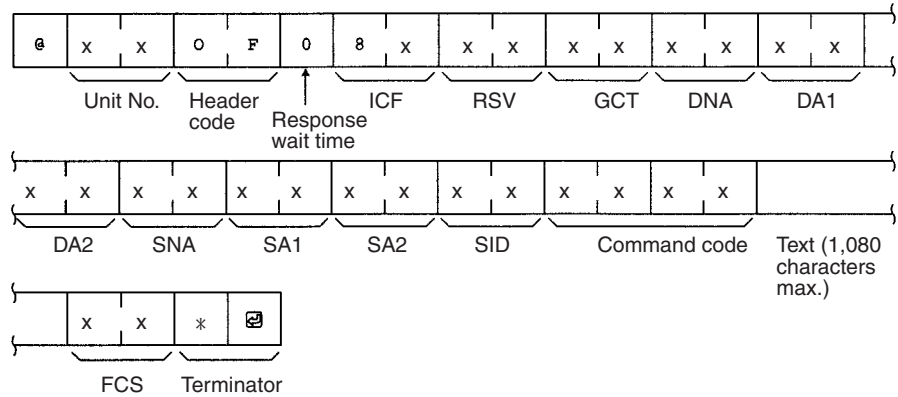
Unit Number
The unit number of the Host Link port connected to the host computer is set.

Header Code
The header code in FINS commands sent to the host computer is always set to "OF" (ASCII: 4F, 46).

Response Wait Time
The response wait time in FINS commands sent to the host computer is fixed at to "0" (ASCII: 4F, 46).

ICF (Information Control Field)
Specifies whether or not a response is required.

Response required: "80" (ASCII: 38,30)
Response not required: "81" (ASCII: 38,31)

RSV (Reserved)
Always set to "00" (ASCII: 30,30) in commands sent to the host computer.

GCT (Gateway Count)
The number of networks through which the command is relayed subtracted from 2 is set. (See note.)

Number of networks = 0: "02" (ASCII: 30, 32)
Number of networks = 1: "01" (ASCII: 30, 31)
Number of networks = 2: "00" (ASCII: 30, 30)
Number of networks = 7: "07" (ASCII: 30, 37)

Note The number of networks is subtracted from 7 for a CS/CJ-series CPU Unit with unit version 2.0 or later, CP-series CPU Unit, or NSJ Controller.

DNA, DA1, DA2
The addresses for the Host LInk Unit connected to the host computer are set.

DNA (Destination Network Address)
The network address (00 to 7F Hex) of the CPU Unit is set in hexadecimal.

DA1 (Destination Node Address)
The node address (01 to 7E Hex) of the CPU Unit is set in hexadecimal.

DA2 (Destination Unit Address)
The unit address of the Host Link port is set.

SNA, SA1, SA2
The addresses for the source node (e.g., PLC, FA computer) are set.

SNA (Source Network Address)
The network address (00 to 7F Hex) of the source is set in hexadecimal.

SA1 (Source Node Address)

The node address (01 to 7E Hex) of the source is set in hexadecimal.

SA2 (Source Unit Address)

The unit address of the source is set.

<u>**SID (Source ID)**</u>

Automatically set by the CPU Unit using SEND(090), RECV(098), and CMND(490).

3-5-7 Response Format Returned by the Host Computer

Responses to FINS commands received by the host computer are returned in the format shown below.
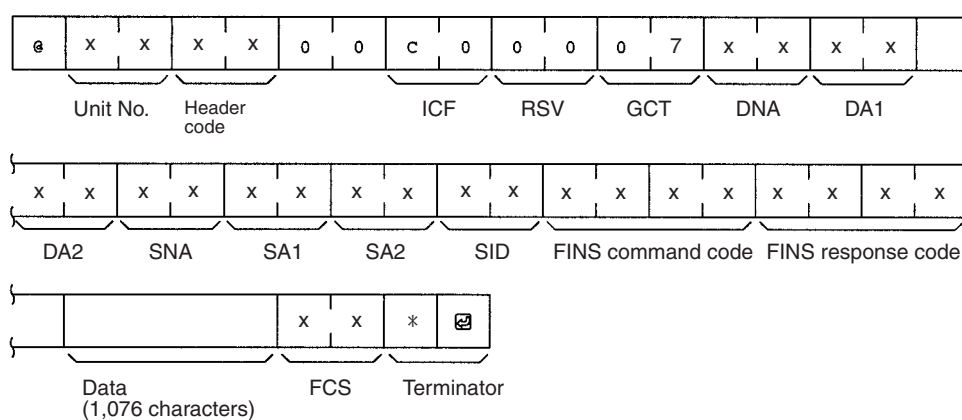
<u>ICF (Information Control Field)</u>
"C0" (ASCII: 43, 30) will be returned.

<u>RSV (Reserved)</u>
"00" (ASCII: 30, 30) is returned.

<u>GCT (Gateway Count)</u>
"07" (ASCII: 30, 37) is returned.

<u>DNA (Destination Network Address), DA1 (Destination Node Address), DA2 (Destination Unit Address)</u>
The same contents specified for SNA, SA1, and SA2 in the command that was received will be returned.

<u>SNA (Source Network Address), SA1 (Source Node Address), SA2 (Source Unit Address)</u>
The same contents specified for DNA, DA1, and DA2 in the command that was received will be returned.

<u>SID (Source ID)</u>
The SID that was specified in the command that was received will be returned.

<u>Command Code</u>
The command code that was specified in the command that was received will be returned.

Note The length of the response cannot exceed 1,115 characters. Create responses so that the response data without the response code is less than 1,076 characters (538 bytes).

3-5-8　Flags for Network Communications

This section describes the flags in the Auxiliary Area that are used when executing SEND(090), RECV(098), and CMND(490).

Communications Port Enabled Flags

A Communications Port Enabled Flag turns ON when SEND(090), RECV(098), and CMND(490) can be executed. The Flag will turn OFF during execution of these commands and turn ON again when the command execution is completed. When creating the ladder diagram, use these Flags as input conditions when executing these instructions.

Word	Bit	Content
A202	08 to 15	Reserved
	07	Communications Port Enabled Flag, Port No. 7
	06	Communications Port Enabled Flag, Port No. 6
	05	Communications Port Enabled Flag, Port No. 5
	04	Communications Port Enabled Flag, Port No. 4
	03	Communications Port Enabled Flag, Port No. 3
	02	Communications Port Enabled Flag, Port No. 2
	01	Communications Port Enabled Flag, Port No. 1
	00	Communications Port Enabled Flag, Port No. 0

Communications Port Error Flags

A Communications Port Error Flag will turn ON in the following cases.

- When an error is generated during execution of SEND(090), RECV(098), or CMND(490).
- When an error response or retry error has been generated for the port.

These Flags will turn OFF when the corresponding Communications Port Enabled Flag is turned OFF at the start of operation or at the start of executing the SEND(090), RECV(098), or CMND(490).

Word	Bit	Content
A219	15 to 08	Reserved
	07	Communications Port Error Flag, Port No. 7
	06	Communications Port Error Flag, Port No. 6
	05	Communications Port Error Flag, Port No. 5
	04	Communications Port Error Flag, Port No. 4
	03	Communications Port Error Flag, Port No. 3
	02	Communications Port Error Flag, Port No. 2
	01	Communications Port Error Flag, Port No. 1
	00	Communications Port Error Flag, Port No. 0

| Communications Port Completion Codes | The Communication Port Completion Code words will contain the FINS end code after SEND(090), RECV(098), or CMND(490) has been executed. |

If the Communications Port Enabled Flag turns OFF when operation is started or SEND(090), RECV(098), or CMND(490) are executed, the contents of these words will be cleared.

Word	Content
A203	Communications Port Completion Code, Port No. 0
A204	Communications Port Completion Code, Port No. 1
A205	Communications Port Completion Code, Port No. 2
A206	Communications Port Completion Code, Port No. 3
A207	Communications Port Completion Code, Port No. 4
A208	Communications Port Completion Code, Port No. 5
A209	Communications Port Completion Code, Port No. 6
A210	Communications Port Completion Code, Port No. 7
A211 to A218	Reserved

Flag Transitions
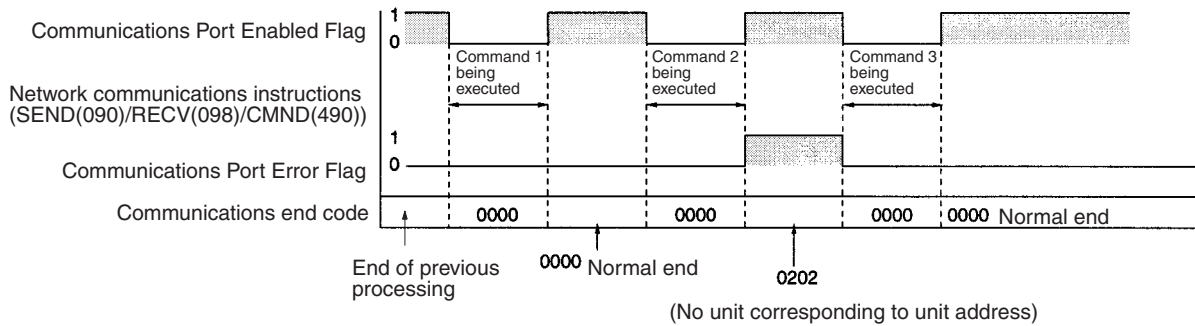
3-5-9 Timing of Commands to Host Computers

Commands sent to a host computer are transmitted with the timing shown below.

Data Received from Host Computer
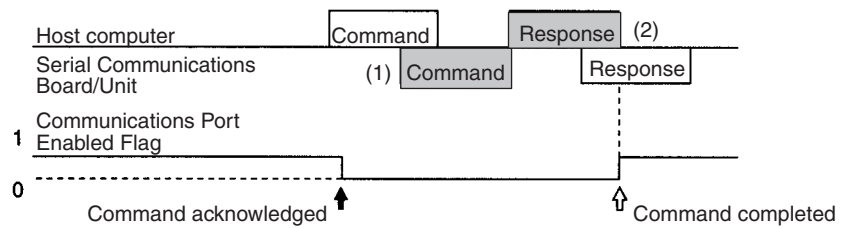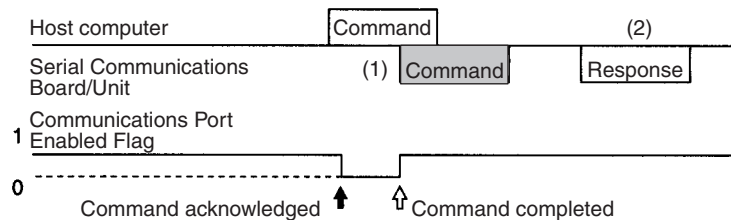
Command transmission to the host computer can commence even when the port is receiving a command from the host computer (1). The transmission of a response to the command from the host computer is postponed until the transmission of the command to the host computer is completed (2).

When a response is not required from the host computer, the Communications Port Enabled Flag will turn ON when the command to the host computer has passed from the CPU Unit to the port.

Host Computer Receiving Data

Response Required

```
Host computer                         ┌─────────┐              ┌────────────┐
                                      │ Command │ (1)     (2)  │  Response   │
Serial Communications Board/Unit      └─────────┘┌─────────┐┌──────────┐└────
                                                 │Response │ │ Command  │
                                                 └─────────┘ └──────────┘
1  Communications Port Enabled Flag
0
          Command acknowledged ▲                          ⇧
                                                            Command completed
```

No Response Required
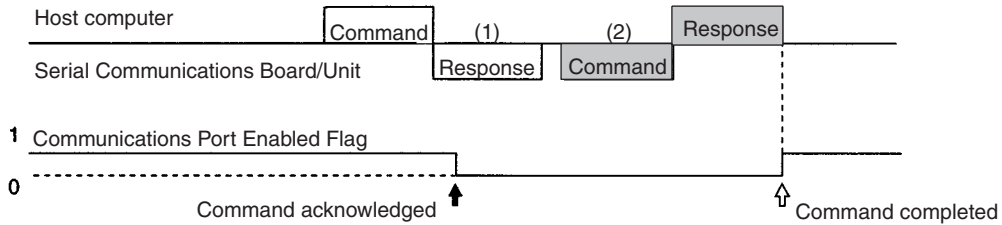
```
Host computer                         ┌─────────┐  (1)        (2)
                                      │ Command │
Serial Communications Board/Unit      └─────────┘┌─────────┐┌──────────┐
                                                 │Response │ │ Command  │
                                                 └─────────┘ └──────────┘
1  Communications Port Enabled Flag
0
          Command acknowledged ▲  ⇧ Command completed
```
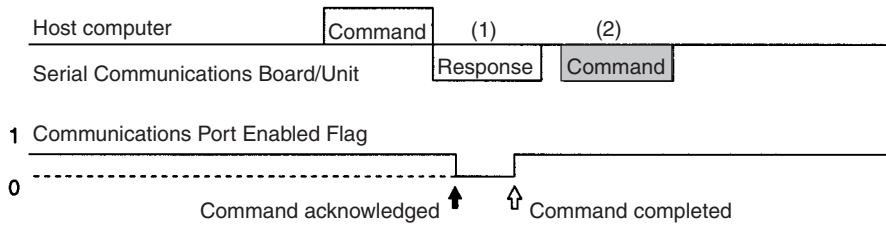
At (1) in the diagram, the response to a command sent from the host computer is being transmitted from the port. In this case, the command transmission to the host computer is postponed until the response transmission is completed (2).

When a response is not required from the host computer, the Communications Port Enabled Flag will turn ON when the command to the host computer has passed from the CPU Unit to the port.

Response Wait Time

Response Required

Host computer | Command | Response

Serial Communications Board/Unit | (1) | Command | Response

Response wait time (2)

1 Communications Port Enabled Flag

0

Command acknowledged ↑   ⇧ Command completed

No Response Required

Host computer | Command

Serial Communications Board/Unit | (1) | Command | Response

Response wait time (2)

1 Communications Port Enabled Flag

0
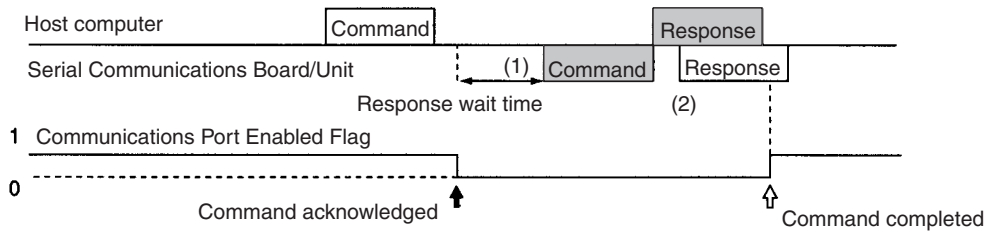
Command acknowledged ↑ ⇧ Command completed
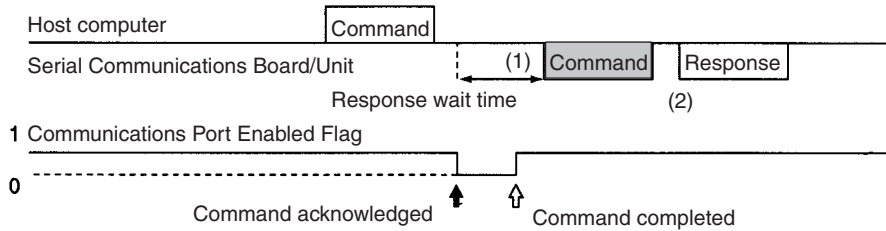
When response wait time has been set in the command format from the host computer, commands to the host computer will not be transmitted until the response time has elapsed (1). Transmission of responses to commands from the host computer will be postponed until the command transmission to the host computer has been completed.

When a response is not required from the host computer, the Communications Port Enabled Flag will turn ON when the command to the host computer has passed from the CPU Unit to the port.

3-5-10 Programming Example
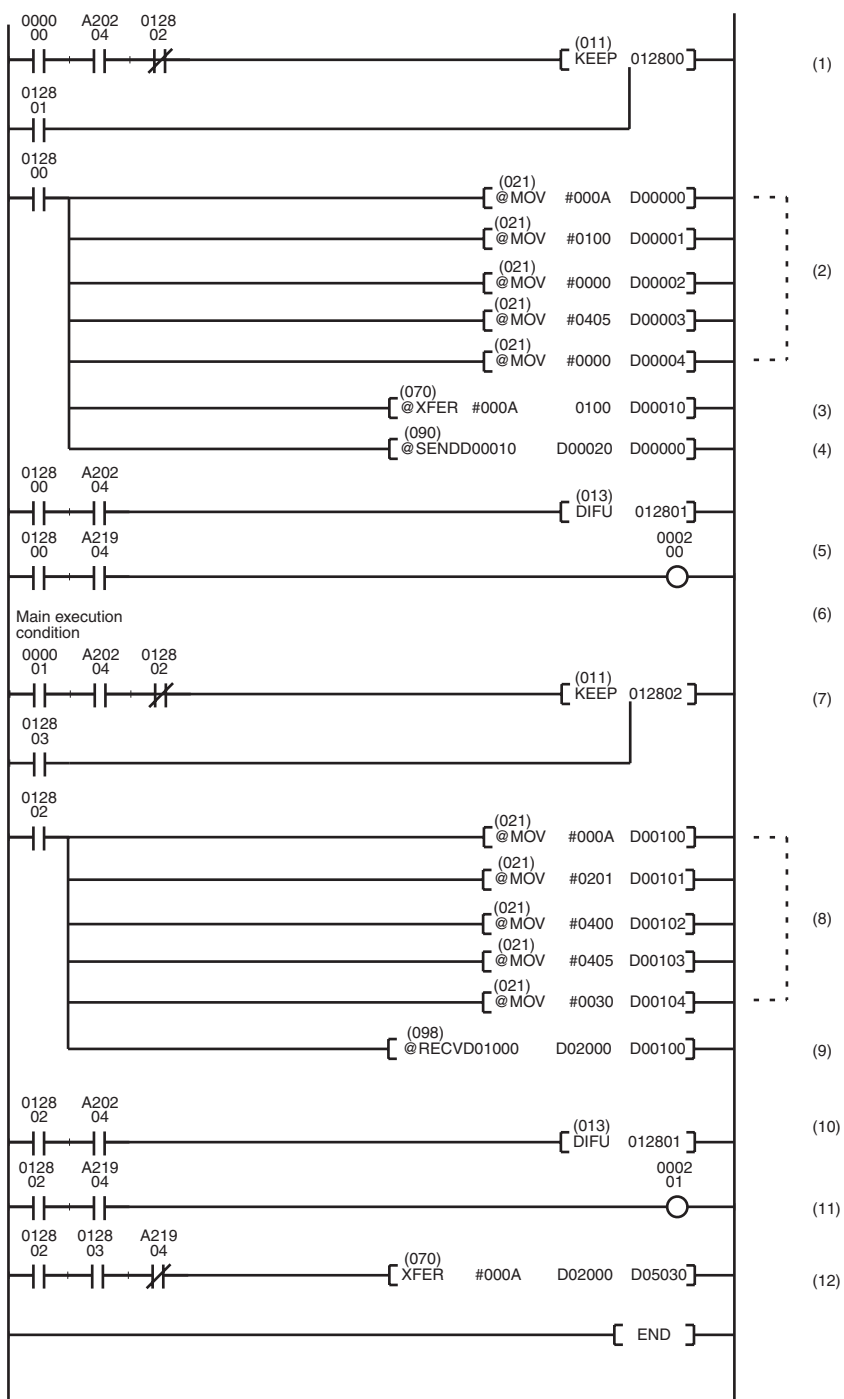
1,2,3... 1. When the SEND(090)/RECV(098) Enabled Flag is ON, and the execution condition CIO 000000 is ON, execution of the instructions for network transmissions are started. CIO 012800 will remain ON from when SEND(090) is started until execution has been completed.

2. Set the control data.

D00000	00	0A	← Number of send words: 10
D00001	01	00	← Serial port 1 (peripheral port) Destination network address $00 (B network)
D00002	00	00	← Destination node address $00 (B node) Destination unit address $00 (CPU Unit)
D00003	04	05	← Response required, Communications port No. 4 Number of retries: 5
D00004	00	00	← Response monitor time: 2 s ($0000: Default)

3. Transmit Data Stored

   Stores 10 words of data starting from CIO 0100 to D00010 and later.

4. Execute SEND(090).

5. When the instruction for network communications has been completed (A20204: ON), CIO 012801 will turn ON, and the instruction for sending on the network is completed.

6. Turns ON when an error is generated during execution of network communications.

7. When the Communications Port Enabled Flag is ON and execution condition CIO 000001 is ON, execution of the instruction for receiving via the network (RECV(098)) is started.

8. Set the control data.

D00100	00	0A	← Number of receive words: 10
D00101	02	01	← Serial port 2 Source network address $01 Source node address $04
D00102	04	00	← Source unit address $01 (Inner Board) Response required, Communications port No. 4
D00103	04	05	← Number of retries: 5
D00104	00	30	← Response monitor time: 4.8 s ($0030)

9. Execute RECV(098).

10. When the execution of network communications instructions has been completed (A20204: ON), CIO 012803 will turn ON, and the instruction for receiving via the network is completed.

11. Turns ON when an error is generated during execution of network communications.

12. Reception data processing

    When there is no reception error, 10 words of data (starting from D02000) are stored from D05030 onwards.

Programming Example for Host Computer Side (BASIC): Send

```
10   '****************************************
20   '**** CS1W-SCU21 Serial Communications Unit ****
30   '**** Command to Host Computer (SEND(090)) ****
40   '**** Sample Send Program ****
50   '****************************************
60   '
70   '=========== Initial Settings ===========
80   CLOSE 1
90   ON ERROR GOTO *EROPE
100  DIM CHDATA$ (300)                               :' Data array declaration
110  OPEN "COM:E73" AS #1                            :' Opens port.
120  '
130  '=========== Main Process ===========
140  INPUT #1, COMMAND$                              :' Receives data from PLC (line).
150  T$=LEFT$ (COMMAND$, LEN (COMMAND$) -3)          :' Checks FCS.
160  GOSUB *FCS
170  IF FCS$<>MID$ (COMMAND$, LEN (COMMAND$) -2, 2) THEN ENDCODE$="1004":GOTO *RESPONSE
180  CMNDCODE$=MID$ (COMMAND$, 27, 4)                :' Checks command code.
190  IF CMNDCODE$<>"0102" THEN ENDCODE$="0401" :GOTO *RESPONSE
200  FOR I=0 TO VAL ("&H"+MID$ (COMMAND$, 39, 4) ) -1 :' Sets No. of write elements.
210     CHDATA$ (I) =MID$(COMMAND$, 43+I*4, 4)
220      PRINT "Data";":";CHDATA$(I)
230  NEXT I
240  ENDCODE$="0000"                                 :' Sets end code to "0000".
250  '========================================
260  *RESPONSE                                       :' Creates a response frame.
270  RSV$=MID$ (COMMAND$, 9, 2)                       :' Returns received RSV, SID
280  DA$=MID$ (COMMAND$, 19, 6)                       :' without change.
290  SA$=MID$ (COMMAND$, 13, 6)                       :' Swaps DNA, DA1, DA2
300  SID$=MID$ (COMMAND$, 25, 2)                      :' with SNA, SA1, and SA2.
310  T$="@000F00C0"+RSV$+"02"+DA$+SA$+SID$+CMNDCODE$+ENDCODE$
320  GOSUB *FCS
330  RESPONSE$=T$+FCS$+"*"
340  PRINT #1, RESPONSE$                             :' Transmits data to PLC (line).
350  GOTO 140
360  '
370  '===== FCS Calculation Subroutine =====
380  *FCS                                            :' Adds FCS.
390  L=LEN (T$)
400  A=0
410  FOR J=1 TO L
420      TJ$=MID$ (T$, J, I)
430      A+ASC (TJ$)    XOR  A
440  NEXT J
450  FCS$=HEX$ (A)
460  IF LEN (FCS$) =1 THEN FCS$="0"+FCS$
470  RETURN
480  '
490  '========== Error processing ==========
500  *EROPE
510  PRINT "ERL=":ERL, "ERR";ERR
520  CLOSE 1
530  END
```

Programming Example for Host Computer Side (BASIC): Reception

```
10   '**************************************
20   '**** CS1W-SCU21 Serial Communications Unit  ****
30   '**** Command to Host Computer (RECV(098))  ****
40   '**** Sample Reception Program  ****
50   '**************************************
60   '
70   '=========== Initial Settings ===========
80   CLOSE 1
90   ON ERROR GOTO *EROPE
100  DIM CHDATA$ (300)                                        :' Data array declaration
110  CHDATA$ (0) ="0000":CHDATA$ (1) ="1111":CHDATA$ (2) ="2222"
120  CHDATA$ (3) ="3333":CHDATA$ (4) ="4444":CHDATA$ (5) ="5555"
130  OPEN "COM:E73" AS #1                                     :' Opens port.
140  '
150  '=========== Main Process ===========
160  RESPDATA$=""
170  INPUT #1, COMMAND$                                       :' Receives data from PLC (line).
180  T$=LEFT$ (COMMAND$, LEN (COMMAND$) -3)                   :' Checks FCS.
190  GOSUB *FCS
200  IF FCS$<>MID$ (COMMAND$, LEN (COMMAND$) -2, 2) THEN ENDCODE$="1004":GOTO *RESPONSE
210  CMNDCODE$=MID$ (COMMAND$, 27, 4)                         :' Checks command code.
220  IF CMNDCODE$<>"0101" THEN ENDCODE$="0401" :GOTO *RESPONSE
230  FOR I=0 TO VAL ("&H"+MID$ (COMMAND$, 39, 4) ) -1 :' Sets No. of read elements.
240      RESPDATA$=RESPDATA$+CHDATA$ (I)
250  NEXT I
260  PRINT "Send data";RESPDATA$
270  ENDCODE$="0000"                                          :' Sets end code to "0000".
280  '=======================================
290  *RESPONSE                                                :' Creates a response frame.
300  RSV$=MID$ (COMMAND$, 9, 2)                               :' Returns received RSV, SID
310  DA$=MID$ (COMMAND$, 19, 6)                               :' without change.
320  SA$=MID$ (COMMAND$, 13, 6)                               :' Swaps DNA, DA1, DA2
330  SID$=MID$ (COMMAND$, 25, 2)                              :' with SNA, SA1, and SA2.
340  T$="@000F00C0"+RSV$+"02"+DA$+SA$+SID$+CMNDCODE$+ENDCODE$+RESPDATA$
350  GOSUB *FCS
360  RESPONSE$=T$+FCS$+"*"
370  PRINT #1, RESPONSE$                                      :' Transmits data to PLC (line).
380  GOTO 160
390  '
400  '===== FCS Calculation Subroutine =====
410  *FCS                                                     :' Adds FCS.
420  L=LEN (T$)
430  A=0
440  FOR J=1 TO L
450      TJ$=MID$ (T$, J, I)
460      A+ASC (TJ$)   XOR   A
470  NEXT J
480  FCS$=HEX$ (A)
490  IF LEN (FCS$) =1 THEN FCS$="0"+FCS$
500  RETURN
510  '
520  '========== Error processing ==========
530  *EROPE
540  PRINT "ERL=":ERL, "ERR";ERR
550  CLOSE 1
560  END
```

3-6 Serial Gateway Overview

3-6-1 Overview

FINS messages (commands) that are received are automatically converted into the corresponding protocol and then sent via serial communications. The responses are also automatically converted. FINS messages can be converted into the following protocols.

- CompoWay/F
- Modbus-RTU
- Modbus-ASCII
- Host Link FINS (FINS commands enclosed in Host Link header and terminator)

   Note Serial Communications Boards/Units can receive FINS commands via a FINS network (including Host Link FINS) or via the CPU bus.

Applicable Units and Serial Communications Ports

Command after conversion	Applicable Units and serial communications ports
CompoWay/F	CS/CJ-series CPU Unit with unit version 3.0 or later, serial port C on the Controller Section of an NSJ Controller, or serial port 1 or 2 on Option Board of CP-series CPU Unit
	Serial communications port on Serial Communications Board/Unit with unit version 1.2 or later
Modbus-RTU	Serial communications port on Serial Communications Board/Unit with unit version 1.2 or later or serial port 1 or 2 on Option Board of CP-series CPU Unit
Modbus-ASCII	Serial communications port on Serial Communications Board/Unit with unit version 1.2 or later
Host Link FINS	

Using the CPU Unit
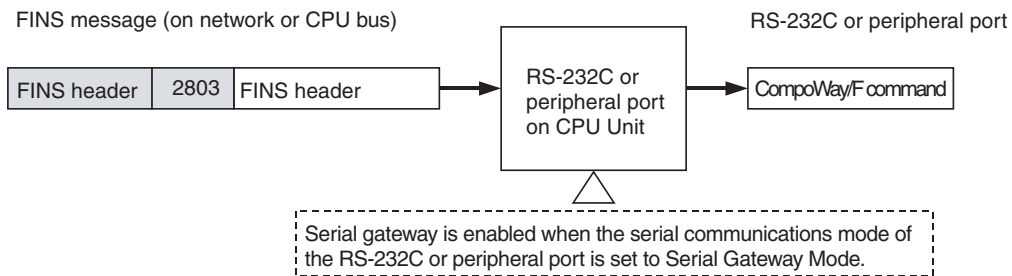
Using a Serial Communications Board/Unit
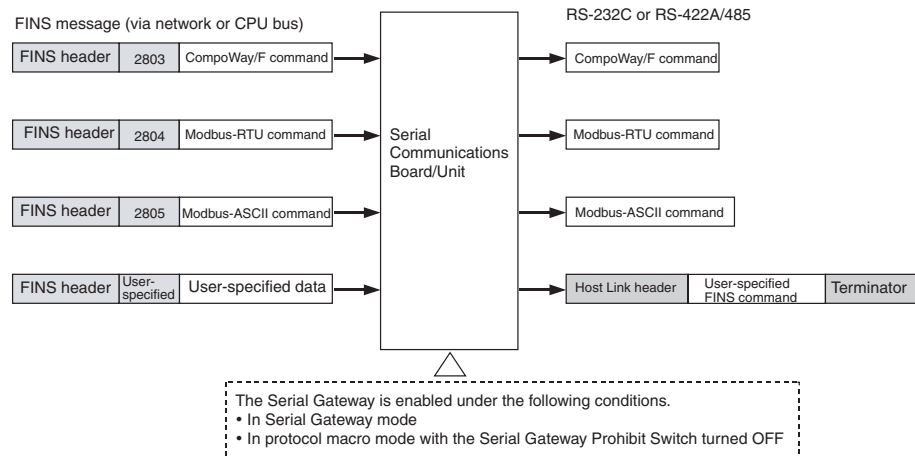
3-6-2 Types of Protocol Conversion

Type of conversion (from FINS)	Frame before conversion			Processing at Board/Unit	Protocol after conversion (using serial communications)	Target (communications partner)
	Destination address	FINS command	FINS data			
Converting to CompoWay/F	Serial port number on Board/Unit	2803 hex	CompoWay/F command	CompoWay/F command with FINS header removed sent to serial port.	CompoWay/F command	OMRON Component (e.g., Temperature Controller, Digital Panel Meter, or Smart Sensor)
Converting to Modbus-RTU		2804 hex	Modbus-RTU command	Modbus-RTU command with FINS header removed sent to serial port.	Modbus-RTU command	Modbus-RTU Slave-compatible device (including OMRON 3G3JV, 3G3MV, and 3G3RV Inverters)
Converting to Modbus-ASCII		2805 hex	Modbus-ASCII command	Modbus-ASCII command with FINS header removed sent to serial port.	Modbus-ASCII command	Modbus-ASCII Slave-compatible device (e.g., temperature controller, indicator, or power monitor)
Converting to Host Link FINS	Any address except Board/Unit's serial port number.	User-specified	User-specified	Transfers FINS command inside Host Link header and terminator.	FINS command for Host Link communications	OMRON PC (CS/CJ/CP/NSJ Series, or CVM1/CV Series)

3-6-3 Converting FINS to CompoWay/F

OMRON Components connected serially to a PC via CompoWay/F can be accessed from the CPU Unit or PT using CompoWay/F commands enclosed in FINS messages.

- Sent FINS message: FINS header + FINS command code 2803 hex + CompoWay/F command
- Message after conversion: CompoWay/F command
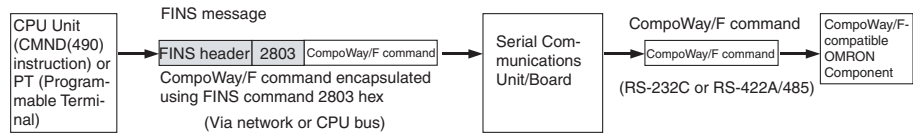
CompoWay/F Slave-compatible Components

Component		Model series
Temperature Controllers	Thermac NEO	E5GN (G components)
		E5CN
		E5EN
		E5AN
	Thermac R	E5AR
		E5ER
	Plug-in Temperature Controllers	E5ZN
	Digital Controller Boards	E5ZM
	Digital Controllers	ES100X
Timer/Counters	Timers/Counters	H8GN (G components)
Digital Panel Meters	Digital Panel Meters	K3GN (G components) K3NX
	Digital Load Cell Meters	K3NV
	Digital Rotary/Pulse Meters	K3NR
	Digital Incrementing Panel Meters	K3NP
	Digital Time Interval Meters	K3NC
	Digital Temperature/Process Meters	K3NH
Smart Sensors	ZX Communications Interface Units	ZX-SF11
Cam Positioners	---	3F88L-160, 3F88L-162
Safety Controllers	---	F3SX

System Configuration Patterns

Sending FINS Messages Using CMND(490) in CPU Unit's Ladder Program

The Board/Unit converts the FINS messages to CompoWay/F protocol for sending in this operation.

Access from CPU Unit (on the Same PC)

CPU Bus-to-Serial	Details	Routing tables to treat serial communications path as network
	OMRON components connected serially to the Serial Communications Board/Unit using CompoWay/F can be accessed from a CPU Unit in the same PC.	Optional

Access from CPU Unit (PC on the Network)

FINS message-to-Serial	Details	Routing tables to treat serial communications path as network
	OMRON components connected serially to the Serial Communications Board/Unit using CompoWay/F can be accessed from a CPU Unit in a PC connected to the network.	Optional

Executing Smart Active Parts Using an NS-series PT (Sending Internal FINS Messages)

The Board/Unit converts the FINS messages to CompoWay/F protocol for sending in this operation.

Access from PT on Ethernet or serial NT Link	Details	Routing tables to treat serial communications path as network
  Note When the NS-series PT is connected serially to the PC using serial communications mode (1:N NT Links), and the NS-series PT sends FINS commands encapsulated in NT Link commands using Smart Active Parts, the CPU Unit removes the NT Link header, etc. from the received command, converting it to a FINS command, and transfers the command to the Serial Communications Board/Unit. The Serial Communications Board/Unit uses the Serial Gateway to convert the command into the specified protocol. This operation enables serially connected devices to access the Serial Communications Board/Unit from Smart Active Parts using an NS-series PT.	Access via serial communications using CompoWay/F is possible from a PT connected to the network by executing a Smart Active Part that is connected serially, which automatically sends an internal FINS command.	Optional

Note (1) The FINS header contains the following information.

• Remote destination network address (DNA)

- With routing tables that treat serial communications path as a network: Network address corresponding to serial port in the routing tables.

- Without routing tables that treat serial communications path as a network: Network address for specifying actual remote PC.

- Remote destination node address (DA1)

  - With routing tables that treat serial communications path as a network: 00 hex (local PC's internal communications) (For serial-to-serial-to-serial conversion, increment the Host Link unit number by 1.)

  - Without routing tables that treat serial communications path as a network: Node address for specifying actual remote PC (For serial-to-serial-to-serial conversion, increment the Host Link unit number by 1.)

- Remote destination unit address (DA2)
  Unit address of serial port

(2) The contents of the CompoWay/F command enclosed in the FINS message that is sent is as follows:
Node number + subaddress + SID + command text (ASCII must be used.)
STX, ETX+BCC are not required when sending FINS. They are added automatically for serial communications.

3-6-4 Converting FINS to Modbus-RTU

Modbus-RTU Slave-compatible devices (including OMRON Inverters) connected serially to a PC via Modbus-RTU can be accessed from the PC or PT using Modbus-RTU commands enclosed in FINS messages.

- Sent FINS message: FINS header + FINS command code 2804 hex + Modbus-RTU command

- Message after conversion: Modbus-RTU command
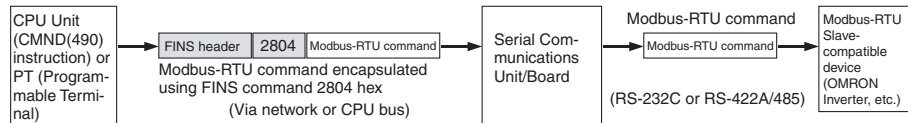
Modbus-RTU Slave-compatible OMRON Devices

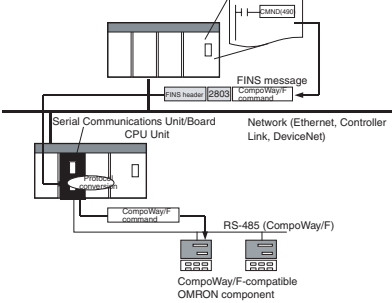| Type	Model series
Inverters	3G3JV
	3G3MV
	3G3RV
Temperature Controllers	E5CN (New version)

System Configuration Patterns

Sending FINS Messages Using CMND(490) in CPU Unit's Ladder Program

The Board/Unit converts the FINS messages to Modbus-RTU protocol for sending in this operation.
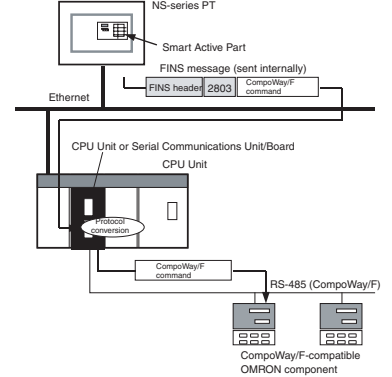
Access from CPU Unit (on the Same PC)

CPU Bus-to-Serial	Details	Routing tables to treat serial communications path as network
	OMRON Inverters connected serially to the Serial Communications Board/Unit using Modbus-RTU can be accessed from a CPU Unit in the same PC.	Optional

Access from CPU Unit (on Network PC)

FINS message-to-Serial	Details	Routing tables to treat serial communications path as network
	OMRON Inverters connected serially to the Serial Communications Board/Unit using Modbus-RTU can be accessed from a CPU Unit in a PC connected to the network.	Optional

Executing Smart Active Parts Using an NS-series PT (Sending Internal FINS Messages)

The Board/Unit converts the FINS messages to Modbus-RTU protocol for sending in this operation.

| Access from PT on Ethernet or serial NT Link	Details	Routing tables to treat serial communications path as network
  Note When the NS-series PT is connected serially to the PC using serial communications mode (1:N NT Links), and the NS-series PT sends FINS commands encapsulated in NT Link commands using Smart Active Parts, the CPU Unit removes the NT Link header, etc. from the received command, converting it to a FINS command, and transfers the command to the Serial Communications Board/Unit. The Serial Communications Board/Unit uses the Serial Gateway to convert the command into the specified protocol. This operation enables serially connected devices to access the Serial Communications Board/Unit from Smart Active Parts using an NS-series PT.	Access via serial communications using Modbus-RTU is possible from a PT connected to the network by executing a Smart Active Part that is connected serially, which automatically sends an internal FINS command.	Optional

Note (1) The FINS header contains the following information.

- Remote destination network address (DNA): Same as for CompoWay/F.

- Remote destination node address (DA1): Same as for CompoWay/F.

- Remote unit address (DA2): Same as for CompoWay/F.

(2) The contents of the Modbus-RTU command enclosed in the FINS message that is sent is as follows:
Slave address (binary) + FUNCTION code (binary) + Communications data (binary)
Start and CRC+End are not required when sending FINS. They are added automatically for serial communications.

3-6-5 Converting from FINS to Modbus-ASCII

Modbus-ASCII Slave-compatible devices connected serially to a PLC via Modbus-ASCII can be accessed from the PLC using Modbus-ASCII commands enclosed in FINS messages.

- Sent FINS message: FINS header + FINS command code 2805 hex + Modbus-ASCII command
- Message after conversion: Modbus-ASCII command
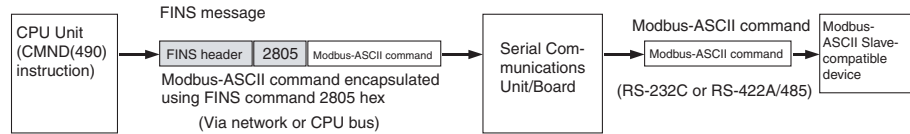
System Configuration Patterns

Sending FINS Messages Using CMND(490) in CPU Unit's Ladder Program

The Board/Unit converts the FINS messages to Modbus-ASCII protocol for sending in this operation.

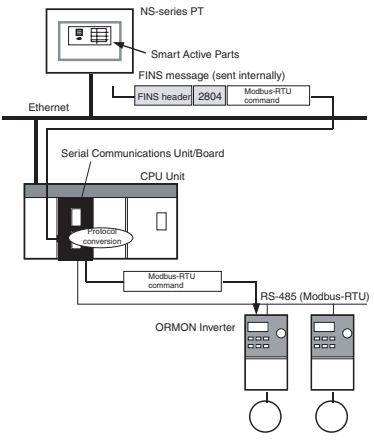#### Access from CPU Unit (on the Same PLC)

CPU Bus-to-Serial	Details	Routing tables to treat serial communications path as network
	Slaves connected serially to the Serial Communications Board/Unit using Modbus-ASCII can be accessed from a CPU Unit in the same PLC.	Optional

Access from CPU Unit (on Network PLC)

FINS message-to-Serial	Details	Routing tables to treat serial communications path as network
	Slaves connected serially to the Serial Communications Board/Unit using Modbus-ASCII can be accessed from a CPU Unit in a PLC on the network.	Optional

Note (1) The FINS header contains the following information.

- Remote destination network address (DNA): Same as for CompoWay/F.
- Remote destination node address (DA1): Same as for CompoWay/F.
- Remote unit address (DA2): Same as for CompoWay/F.

(2) The contents of the Modbus-ASCII command enclosed in the FINS message that is sent is as follows:
Slave address (ASCII) + FUNCTION code (ASCII) + Communications data (ASCII)

The header ":" (3A hex) and LRC+CR/LF are not required when sending FINS. They are added automatically for serial communications.

3-6-6 Converting from FINS to Host Link FINS

A PC slave that is connected serially to the PC master via Host Link can be accessed from the PC master or personal computer (see note) using FINS messages. Accessing a device on another network via Host Link (serial communications) is also possible by using FINS messages. By converting the FINS to Host Link FINS, the PC can function as a Host Link master.

Note Applications such as CX-Programmer or CX-Protocol that use CX-Server as a communications driver.

- Sent FINS message: FINS header + User-specified FINS command (see note 1)
- Message after conversion: FINS command enclosed in Host Link header and terminator (see note 2)
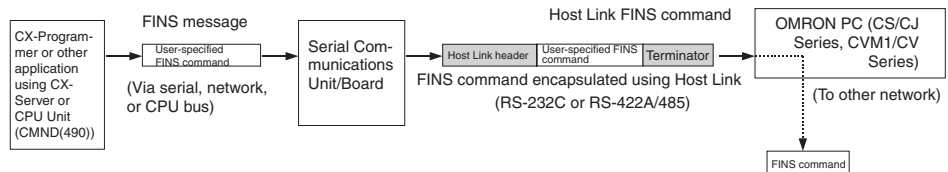
System Configuration Patterns

Access from CX-Programmer (Sending Internal FINS Messages)

The Board/Unit converts the FINS messages to Host Link FINS for sending in this operation.

Access from Serially Connected CX-Programmer

Serial-to-Serial	Details	Routing tables to treat serial communications path as network
	Personal computers (e.g., CX-Programmer) connected serially (via tool bus or Host Link) to the PC master can access a PC slave that is connected serially to the PC master via Host Link.	Optional

Use the following method to access the serially (serial-to-serial) connected PC from the CX-Programmer.

System Configuration Example
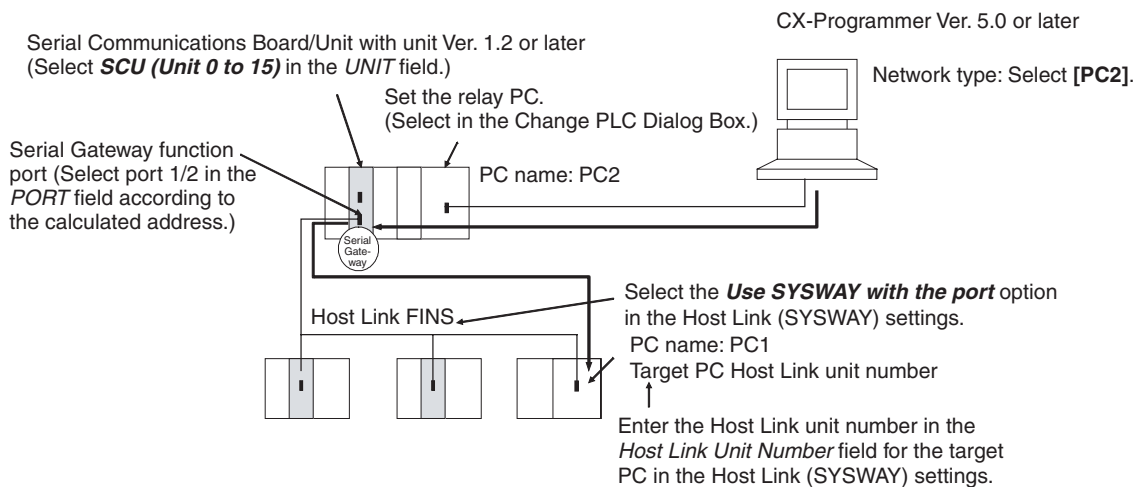
1,2,3...
1. Register the PC to be connected serially (using Host Link FINS) in the project gateway (e.g., PC2).

2. In the Change PLC Dialog Box of the target PC (e.g., PC1), select the relay PC (gateway PC) in the Network Type pull-down menu (e.g., [PC2] (See note.)) and click the **Settings** Button to the right of the Network Type pull-down menu.

   Note The PC name enclosed in square brackets (e.g., [PC2]) indicates the gateway PC.
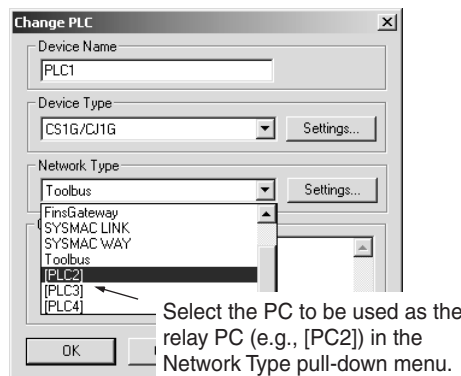
3. The Network Settings Dialog Box will be displayed. Click the **Guide for Serial Gateway** Button.

4. The **Serial Gateway Guide** Dialog Box will be displayed.
   Select the unit and the port number under the *Calculate Address Area*, the serial port number address is automatically calculated in the *Calculated Address Field*.
   Select the *Use SYSWAY with the port* option, and enter the actual Host Link unit number for the target (communications partner) PC in the *Host Link Unit Number field* (see note).
   Finally, click the **Apply** Button.

Serial Gateway Guide

Select the Unit. → Calculate Address

UNIT [CPU ▼]   Calculated Address [252] → The Serial Communications port address is automatically calculated.

Select the port. → PORT [CPU: Peripheral ▼]

Hostlink(SYSWAY) Setting

Select this option. → ☑ Use SYSWAY with the port   If using Hostlink(SYSWAY), calculated address will be reflected into Network number

Hostlink Unit Number [0 ▲▼] → Enter the unit number for the actual Host Link (values are incremented by 1 automatically).

[Cancel]   [HELP]

Note When using the CX-Programmer, enter the actual Host Link unit number. Do not add 1 to the value. The CX-Programmer will automatically add 1 internally.

<u>**Access from CX-Programmer Connected to Network**</u>

Network-to-Serial	Details	Routing tables to treat serial communications path as network
	Personal computers (e.g., CX-Programmer) connected through the network to the PC master can access a PC slave that is connected serially to the PC master via Host Link.	Required

Note This configuration can be connected to other networks, as shown below.

Network-to-Serial-to-Network	Details	Routing tables to treat serial communications path as network
	Personal computers (e.g., CX-Programmer) connected through the network to the PC master can access a PC on another network via a PC slave that is connected serially to the PC master via Host Link.	Required

Sending FINS Messages or Sending/Receiving Data Using CMND(490), RECV(098), SEND(090) in the CPU Unit's Ladder Program

The Board/Unit converts the FINS messages to Host Link FINS in this operation.

Access from CPU Unit (on the Same PC)

CPU bus-to-Serial	Details	Routing tables to treat serial communications path as network
	Slave PCs connected serially to the Serial Communications Board/Unit using Host Link can be accessed from the CPU Unit in the same PC.	Optional

Access from CPU Unit (on Network PC)

Network-to-Serial	Details	Routing tables to treat serial communications path as network
	Slave PCs connected serially to the Serial Communications Board/Unit using Host Link can be accessed from a CPU Unit in a PC connected to the network.	Required

Note This configuration can be connected to other networks, as shown below

Network-to-Serial-to-Network	Details	Routing tables to treat serial communications path as network
	CPU Units in PCs connected to the network can access a PC on another network via a PC slave that is connected serially to the Serial Communications Board/Unit via Host Link.	Required

Note (1) The FINS header contains the following information.

- Remote destination network address (DNA)
    - With routing tables that treat serial communications path as a network: Network address corresponding to serial port in the routing tables.
    - Without routing tables that treat serial communications path as a network: Unit address of serial port.
- Remote destination node address (DA1)
    - With routing tables that treat serial communications path as a network: Unit number for Host Link incremented by 1 (1 to 32)
    - Without routing tables that treat serial communications path as a network: Unit number for Host Link incremented by 1 (1 to 32)
- Remote destination unit address (DA2)
  Any unit address except that for the serial port (The destination for the FINS message must not be the serial port of the Board/Unit.)
- FINS command code: Any

(2) When creating Host Link FINS command frames using the CMND(490) instruction, always set the unit number for Host Link incremented by one (1 to 32) for the remote destination (send destination) node address (word C+3, bits 08 to 15 of the CMND(490) instruction). Do not set the unit number of the actual Host Link slave (0 to 31). Using the Host Link unit number without incrementing by one will access the PC with the entered Host Link unit number less one.

For example, specify the remote PC with Host Link unit number 2 by entering *3* for the remote destination node address. If 2 is entered, the PC with Host Link unit number 1 will be accessed.

To access a PC on a Host Link FINS network using the Serial Gateway from CX-Programmer, however, enter the actual Host Link unit number, without incrementing by one. (Select ***Change PLC***, click the **Display Serial Gateway Guide** Button, and set unit number in the ***Host Link SYSWAY Settings*** field of the Serial Gateway Guide Dialog Box.

(3) The contents of the FINS command enclosed by the Host Link header and terminator is as follows:
  @ + Host Link unit number + Host Link header FA + FINS header + FINS command + Text + FCS + * + CR

3-6-7 Treating Serial Communications Paths as Networks

When the Serial Gateway is executed, routing tables are either required or optional as follows:

- Routing tables are required to treat a serial communications path as a network when converting FINS messages to Host Link FINS for serial conversion via the network.
- Under other conditions, routing tables are optional.

The details are provided in the following tables.

Conditions Requiring Routing Tables According to Target

Target		Protocol conversion	Case	Example	Routing tables for treating serial communications path as network
PLC (CS/CJ/CP/NSJ Series, CVM1/ CV Series)		Host Link FINS	Routing FINS network including serial communications path (for Serial Gateway)	Network-to-serial conversion	Required
			Serial communications path connection only	Serial-to-serial conversion	Optional
Any component except PLC	OMRON Component	CompoWay/ F	Routing FINS network including serial communications path (for Serial Gateway)	Network-to-serial conversion	Optional
	Modbus-RTU Slave (including OMRON Inverter)	Modbus-RTU	Serial communications path connection only	Serial-to-serial conversion	Optional
	Modbus-ASCII Slave	Modbus-ASCII			

Specifying Address in FINS Command Source

Target		Protocol conversion	Routing tables for treating serial communications path as network	FINS header		
				Remote network address	Remote node address	Remote unit address
PLC (CS/CJ /CP/NSJ Series, CVM1/CV Series)		Host Link FINS	Created	Network address assigned to the serial port according to the routing tables	Host Link unit number incremented by 1 (1 to 32) (See note.)	Must be the actual unit address of the destination unit.
			Not created	Serial port unit address		
Any component except PLC	OMRON Component	CompoWay/ F	Created	Network address assigned to the serial port according to the routing tables	00 hex (indicates communications in local PC)	Must be the unit address of the serial port.
	Modbus-RTU Slave (including OMRON Inverter)	Modbus-RTU	Not created	Network address for specifying the actual remote PC	Node address for specifying the actual remote PC	
	Modbus-ASCII Slave	Modbus-ASCII				

Note To access from a CX-Programmer, Select **Change PLC** - **Serial Gateway Guide**, and enter the actual Host Link unit number, The CX-Programmer will automatically increment the value by one.

3-6-8 Using a PLC as the Target

Network-to-Serial Conversion

Routing tables are required to enable the serial communications path to be treated as a network.

Required Routing Tables

Specify the addresses as shown in the following example.

Address Specification

Address	Contents	Example
Remote network address	(1) Serial communications path network address	A
Remote node address	(2) Unit No. for Host Link incremented by 1.	s+1
Remote unit address	(3) Actual remote unit address for FINS command	CPU Unit: 00 hex

Routing tables for treating serial communications path as a network

Unit number	Network address
80 hex (128 decimal) Calculated from unit number: 0, port 1	A

(1) Network address:
To serial communications path network address A

Target: PLC
(2) Node address: Unit numbers for Host Link (0 to 31) + 1

(3) Unit address: E.g., 00 hex for CPU Unit

Serial-to-Serial Conversion

Routing tables to enable the serial communications path to be treated as a network are optional.

Without Routing Tables

Specify the addresses as shown in the following example.

Address Specification

Address	Contents	Example
Remote network address	(1) Serial communications path unit address	80 hex (128 decimal) Calculated from Unit No. 0, port 1
Remote node address	(2) Unit No. for Host Link incremented by 1.	s+1
Remote unit address	(3) Actual remote unit address for FINS command	CPU Unit: 00 hex

No routing tables required to treat serial communications path as a network

(1) Network address:
To serial communications path unit address (e.g., 80 hex)

Target: PLC
(2) Node address: Unit numbers for Host Link (0 to 31) + 1

(3) Unit address: E.g., 00 hex for CPU Unit

With Routing Tables

Specify the addresses as shown in the following example.

Address Specification

Address	Contents	Example
Remote network address	(1) Serial communications path unit address	A
Remote node address	(2) Unit No. for Host Link incremented by 1.	s+1
Remote unit address	(3) Actual remote unit address for FINS command	CPU Unit: 00 hex

FINS command sent

Serial communications path (Host Link FINS)

Serial Communications Unit/Board
E.g., Unit number 0, port 1

PLC Routing tables for treating serial communications path as a network

Unit number	Network address
80 hex (128 decimal) Calculated from Unit No. 0, port 1	A

Serial communications path (Host Link FINS)

(1) Network address:
To serial communications path network address A

Target: PLC
(2) Node address: Unit numbers for Host Link (0 to 31) + 1
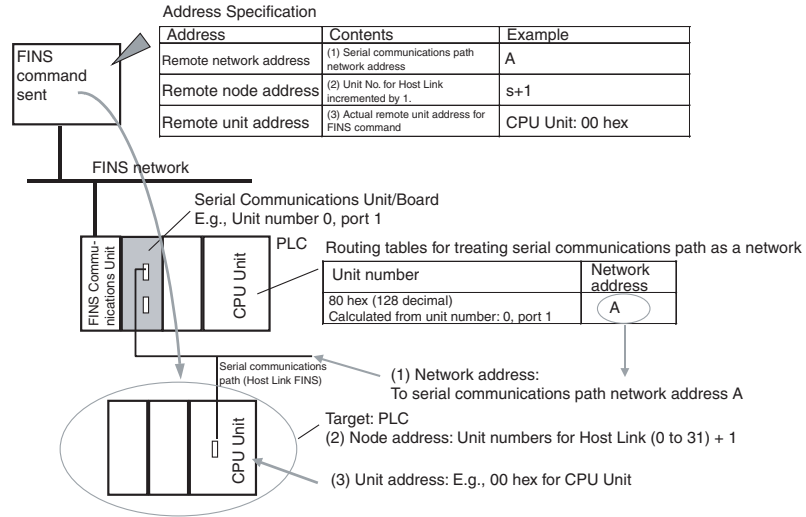
(3) Unit address: E.g., 00 hex for CPU Unit

3-6-9   Using a non-PLC Component as the Target

Network-to-Serial Conversion

Routing tables to enable the serial communications path to be treated as a network are optional.

Without Routing Tables

Specify the addresses as shown in the following example.

Address Specification

Address	Contents		Example
Remote network address	Address to distinguish standard PLC	(1) Network address	N
Remote node address		(2) Node address	m
Remote unit address		Serial port unit address	80 hex (128 decimal) Calculated from unit number 0, port 1

FINS command sent

FINS network: Network address N

Serial Communications Unit/Board
E.g., Unit number 0, port 1

PLC

Address to distinguish standard PLC
(1) Network address: To N
(2) Node address: To m

No routing tables required to treat serial communications path as a network

(3) Unit address:
To serial port unit address (e.g., 80 hex)

Serial communications path (CompoWay/F, Modbus)

Target: OMRON Component or Modbus Slave

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With Routing Tables

Specify the addresses as shown in the following example.

Address Specification

Address	Contents	Example
Remote network address	(1) Serial communications path network address	A
Remote node address	(2) Local PC internal communications	00 hex
Remote unit address	(3) Serial port unit address	80 hex (128 decimal) Calculated from Unit No. 0, port 1

FINS command sent

FINS network

Serial Communications Unit/Board
E.g., Unit number 0, port 1

PLC   Routing tables for treating serial communications path as a network

(2) Node address: Local PLC internal communications To 00 hex

FINS Communications Unit

CPU Unit

Unit number	Network address
80 hex (128 decimal) Calculated from Unit No. 0, port 1	A

(3) Unit address: To serial port unit address (e.g., 80 hex)

Serial communications path (CompoWay/F, Modbus)

(1) Network address: To serial communications path network address A
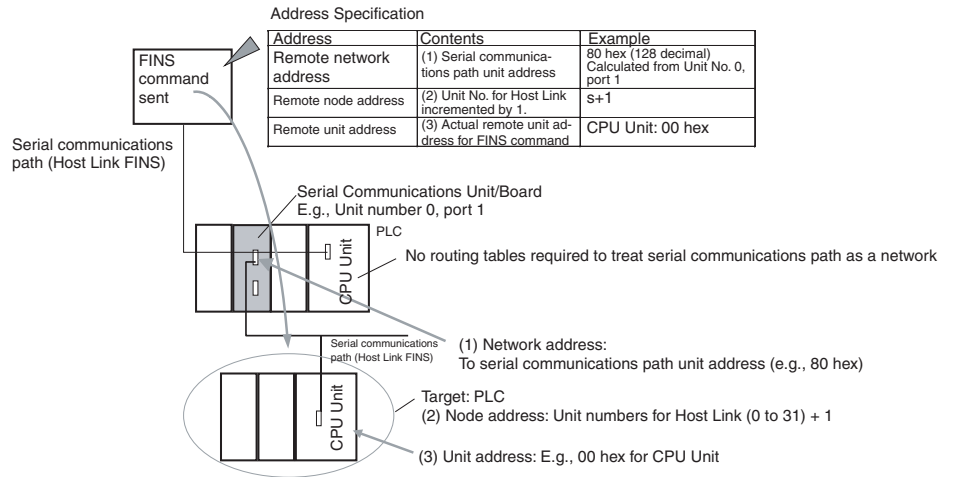
Target: OMRON Component or Modbus Slave

Serial-to-Serial Conversion

Routing tables to enable the serial communications path to be treated as a network are optional.

Without Routing Tables
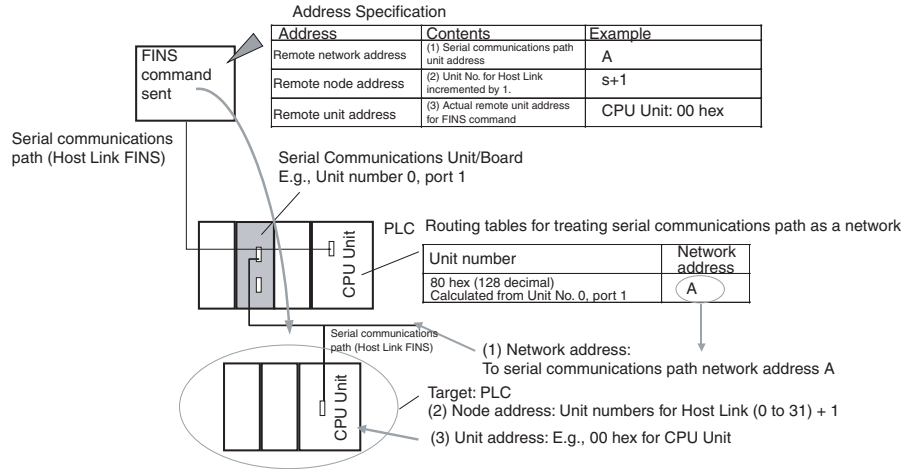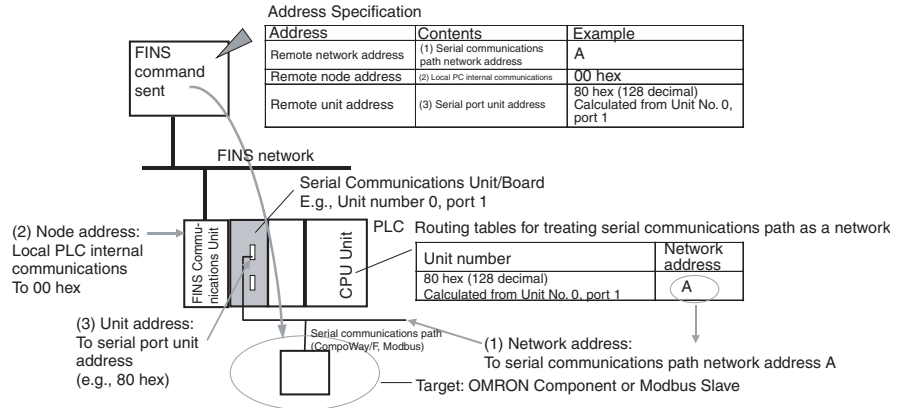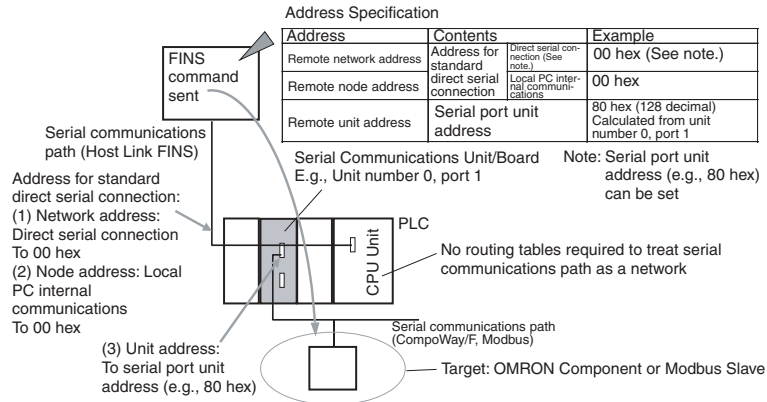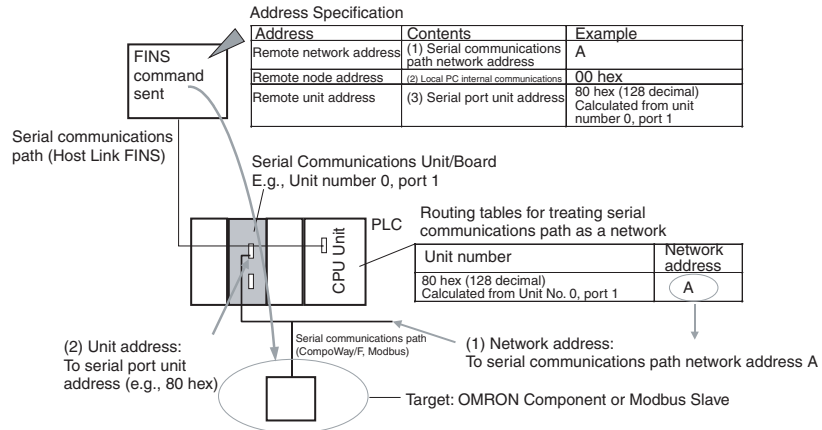
Specify the addresses as shown in the following example.

Address Specification

Address	Contents		Example
Remote network address	Address for standard direct serial connection	Direct serial connection (See note.)	00 hex (See note.)
Remote node address		Local PC internal communications	00 hex
Remote unit address	Serial port unit address		80 hex (128 decimal) Calculated from unit number 0, port 1

FINS command sent

Serial communications path (Host Link FINS)

Address for standard direct serial connection:
(1) Network address: Direct serial connection To 00 hex
(2) Node address: Local PC internal communications To 00 hex

Serial Communications Unit/Board
E.g., Unit number 0, port 1

Note: Serial port unit address (e.g., 80 hex) can be set

CPU Unit   PLC

No routing tables required to treat serial communications path as a network

(3) Unit address: To serial port unit address (e.g., 80 hex)

Serial communications path (CompoWay/F, Modbus)

Target: OMRON Component or Modbus Slave

With Routing Tables

Specify the addresses as shown in the following example.

Address Specification

Address	Contents	Example
Remote network address	(1) Serial communications path network address	A
Remote node address	(2) Local PC internal communications	00 hex
Remote unit address	(3) Serial port unit address	80 hex (128 decimal) Calculated from unit number 0, port 1

FINS command sent

Serial communications path (Host Link FINS)

Serial Communications Unit/Board
E.g., Unit number 0, port 1

Routing tables for treating serial communications path as a network

CPU Unit   PLC

Unit number	Network address
80 hex (128 decimal) Calculated from Unit No. 0, port 1	A

(2) Unit address: To serial port unit address (e.g., 80 hex)

Serial communications path (CompoWay/F, Modbus)

(1) Network address: To serial communications path network address A
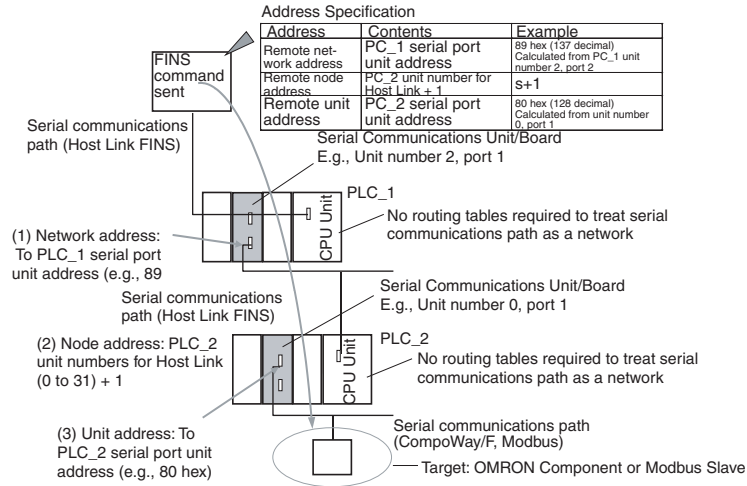
Target: OMRON Component or Modbus Slave

Serial-to-Serial-to-Serial Conversion

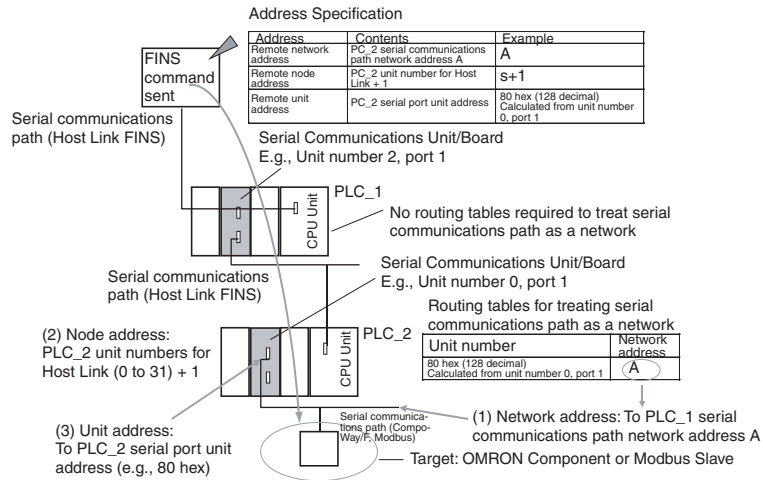Routing tables to enable the serial communications path to be treated as a network are optional.

Without Routing Tables

Specify the addresses as shown in the following example.

Address Specification

Address	Contents	Example
Remote network address	PC_1 serial port unit address	89 hex (137 decimal) Calculated from PC_1 unit number 2, port 2
Remote node address	PC_2 unit number for Host Link + 1	s+1
Remote unit address	PC_2 serial port unit address	80 hex (128 decimal) Calculated from unit number 0, port 1

FINS command sent

Serial communications path (Host Link FINS)

Serial Communications Unit/Board
E.g., Unit number 2, port 1

PLC_1

No routing tables required to treat serial communications path as a network

(1) Network address: To PLC_1 serial port unit address (e.g., 89

Serial communications path (Host Link FINS)

Serial Communications Unit/Board
E.g., Unit number 0, port 1

PLC_2

No routing tables required to treat serial communications path as a network

(2) Node address: PLC_2 unit numbers for Host Link (0 to 31) + 1

Serial communications path (CompoWay/F, Modbus)

(3) Unit address: To PLC_2 serial port unit address (e.g., 80 hex)

Target: OMRON Component or Modbus Slave

With Routing Tables

Specify the addresses as shown in the following example.

Address Specification

Address	Contents	Example
Remote network address	PC_2 serial communications path network address A	A
Remote node address	PC_2 unit number for Host Link + 1	s+1
Remote unit address	PC_2 serial port unit address	80 hex (128 decimal) Calculated from unit number 0, port 1

FINS command sent

Serial communications path (Host Link FINS)

Serial Communications Unit/Board
E.g., Unit number 2, port 1

PLC_1

No routing tables required to treat serial communications path as a network

Serial communications path (Host Link FINS)

Serial Communications Unit/Board
E.g., Unit number 0, port 1

Routing tables for treating serial communications path as a network

(2) Node address: PLC_2 unit numbers for Host Link (0 to 31) + 1

PLC_2

Unit number	Network address
80 hex (128 decimal) Calculated from unit number 0, port 1	A

(3) Unit address: To PLC_2 serial port unit address (e.g., 80 hex)

Serial communications path (CompoWay/F, Modbus)

(1) Network address: To PLC_1 serial communications path network address A

Target: OMRON Component or Modbus Slave

3-6-10 Explanation

To treat the serial communications path as a network, the serial port itself is recognized as a Communications Unit and is allocated a network address.
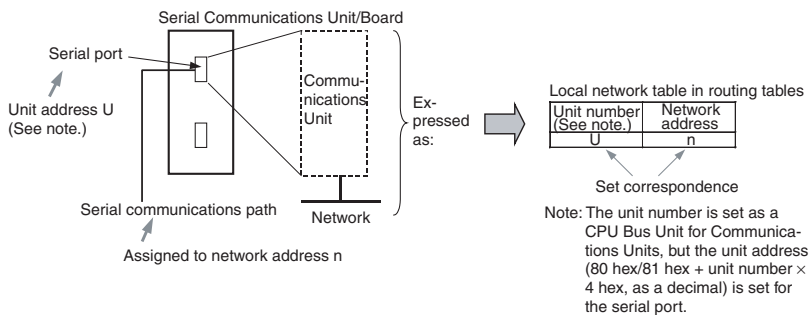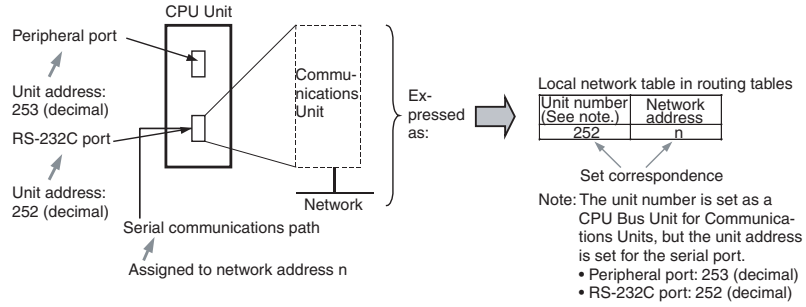

The CX-Net in the CX-Programmer is used to set the relationship between the serial port's unit address and the allocated network address in the local network tables of the routing tables. These settings are then transferred to the CPU Unit to which the Serial Communications Unit/Board is mounted.
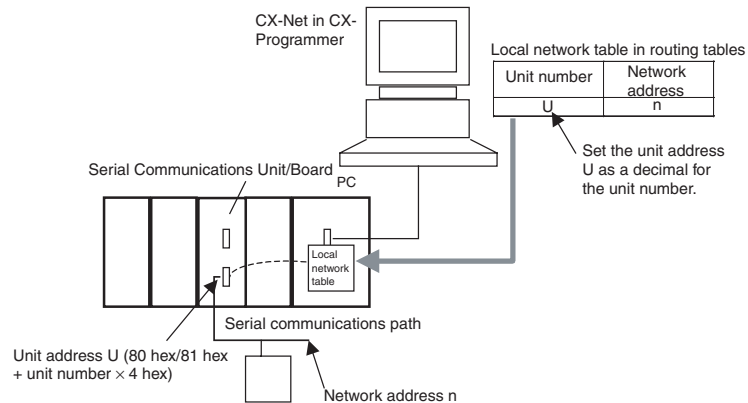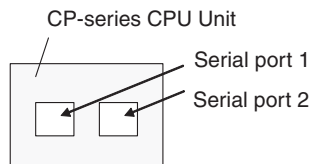

Unit Addresses for Serial Communications Ports

CS/CJ Series CPU Unit
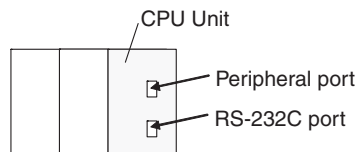
Serial communications port on CPU Unit	Unit address
Peripheral port	FD hex (253 decimal)
RS-232C port	FC hex (252 decimal)

CP-series CPU Unit

CP-series CPU Unit

Serial port 1
Serial port 2

Serial communications port on Option Board of CPU Unit	Unit address
Serial port 1	FD hex (253 decimal)
Serial port 2	FC hex (252 decimal)

NSJ Controller

NSJ Controller

Serial port C on Controller Section
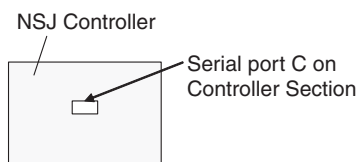
Serial communication port on NSJ Controller	Unit address
Serial port C	FC hex (252 decimal)

Serial Communications Unit/Board

• Serial Port 1 Unit Addresses

Unit number	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	Board
Hexadecimal	80	84	88	8C	90	94	98	9C	A0	A4	A8	AC	B0	B4	B8	BC	E4
Decimal	128	132	136	140	144	148	152	156	160	164	168	172	176	180	184	188	228

• Serial Port 2 Unit Addresses

Unit number	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	Board
Hexadecimal	81	85	89	8D	91	95	99	9D	A1	A5	A9	AD	B1	B5	B9	BD	E5
Decimal	129	133	137	141	145	149	153	157	161	165	169	173	177	181	185	189	229

These settings enable the serial communications path to be treated as a single FINS network. Further, the network address allocated to the serial port can be specified in the destination network address part of the FINS message. This enables messages to passed on to serial ports in a system comprised of multiple networks connected to a single PC (including the serial communications path).

FINS message

Serial Communications Unit/Board
CPU Unit

Routing enabled

Local network table

Serial communications path

Specify on which path to send the message
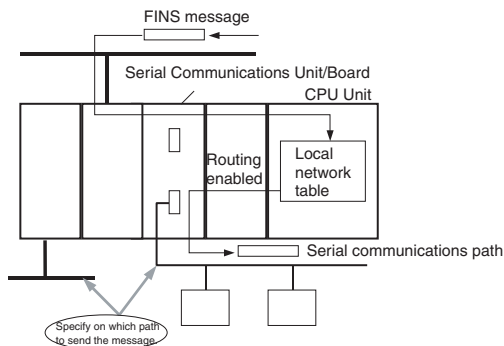
Reasons for Routing Tables

CompoWay/F, Modbus-RTU, Modbus-ASCII Protocol Conversion

Routing tables are not required to enable serial communications paths to be treated as networks. (The serial port can be specified in the node without using routing tables by specifying the node to which the Board/Unit is connected, and specifying the unit address as that of the serial port.)

Host Link FINS Protocol Conversion and Use of Network

Routing tables are required to enable the serial communications path to be treated as a network. This is because with Host Link FINS, the FINS remote node address is used to specify the target (communications partner PC that is the Host Link slave). Therefore, the node to which the Board/Unit is mounted cannot always be specified, depending on the FINS remote node address. To specify the Unit at the target requires the FINS remote unit address. Therefore, the serial port cannot always be specified depending on the FINS unit address.

The network address for the serial communications path is used to specify from the network the node to which the Board/Unit is mounted and the serial port. Therefore, routing tables must be used to enable the serial communications path to be treated as a network.

Host Link FINS Protocol Conversion and Use of Serial Connection

Routing tables are not required to enable serial communications paths to be treated as networks. The serial port in the node can be specified without routing tables by specifying the network address as the unit address of the serial port.

3-7 Communications Frames

3-7-1 CompoWay/F

Command Frame

Frame before Conversion

FINS header				FINS command		CompoWay/F (See note.)				
Remote network address (DNA)	Remote node address (DA1)	Remote unit address (DA2)	Etc.	MRC	SRC	Node No. ($\times 10^1$) ($\times 10^2$) (ASCII code 2 bytes)	Sub-address "00" (ASCII code 3030 hex) etc.	SID "0" (ASCII code 30 hex)	Command (MRC, SRC) (ASCII code 4 bytes)	Text (ASCII code)
Serial port allocated address or local network address	00 hex or local network node address	Serial port unit address		28	03					

Frame after Conversion

CompoWay/F							
STX (02 hex)	Node No. ($\times 10^1$) ($\times 10^2$) (ASCII code 2 bytes)	Sub-address "00" (ASCII code 3030 hex) etc.	SID "0" (ASCII code 30 hex)	Command (MRC, SRC) (ASCII code 4 bytes)	Text (ASCII code)	ETX (03 hex)	BCC

Note CompoWay/F commands use ASCII as the transmission code. Therefore, be sure to use ASCII for the CompoWay/F command after the FINS command code 2803 hex (from node number to text) using CMND(490) or other instruction.

Example: If the CompoWay/F command MRC SRC is "01" "02" (where the quotation marks (" ") indicate ASCII characters), 0, 1, 0, 2 must be treated as ASCII characters. Therefore, set "01" as 3031 hex (not 01 hex), and "02" as 3032 hex (not 02 hex).
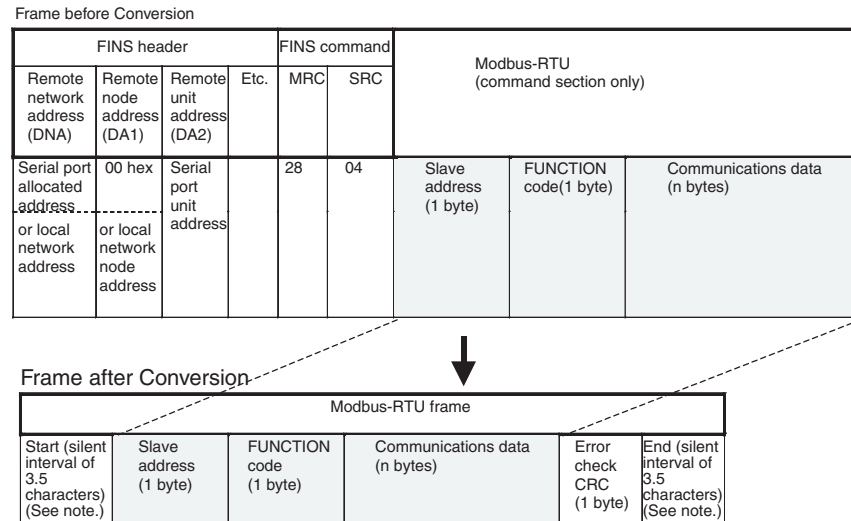
Further, to write the CompoWay/F command to the command storage area using CMND(490) in frame order (without creating empty bytes), the SID component of the CompoWay/F command requires 1 byte of ASCII as 30 hex, so the subsequent components (s+3 and afterwards) must be set in one byte each.

Response Frame

Frame before Conversion

Frame after Conversion

3-7-2 Modbus-RTU

Command Frame

Frame before Conversion

Frame after Conversion

Note The silent interval in the Modbus-RTU frame is automatically generated by the Serial Communications Board/Unit.

Response Frame

Frame before Conversion

			Modbus-RTU frame			
Start (silent interval of 3.5 characters) (See note.)	Slave address (1 byte)	FUNCTION code (1 byte)	Communications data (n bytes)		Error check CRC (1 byte)	End (silent interval of 3.5 characters) (See note.)

Frame after Conversion

FINS header				FINS command		FINS end code		Modbus-RTU (command section only)		
Remote network address (DNA)	Remote node address (DA1)	Remote unit address (DA2)	Etc.	MRC	SRC	MRES	SRES			
Serial port allocated address or local network address	00 hex or local network node address	Serial port unit address		28	04	User-speci-fied	User-speci-fied	Slave address (1 byte)	FUNCTION code (1 byte)	Communica-tions data (n bytes)

3-7-3 Modbus-ASCII

Command Frame

Frame before Conversion

FINS header				FINS command		Modbus-ASCII (command section only)		
Remote network address (DNA)	Remote node address (DA1)	Remote unit address (DA2)	Etc.	MRC	SRC			
Serial port allocated address or local network address	00 hex or local network node address	Serial port unit address		28	05	Slave address (ASCII code 2 characters: 4 bytes)	FUNCTION code (ASCII code 2 characters: 4 bytes)	Communications data (ASCII code n characters)

Frame after Conversion

			Modbus-ASCII frame		
Header ":" (ASCII code 3A hex)	Slave address (ASCII code 2 characters: 4 bytes)	FUNCTION code (ASCII code 2 characters: 4 bytes)	Communications data (ASCII code n characters)	CR (0D hex)	LF (0A hex)

Response Frame

Frame before Conversion

			Modbus-ASCII frame		
Header ":" (ASCII code 3A hex)	Slave address (ASCII code 2 characters: 4 bytes)	FUNCTION code (ASCII code 2 characters: 4 bytes)	Communications data (ASCII code n characters) or error code	CR (0D hex)	LF (0A hex)

Frame after Conversion

FINS header				FINS command		FINS end code		Modbus-ASCII (command section only)		
Remote network address (DNA)	Remote node address (DA1)	Remote unit address (DA2)	Etc.	MRC	SRC	MRES	SRES			
Serial port allocated address or local network address	00 hex or local network node address	Serial port unit address		28	05	User-speci-fied	User-speci-fied	Slave address (ASCII code 2 characters: 4 bytes)	FUNCTION code (ASCII code 2 characters: 4 bytes)	Communications data (ASCII code n characters) or error code

3-7-4   Host Link FINS

Command Frame

Frame before Conversion

FINS header				FINS command		FINS text
Remote network address (DNA)	Remote node address (DA1)	Remote unit address (DA2)	Etc.	MRC	SRC	
Serial port allocated address or serial port unit address	Unit No. for Host Link + 1 (1 to 32)	Any except serial port unit address		User-speci-fied	User-speci-fied	User-specified

Frame after Conversion

Host Link header		Host Link header code	Etc.	Text			Error check code	Terminator
@	Unit No. for Host Link (0 to 31)	FA		FINS header	FINS command	FINS text	FCS	*+CR

Response Frame

Frame before Conversion

Host Link header	Host Link header code	Etc.	Text				Error check code	Terminator
@	Unit No. for Host Link (0 to 31)	FA	FINS header	FINS command	End code	FINS text	FCS	*+CR

Frame after Conversion

FINS header				FINS command		End code	FINS text
Remote network address (DNA)	Remote node address (DA1)	Remote unit address (DA2)	Etc.	MRC	SRC		
Serial port allocated address or serial port unit address	Unit No. for Host Link + 1 (1 to 32)	Any except serial port unit address		User-speci-fied	User-speci-fied		User-specified

3-7-5 Sending Commands Using the CMND(490) Instruction

Use the following method to send FINS commands to the Serial Communications Board/Unit from the PC.

Setting CMND(490) Operands

S Operand

- Set the FINS command code (2803/2804/2805 hex) in S.
- Set the data without spaces (see note) following the FINS command code in S+1 onwards.

Note   Frames are set in the same order as in I/O memory from leftmost to rightmost byte (without blank bytes (00 hex)).

C Operand

C+2 bits 00 to 07 (Send destination network address)

- With routing tables that treat serial communications path as a network: Network address corresponding to serial port in the routing tables.
- Without routing tables that treat serial communications path as a network:
  - CompoWay/F, Modbus: Depends on the system configuration.
  - Host Link FINS: Always set the unit address of the serial port.

C+3 bits 08 to 15 (Remote destination node address)

- CompoWay/F, Modbus
  - With routing tables that treat serial communications path as a network: 00 hex (indicates local PC communications)
  - Without routing tables that treat serial communications path as a network: Node address for specifying the actual remote PC
- Host Link FINS
  - Host Link unit number incremented by one (1 to 32)

C+3 bits 00 to 07 (Send destination unit address)

- CompoWay/F, Modbus
  Always set the unit address of the serial port

Note Use either of the following methods to specify the serial port using the CMND(490) instruction.

- Set 80/81 hex + 4 × unit number directly as the serial port unit address in the send destination unit address bits 00 to 07 of C+3. (With this method, set the serial port number (physical port) to 0 hex (not used) in bits 08 to 11 of C+2)

- Set the unit address of the Serial Communications Board/Unit itself (Board: E1 hex; Unit: 10 hex + unit number) in the send destination unit address bits 00 to 07 of C+3, and set the serial port numbers (Port number 1: 1 hex; Port number 2: 2 hex) in the serial port number (physical port) bits 08 to 11 of C+2.

- Host Link FINS
Always set the unit address of the actual destination unit.

Sending Modbus-RTU Commands

- Set the FINS command code 2804 hex indicating the Modbus-RTU conversion in S.

- Set the slave address (1 byte) + FUNCTION code (1 byte) + communications data (n bytes) in order of leftmost byte to rightmost bytes (see note) from S+1 onwards.

Note For Modbus-RTU, set the Modbus-RTU slave address (1 byte) in the leftmost byte of S+1, and the FUNCTION code (1 byte) in the rightmost byte of S+.

Example of Sending Modbus-RTU Command Using CMND(490) Instruction

This example is for writing a frequency reference value from an OMRON 3G3MV Inverter connected through RS-485 to the Serial Communications Unit via two networks, Ethernet-to-Controller Link.

Example: The CMND(490) instruction is executed in the PC for Ethernet. The Modbus-RTU command for writing frequency reference value data is sent via Ethernet to the 3G3MV Inverter (Modbus-RTU slave address: 02) that is connected to port 1 (Unit address: 80 hex + 4 hex × unit number 3 = 8C hex) of the Serial Communications Unit (Unit number: 3), that is mounted to the PC on the Controller Link (Network address: 2; Node address: 5). The frequency reference value 10.0 Hz (set as 100 decimal in units of 0.1 Hz) is written.

The Modbus-RTU command is configured from the following elements.
Modbus-RTU slave address: 02
FUNCTION code: 10 hex (DATA WRITE)
Write start register No.: 0002 hex (frequency reference)
Write data: 0064 hex (100 decimal)
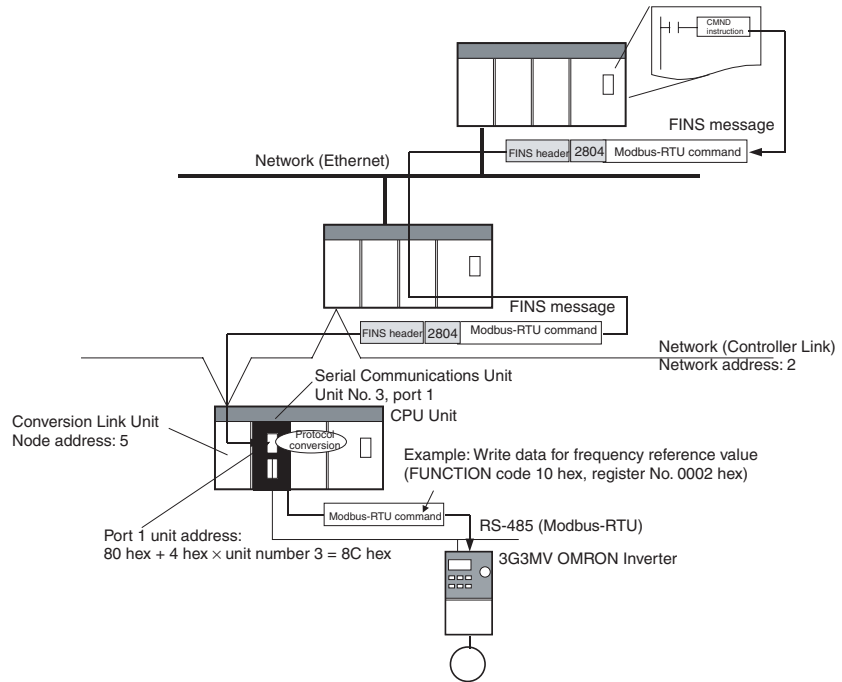
List of Settings

- FINS Network Settings

Item	Value (Example)	Setting location
Send destination network address (Controller Link network address of PC to which Serial Communications Unit is mounted)	2	Set 02 hex in the control data C+2 bits 00 to 07 (network address) of CMND(490). Note: Set 0 hex in the control data C+2 bits 08 to 11 (serial port number) of CMND(490).
Send destination node address (node address in Controller Link for PC to which Serial Communications Unit is mounted)	5	Set 05 hex in the control data C+3 bits 08 to 15 (send destination node address) of CMND(490).
Serial Communications Unit unit number	3	Use to calculate the following unit address for the serial port
Serial Communications Unit serial port	Port 1	80 hex + 4 hex × unit number 3 = 8C hex
Send destination unit address (unit address of serial port on Serial Communications Unit)	80 hex + 4 hex × unit number 3 = 8C hex (or 10 + unit number 3 - 13 hex, and serial port number 1 = 1 hex)	Set 8C hex in the control data C+3 bits 00 to 07 (send destination unit address) of CMND(490). (Alternatively, set 13 hex in the control data C+3 bits 00 to 07 (send destination unit address) and set 1 hex in C+2 bits 08 to 11 (serial port number).)

• Modbus-RTU Settings

Command Frame

Item	Set value	Setting location
FINS command code: Converting to Modbus-RTU = 2804 hex	2804 hex	Set 2804 hex in controller data s of the CMND(490) instruction.
Modbus slave address (e.g., 02 hex)	02 hex	Set 0210 hex in controller data s+1 of the CMND(490) instruction.
FUNCTION code: DATA WRITE = 10 hex	10 hex	
Write data register No. (e.g., frequency reference = 0002 hex)	0002 hex	Set 0002 hex in controller data s+2 of CMND(490).
Number of write data registers (e.g, 1 register)	0001 hex	Set 0001 hex in controller data s+3 of CMND(490).
Number of attached data registers Note: Set 02 hex of this value in the leftmost byte of S+4. Set 00 hex as the leftmost register No. in the rightmost byte of S+4.	0200 hex	Set 0200 hex in controller data s+4 of CMND(490).
Register No. 0002 hex data (e.g., 0064 hex) Note: Set 64 hex as the rightmost register No. in the leftmost byte of S+5.	6400 hex	Set 6400 hex in controller data s+5 of CMND(490).

Response Frame

Item	Setting	Setting location
Modbus Slave address (e.g., 02 hex)	02 hex	Stored in D+2 of CMND(490)
FUNCTION code: Write data (= 10 hex)	10 hex	
Write data register No. (e.g., frequency reference = 0002 hex)	0002 hex	Stored in D+3 of CMND(490)
Write data registers (e.g., 1 register)	0001 hex	Stored in D+4 of CMND(490)

[CMND   S   D   C]

Command Details

Operand	Offset	Value	Meaning
S: D01000	+0:	2804 hex	Conversion to Modbus-RTU (FINS command code: 2804 hex)
	+1:	0210 hex	Modbus-RTU slave address: 02 hex, FUNCTION code: 10 hex (DATA WRITE)
	+2:	0002 hex	Write data register No.: 0002 hex (frequency reference)
	+3:	0001 hex	Number of write data registers: 0001 hex (1 register)
	+4:	0200 hex	Number of attached data bytes: 02 hex (2 bytes); Leftmost register No.: 00 hex
	+5:	6400 hex	Rightmost register No.: 64 hex (Frequency reference value: 10.0 Hz when unit is 0.1 Hz), blank = 00 hex
D: D02000			First response storage word
C: D00000	+0:	00 0C hex	Number of command data bytes: 000C hex (12 bytes decimal)
	+1:	00 0A hex	Number of response data bytes: 000A hex (10 bytes decimal)
	+2:	0002 hex	Send destination network address: 02 hex; Serial port number: 0 hex (direct serial port unit address specification)
	+3:	058C hex	Send destination node address: 05 hex; Send destination unit address: 8C hex
	+4:	0000 hex	Response required; Communications port number: 0; Resends: 0 hex
	+5:	0000 hex	Response monitoring time: 2 s

Response

Operand	Offset	Value	Meaning
D: D02000	+0:	2804 hex	Conversion to Modbus-RTU (FINS command code: 2804 hex)
	+1:	0000 hex	FINS end code: 0000 hex (normal)
	+2:	0210 hex	Modbus-RTU slave address: 02 hex, FUNCTION code: 10 hex (DATA WRITE)
	+3:	0002 hex	Write data register No.: 0002 hex (frequency reference)
	+4:	0001 hex	Number of write data registers: 0001 hex (1 register)

Sending Host Link FINS Commands

- Set any FINS command code in S.
- Be sure to set the Host Link unit number (0 to 31) incremented by one (1 to 32) for the PC slave corresponding to the send destination node address in C+3 bits 08 to 15.

Example of Sending Host Link FINS Commands Using CMND(490)

The following example is for sending FINS commands to a CS/CJ/CP-series PLC or an NSJ Controller connected to the Serial Communications Unit through an RS-422A/485 communications path via an Ethernet network.

Example: The CMND(490) instruction is executed in the PC on the Ethernet. The FINS command (e.g., OPERATING MODE CHANGE STOP: 0402 hex) is sent to the CS/CJ/CP-series PLC or NSJ Controller (Host Link unit number = 1) that is connected to port 2 (unit address = 81 hex + 4 hex × unit number 6 = 99 hex = 153 decimal, corresponding to network address 5 in the routing tables) of the Serial Communications Unit (unit number 6) that is connected to the PC on the Ethernet. Routing is performed between the networks, so use the setting for routing tables.

Settings

• FINS Network Settings

Item	Value (example)	Setting location
Send destination network address (network address allocated to target serial port in routing tables)	Network address for serial communications path allocated in local network table settings is 5	• Set 05 hex in bits 00 to 07 (network address) of control data C+2 in the CMND(490) instruction. **Note** Set 0 hex in bits 08 to 11 (serial port number) of control data C+2 in the CMND(490) instruction
Send destination node address (unit number for Host Link of PC connected to target serial port + 1)	Remote PC unit number for Host Link: 1 Therefore, set 1+1 = 2	• Set 02 hex in bits 08 to 15 (send destination node address) of control data C+3 in the CMND(490) instruction.
Send destination unit address (unit address of remote unit on PC connected to target serial port)	CPU Unit: 00 hex	• Set 00 hex in bits 00 to 07 of control data C+3 in the CMND(490) instruction.
Serial Communications Unit unit number	6	Use the following equation to calculate the unit address of the serial port. 81 hex + 4 hex × unit number 6 = 99 hex (153 decimal) Use CX-Net to set the local network tables in the routing tables. | Unit number	Network address
---	---
Serial Communications Unit's serial port unit address: 153 (decimal)	Serial port network address: 5 (decimal)	
Serial Communications Unit serial port	Port 2	

• Host Link FINS Settings

Command Frame

Item	Setting	Setting location
FINS command code (e.g., change operating mode (stop operation))	0402 hex	Set in 0402 hex of control data S for CMND(490) instruction
FINS command parameter (e.g., always FFFF hex to change operating mode)	FFFF hex	Set in FFFF hex of control data s+1 for CMND(490) instruction

Response Frame

Item	Setting	Setting location
FINS command code (E.g., change operating mode (stop operation))	0402 hex	Stored in D of CMND(490) instruction
FINS command end code (normal end: 0000 hex)	0000 hex	Stored in D+1 of CMND(490) instruction

[CMND   S   D   C]

Command Details

Operand	Offset	Value	Meaning
S: D01000	+0:	0402 hex	Change operating mode (stop operation) (FINS command code: 0402 hex)
	+1:	FFFF hex	Change operating mode (stop operation): Always FFFF hex
D: D02000			First response storage word
C: D00000	+0:	000C hex	Command data bytes: 0004 hex (4 bytes decimal)
	+1:	000A hex	Response data bytes: 0004 hex (4 bytes decimal)
	+2:	0005 hex	Send destination network address: 05 hex; Serial port number: 0 hex (not used)
	+3:	0200 hex	Send destination node address: 02 hex (set the unit number for Host Link + 1); Send destination unit address: 00 hex
	+4:	0000 hex	Response required; Communications port number: 0; Resends: 0 hex
	+5:	0000 hex	Response monitoring time: 2 s

Response

Operand	Offset	Value	Meaning
D: D02000	+0:	0402 hex	Change operating mode (stop operation) (FINS command code: 0402 hex)
	+1:	FFFF hex	FINS end code: FFFF hex (normal end)

Note
1. The method used to set the remote destination network address, node address, and unit address for sending data to or receiving data from the PC connected serially via Host Link to another PC on the network (to which the Serial Communications Board/Unit is mounted) using the SEND(090)/RECV(098) instructions is the same as for the CMND(490) instruction.

2. When creating Host Link FINS command frames using the CMND(490) instruction, always set the unit number for Host Link incremented by one (1 to 32) for the remote destination (send destination) node address (word C+3, bits 08 to 15 of the CMND(490) instruction). Do not set the unit number of the actual Host Link slave (0 to 31). Using the Host Link unit number without incrementing by one will access the PC with the entered Host Link unit number less one.

   For example, specify remote PC with Host Link unit number 2 by entering **3** for the remote destination node address. If the 2 is entered, the PC with Host Link unit number 1 will be accessed.

   To access a PC on a Host Link FINS network using the Serial Gateway from CX-Programmer, however, enter the actual Host Link unit number, without incrementing by one. (Select **Change PLC**, click the **Display Serial Gateway Guide** Button, and set unit number in the **Host Link SYSWAY Settings** field of the Serial Gateway Guide dialog box.

Sending Modbus-ASCII Commands

- Set the FINS command code of 2805 hex in S, indicating conversion to Modbus-RTU.
- In S+1 onwards, set the slave address (2 bytes ASCII) + FUNCTION code (2 bytes ASCII) + communications data (2 × n bytes ASCII) from leftmost bytes to rightmost bytes using ASCII.

Sending CompoWay/F Commands

- Set the FINS command code of 2803 hex in S, indicating conversion to CompoWay/F.
- In S+1 onwards, set the CompoWay/F node number (2 bytes ASCII) + sub-address (2 bytes ASCII) + SID (1 byte ASCII) + CompoWay/F command MRC (2 bytes ASCII) + CompoWay/F command SRC (2 bytes

ASCII) + text (2 × n bytes ASCII) from leftmost bytes to rightmost bytes using ASCII.

Note Set the contents of S+3 when using CompoWay/F commands as follows:
Set the SID "0" as ASCII 30 hex (1 byte) in the leftmost byte, and the leftmost digit of the CompoWay/F command code MRC as ASCII (1 byte) in the rightmost byte. Next, set the bits of S+4 as follows:
Set the rightmost digits of the CompoWay/F command code MRC as ASCII in the leftmost byte, and the leftmost digit of the CompoWay/F command code SRC as ASCII (1 byte) in the rightmost byte. Be sure to set one byte each for the subsequent data without any blank bytes.

This section provides detailed descriptions of the C-mode commands.

4-1   C-mode Command List

The following table lists the C-mode commands (Host Link commands).

Type	Header code	Name	Function
I/O memory reading	RR	CIO AREA READ	Reads the specified number of words beginning with the designated CIO word.
	RL	LR AREA READ	Reads the specified number of words beginning with the designated LR word.
	RH	HR AREA READ	Reads the specified number of words beginning with the designated HR word.
	RC	TIMER/COUNTER PV READ	Reads the specified number of words of the timer/counter PV beginning with the designated word.
	RG	TIMER/COUNTER STATUS READ	Reads the specified number of words of the timer/counter status beginning with the designated word.
	RD	DM AREA READ	Reads the specified number of words beginning with the designated DM word.
	RJ	AR AREA READ	Reads the specified number of words beginning with the designated AR word.
	RE	EM AREA READ	Reads the specified number of words beginning with the designated EM word.
I/O memory writing	WR	CIO AREA WRITE	Writes the specified data in word units beginning with the designated CIO word.
	WL	LR AREA WRITE	Writes the specified data in word units beginning with the designated LR word.
	WH	HR AREA WRITE	Writes the specified data in word units beginning with the designated HR word.
	WC	TIMER/COUNTER PV WRITE	Writes the specified timer/counter PV data in word units beginning with the designated word.
	WD	DM AREA WRITE	Writes the specified data in word units beginning with the designated DM word.
	WJ	AR AREA WRITE	Writes the specified data in word units beginning with the designated AR word.
	WE	EM AREA WRITE	Writes the specified data in word units beginning with the designated EM word.
Timer/counter SV reading	R#	TIMER/COUNTER SV READ 1	Reads in four digits BCD the constant SV that is written as an operand of the designated timer/counter instruction.
	R$	TIMER/COUNTER SV READ 2	Finds the specified timer/counter instruction, beginning with the designated program address, and reads the constant SV in four digits or the word in which the SV is stored.
	R%	TIMER/COUNTER SV READ 3	Finds the specified timer/counter instruction, beginning with the designated program address, and reads the constant SV in four digits (BCD) or the word in which the SV is stored.

Type	Header code	Name	Function
Timer/counter SV changing	W#	TIMER/COUNTER SV CHANGE 1	Changes the SV (timer/counter number S) of the specified timer/counter instruction to a new constant SV.
	W$	TIMER/COUNTER SV CHANGE 2	Finds the specified timer/counter instruction, beginning with the designated program address in the user program, and changes the constant SV in four digits (BCD) or the word in which the SV is stored to a new constant SV or storage word.
	W%	TIMER/COUNTER SV CHANGE 3	Finds the specified timer/counter instruction, beginning with the designated program address in the user program, and changes the constant SV in four digits (BCD) or the word in which the SV is stored to a new constant SV or storage word.
CPU Unit status	MS	STATUS READ	Reads the CPU Unit's operating conditions (operating mode, forced set/reset status, and fatal errors).
	SC	STATUS CHANGE	Changes the CPU Unit's operating mode.
	MF	ERROR READ	Reads the CPU Unit's error information (i.e., all fatal or non-fatal errors currently in effect).
Forced set/reset	KS	FORCED SET	Forcibly sets one designated bit.
	KR	FORCED RESET	Forcibly resets one designated bit.
	FK	MULTIPLE FORCED SET/RESET	Forcibly sets/resets/cancels multiple designated bits.
	KC	FORCED SET/RESET CANCEL	Cancels all forced set/reset status.
PLC model code reading	MM	PLC MODEL READ	Reads the model code of the CPU Unit.
Testing	TS	TEST	Returns, just as it is, a single block that was sent from the host computer.
Program area accessing	RP	PROGRAM READ	Reads, in one batch, the contents of the CPU Unit's user program at the machine language (object) level.
	WP	PROGRAM WRITE	Writes into the CPU Unit's user program area the machine language (object) sent from the host computer.
I/O table creation	MI	I/O TABLE CREATE	Creates an I/O table with the contents of the actual I/O configuration.
I/O memory area registration and reading	QQMR	REGISTER I/O MEMORY	Registers the I/O memory words or bits that are to be read.
	QQIR	READ I/O MEMORY	Reads the registered I/O memory words/bits all at once.
Host Link communications processing	XZ	ABORT (command only)	Aborts the operation being performed by a Host Link command, and then returns to the initial status.
	**	INITIALIZE (command only)	Initializes the transfer control procedures for all Host Link Units.
	IC	Undefined command (response only)	This is the response when the command header code cannot be decoded.

C-mode Command Force Conditions

Header code	Name	Single-frame com-mand	Multiple-frame command	Single-frame response	Multiple-frame response	RUN	MON	PRG	UM write protect	UM read protect
RR	CIO AREA READ	Valid	Not valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid
RL	LR AREA READ	Valid	Not valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid
RH	HR AREA READ	Valid	Not valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid
RC	PV READ	Valid	Not valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid
RG	TC STATUS READ	Valid	Not valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid
RD	DM AREA READ	Valid	Not valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid
RJ	AR AREA READ	Valid	Not valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid
RE	EM AREA READ	Valid	Not valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid
WR	CIO AREA WRITE	Valid	Valid	Valid	Not valid	Not valid	Valid	Valid	Valid	Valid
WL	LR AREA WRITE	Valid	Valid	Valid	Not valid	Not valid	Valid	Valid	Valid	Valid
WH	HR AREA WRITE	Valid	Valid	Valid	Not valid	Not valid	Valid	Valid	Valid	Valid
WC	PV WRITE	Valid	Valid	Valid	Not valid	Not valid	Valid	Valid	Valid	Valid
WD	DM AREA WRITE	Valid	Valid	Valid	Not valid	Not valid	Valid	Valid	Valid	Valid
WJ	AR AREA WRITE	Valid	Valid	Valid	Not valid	Not valid	Valid	Valid	Valid	Valid
WE	EM AREA WRITE	Valid	Valid	Valid	Not valid	Not valid	Valid	Valid	Valid	Valid
R#	SV READ 1	Valid	Not valid	Valid	Not valid	Valid	Valid	Valid	Valid	Not valid
R$	SV READ 2	Valid	Not valid	Valid	Not valid	Valid	Valid	Valid	Valid	Not valid
R%	SV READ 3	Valid	Not valid	Valid	Not valid	Valid	Valid	Valid	Valid	Not valid
W#	SV CHANGE 1	Valid	Not valid	Valid	Not valid	Not valid	Valid	Valid	Not valid	Not valid
W$	SV CHANGE 2	Valid	Not valid	Valid	Not valid	Not valid	Valid	Valid	Not valid	Not valid
W%	SV CHANGE 3	Valid	Not valid	Valid	Not valid	Not valid	Valid	Valid	Not valid	Not valid
MS	STATUS READ	Valid	Not valid	Valid	Not valid	Valid	Valid	Valid	Valid	Valid
SC	STATUS CHANGE	Valid	Not valid	Valid	Not valid	Valid	Valid	Valid	Valid	Valid
MF	ERROR READ	Valid	Not valid	Valid	Not valid	Valid	Valid	Valid	Valid	Valid
KS	FORCED SET	Valid	Not valid	Valid	Not valid	Not valid	Valid	Valid	Valid	Valid
KR	FORCED RESET	Valid	Not valid	Valid	Not valid	Not valid	Valid	Valid	Valid	Valid
FK	MULTIPLE FORCED SET/RESET	Valid	Not valid	Valid	Not valid	Not valid	Valid	Valid	Valid	Valid
KC	FORCED SET/ RESET CANCEL	Valid	Not valid	Valid	Not valid	Not valid	Valid	Valid	Valid	Valid
MM	PLC MODEL READ	Valid	Not valid	Valid	Not valid	Valid	Valid	Valid	Valid	Valid
TS	TEST	Valid	Not valid	Valid	Not valid	Valid	Valid	Valid	Valid	Valid
RP	PROGRAM READ	Valid	Not valid	Valid	Valid	Valid	Valid	Valid	Valid	Not valid

Header code	Name	Single-frame command	Multiple-frame command	Single-frame response	Multiple-frame response	RUN	MON	PRG	UM write protect	UM read protect
WP	PROGRAM WRITE	Valid	Valid	Valid	Not valid	Not valid	Not valid	Valid	Not valid	Valid
MI	I/O TABLE GENERATE	Valid	Not valid	Valid	Not valid	Not valid	Not valid	Valid	Not valid	Valid
QQMR	READ I/O MEMORY	Valid	Valid	Valid	Not valid	Valid	Valid	Valid	Valid	Valid
QQIR	REGISTER I/O MEMORY	Valid	Not valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid
XZ	ABORT (command only)	Valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid
**	INITIALIZE (command only)	Valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid
IC	Undefined command (response only)	Valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid	Valid

4-2 End Codes

End Code Summary

These are the response (end) codes that are returned in the response frame. When two or more errors occur, the end code for the first error will be returned.

End code	Contents	Probable cause	Corrective measures
00	Normal completion	No problem exists.	---
01	Not executable in RUN mode	The command that was sent cannot be executed when the PLC is in RUN mode.	Check the relation between the command and the PLC mode.
02	Not executable in MONITOR mode	The command that was sent cannot be executed when the PLC is in MONITOR mode.	
03	UM write-protected	The PLC's UM is write-protected.	Turn OFF pin 1 of the CPU Unit's DIP switch (SW1).
04	Address over	The program address setting in an read or write command is above the highest program address.	Check the program.
0B	Not executable in PROGRAM mode	The command that was sent cannot be executed when the PLC is in PROGRAM mode.	This code is not currently used.
13	FCS error	The FCS is wrong.	Check the FCS calculation method. If there was influence from noise, transfer the command again.
14	Format error	The command format is wrong, or a command that cannot be divided has been divided, or the frame length is smaller than the minimum length for the applicable command.	Check the format and transfer the command again.
15	Entry number data error	The data is outside of the specified range or too long. Hexadecimal data has not been specified.	Correct the data and transfer the command again.
16	Command not supported	The operand specified in an SV Read or SV Change command does not exist in the program.	Check search data or the search starting point.

End code	Contents	Probable cause	Corrective measures
18	Frame length error	The maximum frame length of 131 bytes was exceeded. (If the frame exceeds 280 bytes, the Reception Overflow Flag will be turned ON and there will not be a response.)	Check the command and divide it into multiple frames if necessary.
19	Not executable	The read SV exceeded 9,999, or an I/O memory batch read was executed when items to read were not registered for composite command, or access right was not obtained.	Register items to read before attempting batch read, or obtain access right.
20	Could not create I/O table	Unrecognized Remote I/O Unit, too many I/O words, or word duplication used.	Check the Remote I/O System, the number of I/O words, and the words used.
21	Not executable due to CPU Unit CPU error (See note.)	The command cannot be executed because a CPU error has occurred in the CPU Unit.	Cycle the CPU Unit's power supply.
23	User memory protected	The UM is read-protected or write-protected.	Clear write-protection by setting pin 1 of the DIP switch on the front of the CPU Unit to OFF. Alternatively, clear the CPU Unit's password-protection using CX-Programmer.
A3	Aborted due to FCS error in transmission data	An FCS error occurred in the second or later frame, or there were two bytes or less of data in an intermediate or final frame for multiple writing.	Correct the command data and transfer the command again.
A4	Aborted due to format error in transmission data	The command format did not match the number of bytes in the second or later frame.	
A5	Aborted due to entry number data error in transmission data	There was an entry number data error in the second or later frame, a data length error, or data was not set in hexadecimal.	
A8	Aborted due to frame length error in transmission data	The length of the second and later frames exceeded the maximum of 128 bytes.	

Note Occurs only for a Serial Communications Unit/Board.

A response will not be received with some errors, regardless of the command. These errors are listed in the following table.

Error	PLC operation
A command is received with eight bytes or less from the @ to the delimiter.	The initial command (4 bytes) executes the initial processing. Other commands are discarded.
Parity, overrun, or framing error during command reception. (Same even for commands address to other Units.)	The Communications Error Flag will be turned ON, an error code will be registered, and receptions will be reset. (The error will be cleared automatically if communications restart normally.)
A command is received that does not have the @ character at the beginning of the first frame.	The command is discarded.
Incorrect node number (Not a local unit, BCD, or over 31)	The command is discarded.
An LF code is received after the delimiter.	The LF code is discarded.

Command/End Code Table The following table shows which end codes can be returned for each C-mode command.

Header	Possible End Codes																	Comments
RR	00					13	14	15		18			21						---
RL	00					13	14	15		18			21						---
RH	00					13	14	15		18			21						---
RC	00					13	14	15		18			21						---
RG	00					13	14	15		18			21						---
RD	00					13	14	15		18			21						---
RJ	00					13	14	15		18			21						---
RE	00					13	14	15		18			21						---
WR	00	01				13	14	15		18			21		A3	A4	A5	A8	---
WL	00	01				13	14	15		18			21		A3	A4	A5	A8	---
WH	00	01				13	14	15		18			21		A3	A4	A5	A8	---
WC	00	01				13	14	15		18			21		A3	A4	A5	A8	---
WD	00	01				13	14	15		18			27		A3	A4	A5	A8	---
WJ	00	01				13	14	15		18			21		A3	A4	A5	A8	---
WE	00	01				13	14	15		18			21		A3	A4	A5	A8	---
R#	00					13	14	15	16	18			21	23					---
R$	00				04	13	14	15	16	18			21	23					---
R%	00				04	13	14	15	16	18			21	23					---
W#	00	01			04	13	14	15	16	18	19		21	23					---
W$	00	01			04	13	14	15	16	18	19		21	23					---
W%	00	01			04	13	14	15	16	18	19		21	23					---
MS	00					13	14			18			21						---
SC	00					13	14	15		18	19		21						---
MF	00	01	02			13	14	15		18	19		21						---
KS	00	01				13	14	15		18			21						---
KR	00	01				13	14	15		18			21						---
FK	00	01				13	14	15		18			21						---
KC	00	01				13	14	15		18			21						---
MM	00					13	14			18			21						---
TS						13	14			18			21						---
RP	00					13	14			18	19		21	23					---
WP	00	01	02			13	14	15		18	19		21	23	A3	A4	A5	A8	---
MI	00	01	02	03		13	14			18	19	20							---
QQMR	00					13	14	15		18			21		A3	A4	A5	A8	---
QQIR	00					13	14			18	19								---
XZ	---																		No response
**	---																		No response
IC	---																		No end code

4-3 C-mode Command Details

4-3-1 About this Section

With C-mode command and response formats, a single character is indicated by a single box. Each character is sent and received as a single byte in ASCII.

Execution Conditions The *Execution Conditions* table at the beginning of the description of each command provides the following information.

Commands, Single
Single command frames are used when there are 131 characters or less.

Commands, Multiple
Tells whether the command can be spit into multiple frames when there are more than 131 characters.

Responses, Single
Single response frames are used when there are 131 characters or less.

Responses, Multiple
Tells whether the response can be spit into multiple frames when there are more than 131 characters.

PLC Modes, RUN
Tells if the CPU Unit will accept the command when the CPU Unit is in RUN mode.

PLC Modes, MONITOR
Tells if the CPU Unit will accept the command when the CPU Unit is in MONI-TOR mode.

PLC Modes, PROGRAM
Tells if the CPU Unit will accept the command when the CPU Unit is in PRO-GRAM mode.

UM Area, Write-protected
Tells if the CPU Unit will accept the command when the UM Area is write-protected using the DIP switch on the CPU Unit.

UM Area, Read-protected
Tells if the CPU Unit will accept the command when the UM Area is read-protected using a Programming Device.

Note   1.   WR Area words cannot be read or written using C-mode commands.

2. Timers 2048 to 4095 and counters 2048 to 4095 cannot be read or written and their SV cannot be read or written using C-mode commands.

3. D10000 to D32767 and E10000 to E32767 cannot be read or written using C-mode commands.

4. SV can be read and written only in cyclic task 0. Also, timer SV can be read and written only when the timer number is not indirectly addressed.

4-3-2 CIO AREA READ – – RR

Reads the contents of the specified number of CIO words starting from the specified word.

Command Format

Unit No. (BCD)   Header code   Beginning word (0000 to 6143)   No. of words (0001 to 6144)   FCS   Terminator

Response Format

Unit No. (BCD)   Header code   End code   Read data (1 word)   FCS   Terminator
Read data (for number of words read)

Limitations   The text portion of the response's first frame can contain up to 30 words. If more than 30 words are read, the data will be returned in multiple frames.

In the second and later frames, the text portion of the response can contain up to 31 words.

The INITIALIZE and ABORT commands can be sent instead of the delimiter for multiple responses for this command. If other commands are sent, they will be treated as delimiters.

Execution Conditions

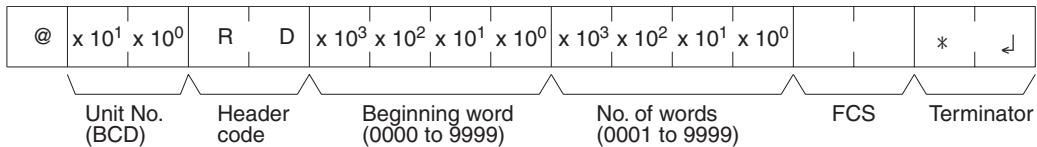| Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	**No**	OK	OK	OK	OK	OK	OK	OK

End Codes   An end code of 14 (format error) will be returned if the length of the command is incorrect and an end code of 15 (entry number data error) will be returned if the specified words exceed the data area boundaries, or are not specified in BCD, or if the number of words to read is 0.

End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-3   LR AREA READ – – RL

Treats CIO 1000 to CIO 1199 as a data link area and reads the contents of the specified number of words starting from the specified word.

Command Format

| @ | $x\ 10^1$ $x\ 10^0$ | R | L | $x\ 10^3$ $x\ 10^2$ $x\ 10^1$ $x\ 10^0$ | $x\ 10^3$ $x\ 10^2$ $x\ 10^1$ $x\ 10^0$ | | * | ↵ |

Unit No. (BCD)   Header code   Beginning word (0000 to 0199)   No. of words (0001 to 0200)   FCS   Terminator

Response Format

| @ | $x\ 10^1$ $x\ 10^0$ | R | L | $x\ 16^1$ $x\ 16^0$ | $x\ 16^3$ $x\ 16^2$ $x\ 16^1$ $x\ 16^0$ | | * | ↵ |

Unit No. (BCD)   Header code   End code   Read data (1 word)   FCS   Terminator

Read data (for number of words read)

Limitations   The text portion of the response's first frame can contain up to 30 words. If more than 30 words are read, the data will be returned in multiple frames.

In the second and later frames, the text portion of the response can contain up to 31 words.

The INITIALIZE and ABORT commands can be sent instead of the delimiter for multiple responses for this command. If other commands are sent, they will be treated as delimiters.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	**No**	OK	OK	OK	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect and an end code of 15 (entry number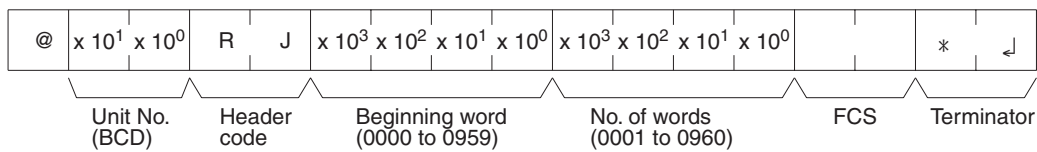 data error) will be returned if the specified words exceed the data area boundaries, or are not specified in BCD, or if the number of words to read is 0.

End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

Note The command is provided for compatibility with previous models. We recommend using CIO AREA READ (RR) whenever possible.

4-3-4   HR AREA READ – – RH

Reads the contents of the specified number of HR words starting from the specified word.

Command Format

| @ | $\times 10^1$ $\times 10^0$ | R | H | $\times 10^3$ $\times 10^2$ $\times 10^1$ $\times 10^0$ | $\times 10^3$ $\times 10^2$ $\times 10^1$ $\times 10^0$ | | $*$ | ↵ |

Unit No. (BCD)   Header code   Beginning word (0000 to 0511)   No. of words (0001 to 0512)   FCS   Terminator

Response Format

| @ | $\times 10^1$ $\times 10^0$ | R | H | $\times 16^1$ $\times 16^0$ | $\times 16^3$ $\times 16^2$ $\times 16^1$ $\times 16^0$ | | $*$ | ↵ |

Unit No. (BCD)   Header code   End code   Read data (1 word)   FCS   Terminator
Read data (for number of words read)

Limitations

The text portion of the response's first frame can contain up to 30 words. If more than 30 words are read, the data will be returned in multiple frames.

In the second and later frames, the text portion of the response can contain up to 31 words.

The INITIALIZE and ABORT commands can be sent instead of the delimiter for multiple responses for this command. If other commands are sent, they will be treated as delimiters.

Execution Conditions

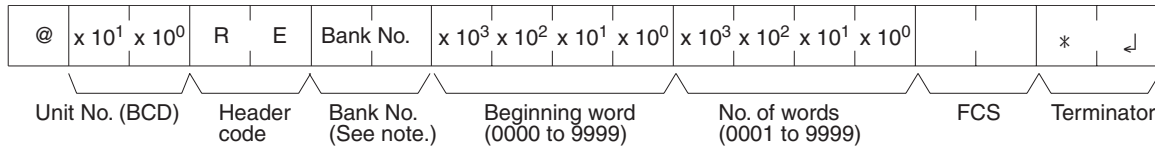| Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	**No**	OK	OK	OK	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect and an end code of 15 (entry number data error) will be returned if

the specified words exceed the data area boundaries, or are not specified in BCD, or if the number of words to read is 0.

End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-5   TIMER/COUNTER PV READ – – RC

Reads the contents of the specified number of timer/counter PVs (present values T0000 to T2047 or C0000 to C2047) starting from the specified timer/counter.

Command Format
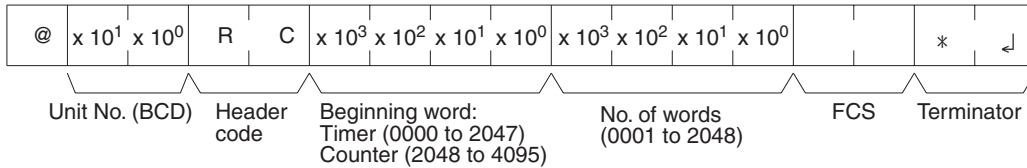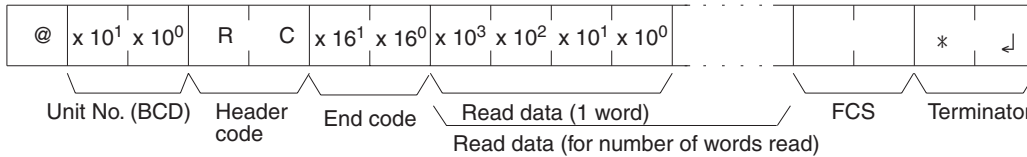
@	x 10^1	x 10^0	R	C	x 10^3	x 10^2	x 10^1	x 10^0	x 10^3	x 10^2	x 10^1	x 10^0		*	↵

Unit No. (BCD) Header code Beginning word: Timer (0000 to 2047) Counter (2048 to 4095) No. of words (0001 to 2048) FCS Terminator

Response Format

@	x 10^1	x 10^0	R	C	x 16^1	x 16^0	x 10^3	x 10^2	x 10^1	x 10^0	. . . .		*	↵

Unit No. (BCD) Header code End code Read data (1 word) FCS Terminator
Read data (for number of words read)

Limitations

The text portion of the response's first frame can contain up to 30 words. If more than 30 words are read, the data will be returned in multiple frames.

In the second and later frames, the text portion of the response can contain up to 31 words.

The INITIALIZE and ABORT commands can be sent instead of the delimiter for multiple responses for this command. If other commands are sent, they will be treated as delimiters.

Designate 0000 to 2047 for timers and 2048 to 4095 for counters (add 2048 to the actual counter number).

Timers T2048 to T4095 and counters T2048 to T4095 cannot be read.

Commands are divided among timers and counters for execution. If an attempt is made to designate across timers and counters, an end code of 15 (entry number data error) will be returned.

Execution Conditions

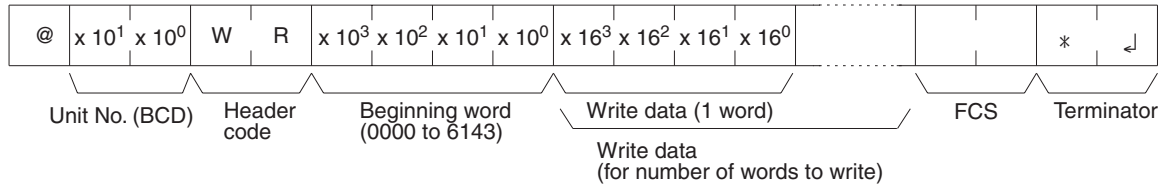| Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	**No**	OK	OK	OK	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect and an end code of 15 (entry number data error) will be returned if

the specified words exceed the data area boundaries, or are not specified in BCD, or if the number of words to read is 0.

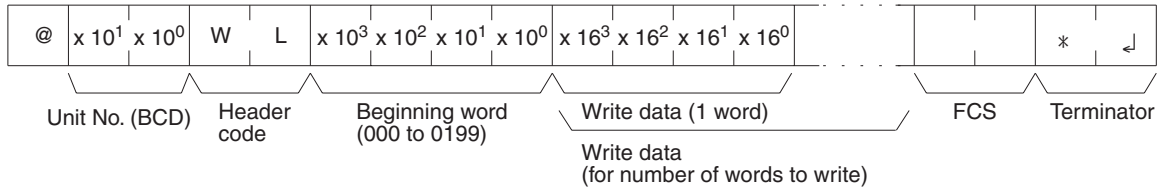| End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-6 TIMER/COUNTER STATUS READ – – RG

Reads the ON/OFF status of the Completion Flags of the specified number of timers/counters starting from the designated word (T0000 to T2047 or C0000 to C2047).

Command Format
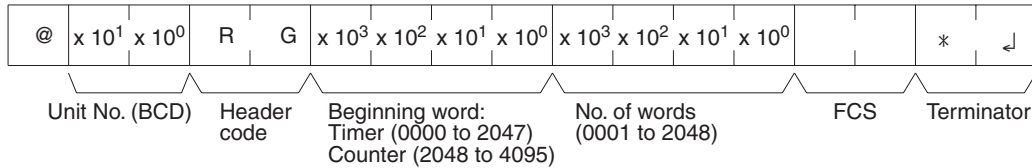
Response Format
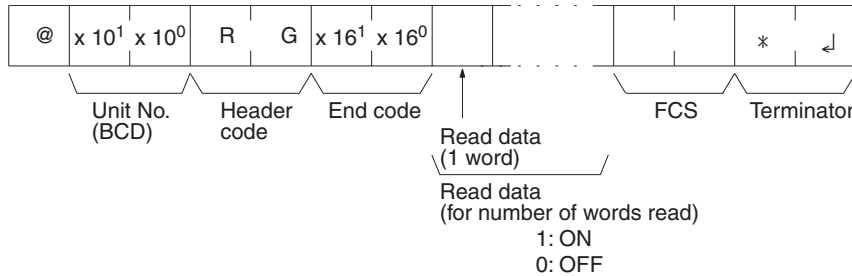
Limitations

The number of words per frame for response data is different to that for C-series Units. For details refer to *2-4 Precautions when Reusing Programs from Earlier Models*.

The text portion of the response's first frame can contain up to 121 words. If more than 121 words are read, the data will be returned in multiple frames.

In the second and later frames, the text portion of the response can contain up to 124 words.

The INITIALIZE and ABORT commands can be sent instead of the delimiter for multiple responses for this command. If other commands are sent, they will be treated as delimiters.

Designate 0000 to 2047 for timers and 2048 to 4095 for counters (add 2048 to the actual counter number).

Timers T2048 to T4095 and counters C2048 to C4095 cannot be read.

Commands are divided with regard to timers and counters. If an attempt is made to designate across timers and counters, an end code of 15 (entry number data error) will be returned.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	**No**	OK	OK	OK	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect and an end code of 15 (entry number data error) will be returned if the specified words exceed the data area boundaries, or are not specified in BCD, or if the number of words to read is 0.

End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-7   DM AREA READ – – RD

Reads the contents of the specified number of DM words starting from the specified word (D00000 to D09999).

Command Format
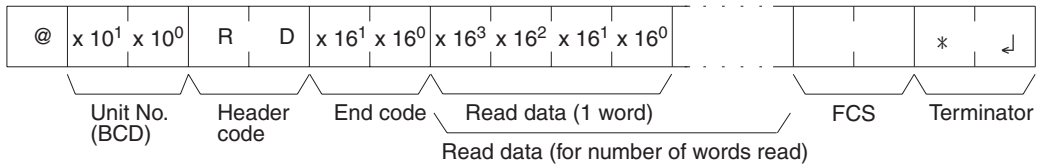
| @ | x 10^1 x 10^0 | R   D | x 10^3 x 10^2 x 10^1 x 10^0 | x 10^3 x 10^2 x 10^1 x 10^0 | | ∗ | ↵ |

Unit No. (BCD)   Header code   Beginning word (0000 to 9999)   No. of words (0001 to 9999)   FCS   Terminator

Response Format

| @ | x 10^1 x 10^0 | R   D | x 16^1 x 16^0 | x 16^3 x 16^2 x 16^1 x 16^0 | | ∗ | ↵ |

Unit No. (BCD)   Header code   End code   Read data (1 word)   FCS   Terminator

Read data (for number of words read)

Limitations

The DM Area is comprised of D00000 to D32767, but the range that can be read by this command is D00000 to D09999.

The text portion of the response's first frame can contain up to 30 words. If more than 30 words are read, the data will be returned in multiple frames.

In the second and later frames, the text portion of the response can contain up to 31 words.

The INITIALIZE and ABORT commands can be sent instead of the delimiter for multiple responses for this command. If other commands are sent, they will be treated as delimiters.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	**No**	OK	OK	OK	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect and an end code of 15 (entry number data error) will be returned if
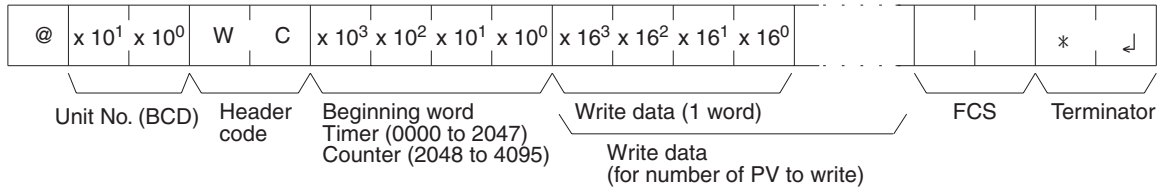
the specified words exceed the data area boundaries, or are not specified in BCD, or if the number of words to read is 0.

End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-8   AR AREA READ – – RJ

Reads the contents of the specified number of Auxiliary Area words (A000 to A959) starting from the specified word.

Command Format

@	$\times 10^1$ $\times 10^0$	R	J	$\times 10^3$ $\times 10^2$ $\times 10^1$ $\times 10^0$	$\times 10^3$ $\times 10^2$ $\times 10^1$ $\times 10^0$		*	↵
	Unit No. (BCD)	Header code		Beginning word (0000 to 0959)	No. of words (0001 to 0960)	FCS	Terminator	

Response Format

@	$\times 10^1$ $\times 10^0$	R	J	$\times 16^1$ $\times 16^0$	$\times 16^3$ $\times 16^2$ $\times 16^1$ $\times 16^0$		*	↵
	Unit No. (BCD)	Header code		End code	Read data (1 word)	FCS	Terminator	

Read data (for number of words read)

Limitations

The text portion of the response's first frame can contain up to 30 words. If more than 30 words are read, the data will be returned in multiple frames.

In the second and later frames, the text portion of the response can contain up to 31 words.

The INITIALIZE and ABORT commands can be sent instead of the delimiter for multiple responses for this command. If other commands are sent, they will be treated as delimiters.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	**No**	OK	OK	OK	OK	OK	OK	OK

End Codes

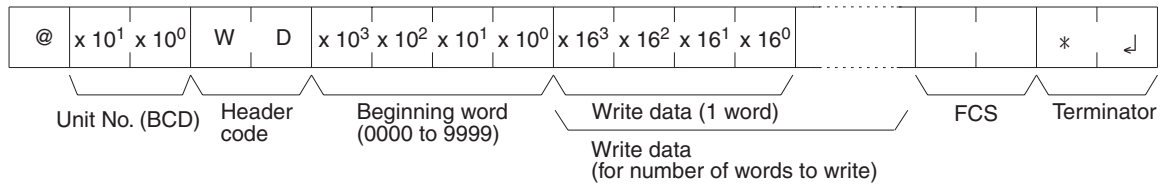An end code of 14 (format error) will be returned if the length of the command is incorrect and an end code of 15 (entry number data error) will be returned if the specified words exceed the data area boundaries, or are not specified in BCD, or if the number of words to read is 0.

End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-9   EM AREA READ – – RE

Reads the contents of the specified number of EM words (E00000 to E09999) starting from the specified word in the specified EM bank.

Command Format

| @ | x 10^1 | x 10^0 | R | E | Bank No. | x 10^3 | x 10^2 | x 10^1 | x 10^0 | x 10^3 | x 10^2 | x 10^1 | x 10^0 | | | ∗ | ↵ |

Unit No. (BCD)   Header code   Bank No. (See note.)   Beginning word (0000 to 9999)   No. of words (0001 to 9999)   FCS   Terminator

> **Note** Input 00, 01, or 0C to specify bank number 0, 1, or C. Input two spaces to specify the current bank.

Response Format

| @ | x 10^1 | x 10^0 | R | E | x 16^1 | x 16^0 | x 16^3 | x 16^2 | x 16^1 | x 16^0 | | | ∗ | ↵ |

Unit No. (BCD)   Header code   End code   Read data (1 word)   FCS   Terminator

Read data (for number of words read)
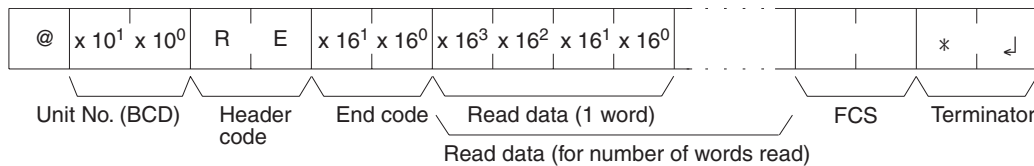
Limitations

A single bank of EM consists of E00000 to E32767, but the range that can be read by this command is E00000 to E09999.

The text portion of the response's first frame can contain up to 30 words. If more than 30 words are read, the data will be returned in multiple frames.

In the second and later frames, the text portion of the response can contain up to 31 words.

This command cannot be used to change the current bank number.

The INITIALIZE and ABORT commands can be sent instead of the delimiter for multiple responses for this command. If other commands are sent, they will be treated as delimiters.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	**No**	OK	OK	OK	OK	OK	OK	OK

End Codes

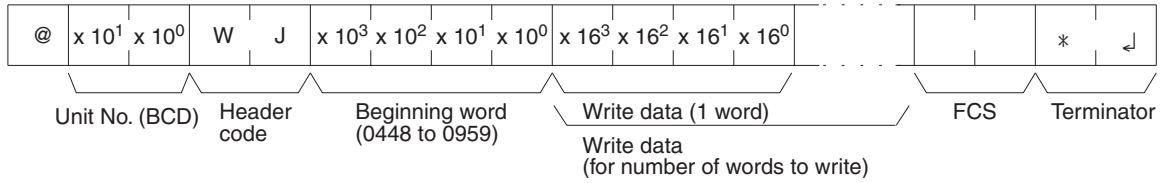An end code of 14 (format error) will be returned if the length of the command is incorrect and an end code of 15 (entry number data error) will be returned if the specified words exceed the data area boundaries, the specified words are not specified in BCD, or an invalid bank number is specified. An end code of 15 will also be returned if there are no banks and file memory access is not possible, or if the number of words to read is 0.

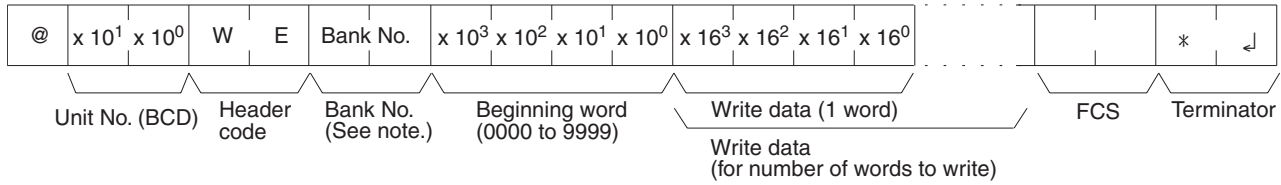| End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-10 CIO AREA WRITE – – WR

Writes data to the CIO Area (CIO 0000 to CIO 6143) starting from the specified word. Writing is done in word units.

Command Format

| @ | x 10¹ x 10⁰ | W R | x 10³ x 10² x 10¹ x 10⁰ | x 16³ x 16² x 16¹ x 16⁰ | .... | | * | ↵ |

Unit No. (BCD)   Header code   Beginning word (0000 to 6143)   Write data (1 word)   FCS   Terminator

Write data (for number of words to write)

Response Format

| @ | x 10¹ x 10⁰ | W R | x 16¹ x 16⁰ | | * | ↵ |

Unit No. (BCD)   Header code   End code   FCS   Terminator

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	OK	OK	**No**	**No**	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect or the first word of write data is not in the first frame.

An end code of 15 (entry number data error) will be returned if the specified write data exceeds the data area boundaries, the beginning word is not specified in BCD, or the write data is not hexadecimal. (An end code of A5 will be returned instead of 15 for non-hexadecimal write data in multiple command frames.)

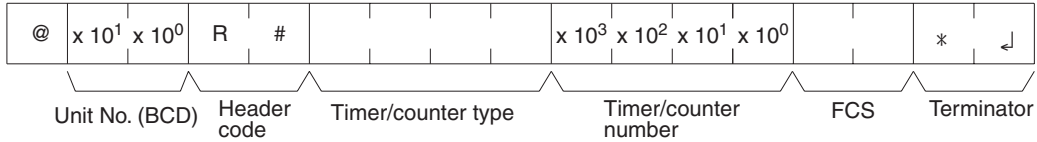| End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.
A3	Aborted due to FCS error in transmit data
A4	Aborted due to format error in transmit data
A5	Aborted due to entry number data error in transmit data
A8	Aborted due to frame length error in transmit data

4-3-11 LR AREA WRITE – – WL

Writes data to the Link Area (CIO 1000 to CIO 1199) starting from the specified word. Writing is done in word units.

Command Format

Unit No. (BCD) Header code Beginning word (000 to 0199) Write data (1 word) Write data (for number of words to write) FCS Terminator

Response Forma

Unit No. (BCD) Header code End code FCS Terminator

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	OK	OK	**No**	**No**	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect.

An end code of 15 (entry number data error) will be returned if the specified write data exceeds the data area boundary, the beginning word is not specified in BCD, or the write data is not hexadecimal. (An end code of A5 will be returned instead of 15 for non-hexadecimal write data in multiple command frames.)

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.
A3	Aborted due to FCS error in transmit data
A4	Aborted due to format error in transmit data
A5	Aborted due to entry number data error in transmit data
A8	Aborted due to frame length error in transmit data

Note The command is provided for compatibility with previous models. We recommend using CIO AREA WRITE (WR) whenever possible.

4-3-12   HR AREA WRITE – – WH

Writes data to the HR Area (H000 to H511) starting from the specified word. Writing is done in word units.

Command Format

| @ | x 10¹ | x 10⁰ | W | H | x 10³ x 10² x 10¹ x 10⁰ | x 16³ x 16² x 16¹ x 16⁰ | ... | | ∗ | ↵ |

- Unit No. (BCD)
- Header code
- Beginning word (0000 to 0511)
- Write data (1 word)
- Write data (for number of words to write)
- FCS
- Terminator

Response Format

| @ | x 10¹ | x 10⁰ | W | H | x 16¹ x 16⁰ | | ∗ | ↵ |

- Unit No. (BCD)
- Header code
- End code
- FCS
- Terminator

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	OK	OK	**No**	**No**	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect or the first word of write data is not in the first frame.

An end code of 15 (entry number data error) will be returned if the specified write data exceeds the data area boundary, the beginning word is not specified in BCD, or the write data is not hexadecimal. (An end code of A5 will be returned instead of 15 for non-hexadecimal write data in multiple command frames.)

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.
A3	Aborted due to FCS error in transmit data
A4	Aborted due to format error in transmit data
A5	Aborted due to entry number data error in transmit data
A8	Aborted due to frame length error in transmit data

4-3-13 TIMER/COUNTER PV WRITE – – WC

Writes the PVs (present values T0000 to T2047 or C0000 to C2047) of timers/counters starting from the specified word.

Command Format

| @ | x 10¹ | x 10⁰ | W | C | x 10³ | x 10² | x 10¹ | x 10⁰ | x 16³ | x 16² | x 16¹ | x 16⁰ | | | | ∗ | ↵ |

Unit No. (BCD)　Header code　Beginning word Timer (0000 to 2047) Counter (2048 to 4095)　Write data (1 word)　Write data (for number of PV to write)　FCS　Terminator

Response Format

| @ | x 10¹ | x 10⁰ | W | C | x 16¹ | x 16⁰ | | | ∗ | ↵ |

Unit No. (BCD)　Header code　End code　FCS　Terminator
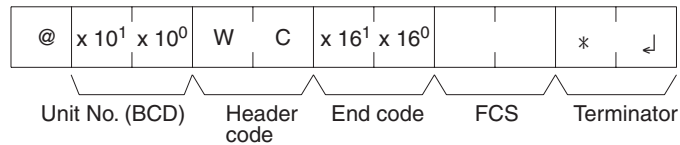
Limitations　Commands are divided with regard to timers and counters. If an attempt is made to designate across timers and counters, an end code of 15 (entry number data error) will be returned.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	OK	OK	**No**	**No**	OK	OK	OK	OK

End Codes　An end code of 14 (format error) will be returned if the length of the command is incorrect.

An end code of 15 (entry number data error) will be returned if the specified write data exceeds the data area boundary, the beginning word is not specified in BCD, or the write data is not hexadecimal. (An end code of A5 will be returned instead of 15 for non-hexadecimal write data in multiple command frames.)

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.
A3	Aborted due to FCS error in transmit data
A4	Aborted due to format error in transmit data
A5	Aborted due to entry number data error in transmit data
A8	Aborted due to frame length error in transmit data

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4-3-14 DM AREA WRITE – – WD

Writes data to the DM Area starting from the specified word (D00000 to D09999). Writing is done in word units.
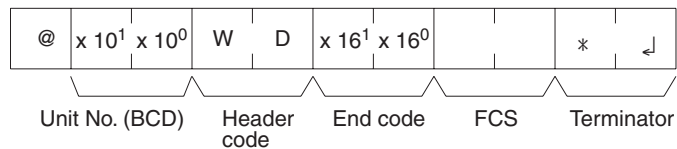
Command Format

Unit No. (BCD)   Header code   Beginning word (0000 to 9999)   Write data (1 word)   FCS   Terminator

Write data (for number of words to write)

Response Format

Unit No. (BCD)   Header code   End code   FCS   Terminator

Limitations The DM Area is comprised of D00000 to D32767, but the range that can be read by this command is D00000 to D09999.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	OK	OK	**No**	**No**	OK	OK	OK	OK

End Codes An end code of 14 (format error) will be returned if the length of the command is incorrect or the first word of write data is not in the first frame.

An end code of 15 (entry number data error) will be returned if the specified write data exceeds the data area boundary, the beginning word is not specified in BCD, or the write data is not hexadecimal. (An end code of A5 will be returned instead of 15 for non-hexadecimal write data in multiple command frames.)

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.
A3	Aborted due to FCS error in transmit data
A4	Aborted due to format error in transmit data
A5	Aborted due to entry number data error in transmit data
A8	Aborted due to frame length error in transmit data

4-3-15 AR AREA WRITE – – WJ

Writes data to the Auxiliary Area (A448 to A959) starting from the specified word. Writing is done in word units.

Command Format

Unit No. (BCD) Header code Beginning word (0448 to 0959) Write data (1 word) Write data (for number of words to write) FCS Terminator

Response Format

Unit No. (BCD) Header code End code FCS Terminator

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	OK	OK	**No**	**No**	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect or the first word of write data is not in the first frame.

An end code of 15 (entry number data error) will be returned if the specified write data exceeds the data area boundary, the beginning word is not specified in BCD, or the write data is not hexadecimal. (An end code of A5 will be returned instead of 15 for non-hexadecimal write data in multiple command frames.)

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.
A3	Aborted due to FCS error in transmit data
A4	Aborted due to format error in transmit data
A5	Aborted due to entry number data error in transmit data
A8	Aborted due to frame length error in transmit data

4-3-16 EM AREA WRITE – – WE

Writes data to the specified EM Area bank starting from the specified word (E00000 to E09999). Writing is done in word units.

Command Format

| @ | x 10¹ | x 10⁰ | W | E | Bank No. | x 10³ x 10² x 10¹ x 10⁰ | x 16³ x 16² x 16¹ x 16⁰ | | | | | ∗ | ↵ |

Unit No. (BCD) — Header code — Bank No. (See note.) — Beginning word (0000 to 9999) — Write data (1 word) — FCS — Terminator

Write data (for number of words to write)

Note Input 00 to 0C to specify bank number 0 to C. Input two spaces to specify the current bank.

Response Format

| @ | x 10¹ | x 10⁰ | W | E | x 16¹ | x 16⁰ | | ∗ | ↵ |

Unit No. (BCD) — Header code — End code — FCS — Terminator
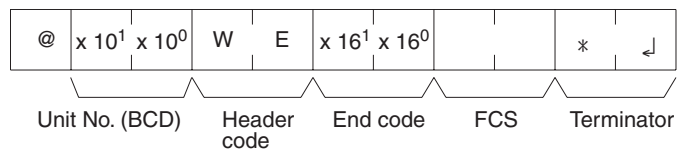
Limitations
The range that can be designated is E0000 to E9999. A single bank of EM consists of E00000 to E32767, but the range that can be written by this command is E00000 to E09999.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	OK	OK	**No**	**No**	OK	OK	OK	OK

End Codes
An end code of 14 (format error) will be returned if the length of the command is incorrect or the first word of write data is not in the first frame.

An end code of 15 (entry number data error) will be returned if the specified write data exceeds the data area boundary, the beginning word is not specified in BCD, or the write data is not hexadecimal. An end code of 15 will also be returned if there are no banks and file memory access is not possible. (An end code of A5 will be returned instead of 15 for non-hexadecimal write data in multiple command frames.)

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.
A3	Aborted due to FCS error in transmit data
A4	Aborted due to format error in transmit data
A5	Aborted due to entry number data error in transmit data
A8	Aborted due to frame length error in transmit data

4-3-17 TIMER/COUNTER SV READ 1 – – R#

Reads the constant SV (4 digits BCD) written in the operands of designated timer/counter instructions from cyclic task 0. If there are multiple timer/counter instructions designated in cyclic task 0, TIMER/COUNTER SV READ 1 will read the SV of the designated instruction with the lowest program address.

Command Format

| @ | x 10^1 | x 10^0 | R | # | | | | | | x 10^3 | x 10^2 | x 10^1 | x 10^0 | | | $*$ | ↵ |

Unit No. (BCD)   Header code   Timer/counter type   Timer/counter number   FCS   Terminator

Instruction name	Timer/counter type				Timer/counter number (BCD)
	Char- acter 1	Char- acter 2	Char- acter 3	Char- acter 4	
HIGH-SPEED COUNTER WAIT	T	M	H	W	0000 to 2047
TIMER WAIT	T	I	M	W	
COUNTER WAIT	C	N	T	W	
HIGH-SPEED TIMER	T	I	M	H	
TOTALIZING TIMER	T	T	I	M	
REVERSIBLE COUNTER	C	N	T	R	
TIMER	T	I	M	(SP)	
COUNTER	C	N	T	(SP)	

Note "SP" represents a space (20 Hex).

Response Format

| @ | x 10^1 | x 10^0 | R | # | x 16^1 | x 16^0 | x 10^3 | x 10^2 | x 10^1 | x 10^0 | | | $*$ | ↵ |

Unit No. (BCD)   Header code   End code   SV of instruction designated by command (constant)   FCS   Terminator

Parameters

Timer/Counter Type (Command)
Designate in ASCII characters the type of TC instruction for reading the constant SV.

Timer Counter Number (Command)
Designate in four digits (BCD) the timer/counter number for reading the constant SV.

Limitations

Timers T2048 to T4095 and counters C2048 to C4095 cannot be read.

The second word of the instruction must be a constant.

If there are multiple relevant instructions in the UM Area, a search will be conducted from program address 0, and the first instruction found will be read.

SV can be read only from cyclic task 0.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	**No**	OK	**No**	OK	OK	OK	OK	**No**

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect.

An end code of 15 (entry number data error) will be returned if the timer/counter type or timer/counter number is out of range (including hexadecimal data).
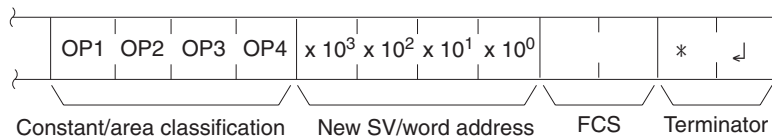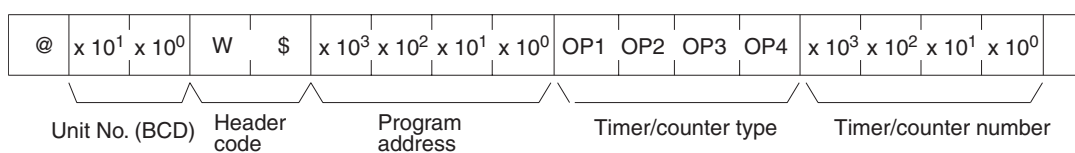
An end code of 16 (command not supported) will be returned if the specified instruction does not exist in the UM Area.

End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
15	Entry number data error
16	Command not supported
18	Frame length error
21	Not executable due to CPU Unit CPU error.
23	User memory protected

4-3-18 TIMER/COUNTER SV READ 2 – – R$

From the specified program address onwards in cyclic task 0, TIMER/COUNTER SV READ 2 finds the specified timer/counter instruction and reads the 4-digit constant SV that is set or the word address where the SV is stored.

Command Format

@	$x\,10^1$ $x\,10^0$	R	$	$x\,10^3$ $x\,10^2$ $x\,10^1$ $x\,10^0$	OP1 OP2 OP3 OP4	$x\,10^3$ $x\,10^2$ $x\,10^1$ $x\,10^0$		*	↵
	Unit No. (BCD)	Header code		Program address (BCD)	Timer/counter type	Timer/counter number (BCD)		FCS	Terminator

Instruction name	Timer/counter type				Timer/counter number (BCD)
	Char-acter 1	Char-acter 2	Char-acter 3	Char-acter 4	
HIGH-SPEED COUNTER WAIT	T	M	H	W	0000 to 2047
TIMER WAIT	T	I	M	W	
COUNTER WAIT	C	N	T	W	
HIGH-SPEED TIMER	T	I	M	H	
TOTALIZING TIMER	T	T	I	M	
REVERSIBLE COUNTER	C	N	T	R	
TIMER	T	I	M	(SP)	
COUNTER	C	N	T	(SP)	

Note "SP" represents a space (20 Hex).

Response Format

| @ | x 10¹ x 10⁰ | R | $ | x 16¹ x 16⁰ | OP1 OP2 OP3 OP4 | x 10³ x 10² x 10¹ x 10⁰ | | * | ↵ |

Unit No. (BCD) — Header code — End code — Constant/area classification — SV/word address — FCS — Terminator

Classification	Constant/area classification				SV or word address
	Character 1	**Character 2**	**Character 3**	**Character 4**	
Constant	C	O	N	(SP)	0000 to 9999
CIO	C	I	O	(SP)	0000 to 6143
AR	A	R	(SP)	(SP)	0000 to 0959
HR	H	R	(SP)	(SP)	0000 to 0511
WR	W	R	(SP)	(SP)	0000 to 0511
Timer	T	I	M	(SP)	0000 to 2047
Counter	C	N	T	(SP)	0000 to 2047
DM	D	M	(SP)	(SP)	0000 to 9999
DM (indirect)	D	M	*	(SP)	0000 to 9999
EM current bank	E	M	(SP)	(SP)	0000 to 9999
EM (indirect) current bank	E	M	*	(SP)	0000 to 9999
EM banks 0 to C	E	M	0 to C	(SP)	0000 to 9999
EM (indirect) banks 0 to C	E	M	0 to C	*	0000 to 9999
Data register	D	R	(SP)	(SP)	0000 to 0015
Index register (indirect)	,	I	R	(SP)	0000 to 0015

Note "SP" represents a space (20 Hex).

Parameters

Program Address (Command)
Designates the program address in four digits decimal (BCD) for beginning the search for the specified timer/counter.

Timer/Counter Type (Command)
Designate in ASCII characters the timer/counter instruction type for reading the constant SV or the word address in which it is stored.

Timer/Counter Number (Command)
Designate in four digits (BCD) the timer/counter instruction number for reading the constant SV or the word address in which it is stored. (Data register designation is not possible.)

Constant/Area Classification (Response)
The constant or I/O memory area classification is returned, in ASCII, to this parameter.

SV/Word Address (Response)
The constant SV or the word address in which it is stored is returned to this parameter.

Limitations

Timers T2048 to T4095 and counters C2048 to C4095 cannot be read.

The SV of the first timer/counter found after the designated program address will be read.

If the SV is outside of range for the timer/counter type or number, an end code of 16 (command not supported) will be returned.

If the SV is a DM or EM indirect address, only indirect BCD designations will be read and an end code of 16 (command not supported) will be returned if the indirect designation is not BCD.

SV can be read only from cyclic task 0.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	**No**	OK	**No**	OK	OK	OK	OK	**No**

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect.

An end code of 15 (entry number data error) will be returned if the program address is not specified in BCD or the operand/SV parameters are incorrect.

An end code of 16 (command not supported) will be returned if the specified instruction does not exist in the UM Area.

End code (Hex)	Contents
00	Normal completion
04	Address over
13	FCS error
14	Format error
15	Entry number data error
16	Command not supported
18	Frame length error
21	Not executable due to CPU Unit CPU error.
23	User memory protected

4-3-19 TIMER/COUNTER SV READ 3 – – R%

From the specified program address onwards in cyclic task 0, TIMER/COUNTER SV READ 3 finds the specified TC instruction and reads the constant SV that is set or the word address where the SV is stored. The SV that is read is a 4-digit decimal number (BCD).

Command Format

| @ | x 10¹ | x 10⁰ | R | % | x 10⁵ | x 10⁴ | x 10³ | x 10² | x 10¹ | x 10⁰ | OP1 | OP2 | OP3 | OP4 | x 10³ | x 10² | x 10¹ | x 10⁰ |

Unit No. (BCD) — Header code — Program address — Timer/counter type — Timer/counter number

| | | * | ↵ |

FCS — Terminator

Instruction name	Timer/counter type				Timer/counter number
	Character 1	Character 2	Character 3	Character 4	
HIGH-SPEED TIMER WAIT	T	M	H	W	0000 to 2047
TIMER WAIT	T	I	M	W	
COUNTER WAIT	C	N	T	W	
HIGH-SPEED TIMER	T	I	M	H	
TOTALIZING TIMER	T	T	I	M	
REVERSIBLE COUNTER	C	N	T	R	
TIMER	T	I	M	(SP)	
COUNTER	C	N	T	(SP)	

Note "SP" represents a space (20 Hex).

Response Format

| @ | x 10¹ | x 10⁰ | R | % | x 16¹ | x 16⁰ | OP1 | OP2 | OP3 | OP4 | x 10³ | x 10² | x 10¹ | x 10⁰ | | | * | ↵ |

Unit No. (BCD) — Header code — End code — Constant/area classification — SV/word address — FCS — Terminator

Classification	Constant/area classification				Constant or word address
	Character 1	Character 2	Character 3	Character 4	
Constant	C	O	N	(SP)	0000 to 9999
CIO	C	I	O	(SP)	0000 to 6143
AR	A	R	(SP)	(SP)	0000 to 0959
HR	H	R	(SP)	(SP)	0000 to 0511
WR	W	R	(SP)	(SP)	0000 to 0511
Timer	T	I	M	(SP)	0000 to 2047
Counter	C	N	T	(SP)	0000 to 2047
DM	D	M	(SP)	(SP)	0000 to 9999
DM (indirect)	D	M	*	(SP)	0000 to 9999
EM current bank	E	M	(SP)	(SP)	0000 to 9999
EM (indirect) current bank	E	M	*	(SP)	0000 to 9999
EM banks 0 to C	E	M	0 to C	(SP)	0000 to 9999
EM (indirect) banks 0 to C	E	M	0 to C	*	0000 to 9999
Data register	D	R	(SP)	(SP)	0000 to 0015
Index register (indirect)	,	I	R	(SP)	0000 to 0015

Note "SP" represents a space (20 Hex).

Parameters

Program Address (Command)
Designates the program address in six digits decimal (BCD) for beginning the search for the specified timer/counter.

Timer/Counter Type (Command)
Designate the timer/counter instruction type for reading the constant SV or the word address in which it is stored.

Timer/Counter Number (Command)
Designate the timer/counter instruction number for reading the constant SV or the word address in which it is stored. (Index register designation is not possible.)

Constant/Area Classification (Response)
The constant or I/O memory area classification is returned, in ASCII, to this parameter.

SV/Word Address (Response)
The constant SV or the word address in which it is stored is returned to this parameter.

Limitations

Timers T2048 to T4095 and counters C2048 to C4095 cannot be read.

The SV of the first timer/counter found after the designated program address will be read.

If the SV is outside of range for the timer/counter type or number, an end code of 16 (command not supported) will be returned.

If the SV is a DM or EM indirect address, only indirect BCD designations will be read and an end code of 16 (command not supported) will be returned if the indirect designation is not BCD.

SV can be read only from cyclic task 0.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	**No**	OK	**No**	OK	OK	OK	OK	**No**

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect.

An end code of 15 (entry number data error) will be returned if the program address is not specified in BCD, or if the timer/counter type or number is out of range (including hexadecimal data).

An end code of 16 (command not supported) will be returned if the specified instruction does not exist in the program.

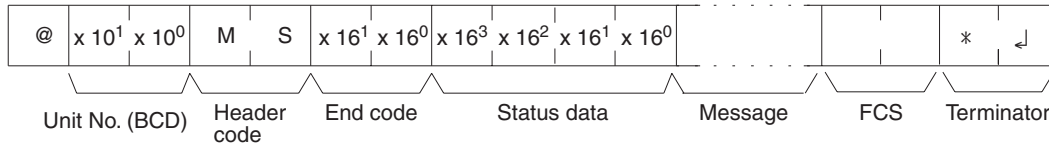| End code (Hex)	Contents
00	Normal completion
04	Address over
13	FCS error
14	Format error
15	Entry number data error
16	Command not supported
18	Frame length error
21	Not executable due to CPU Unit CPU error.
23	User memory protected

4-3-20 TIMER/COUNTER SV CHANGE 1 – – W#

Changes the SV of the designated timer/counter instruction to a new constant SV.

Command Format

| @ | x 10¹ x 10⁰ | W | # | OP1 OP2 OP3 OP4 | x 10³ x 10² x 10¹ x 10⁰ | x 10³ x 10² x 10¹ x 10⁰ | | ∗ | ↵ |

Unit No. (BCD) — Header code — Timer/counter type — Timer/counter number — SV (0000 to 9999 (BCD)) — FCS — Terminator

Instruction name	Timer/counter type				Timer/counter number (BCD)
	Char-acter 1	Char-acter 2	Char-acter 3	Char-acter 4	
HIGH-SPEED TIMER WAIT	T	M	H	W	0000 to 2047
TIMER WAIT	T	I	M	W	
COUNTER WAIT	C	N	T	W	
HIGH-SPEED TIMER	T	I	M	H	
TOTALIZING TIMER	T	T	I	M	
REVERSIBLE COUNTER	C	N	T	R	
TIMER	T	I	M	(SP)	
COUNTER	C	N	T	(SP)	

Note "SP" represents a space (20 Hex).

Response Format

| @ | x 10¹ x 10⁰ | W | # | x 16¹ x 16⁰ | | ∗ | ↵ |

Unit No. (BCD) — Header code — End code — FCS — Terminator

Parameters

Timer/Counter Type (Command)
Designate the timer/counter instruction type for changing the constant SV.

Timer/Counter Number (Command)
Designate in four digits BCD the timer/counter instruction number for changing the constant SV. (Index register designation is not possible.)

New Constant SV (Command)
Designate the new constant SV in four digits hexadecimal.

Limitations

Timers T2048 to T4095 and counters C2048 to C4095 cannot be read.

The command cannot be executed unless the SV is a constant.

If there are multiple relevant instructions in cyclic task 0, a search will be conducted from program address 0, and the first instruction found will be read.

The SV can be changed only in cyclic task 0.

If the SV is a DM or EM indirect address, only indirect BCD designations will be read and an end code of 16 (command not supported) will be returned if the indirect designation is not BCD.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	No	OK	No	No	OK	OK	No	No

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect.

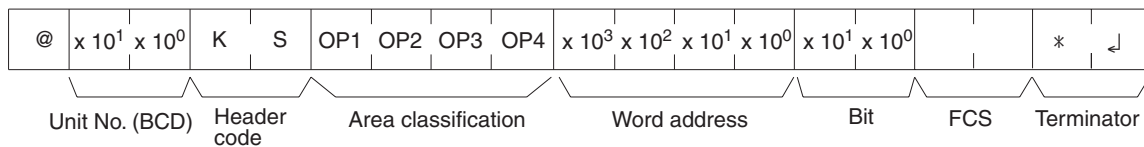An end code of 15 (entry number data error) will be returned if the program address is not specified in BCD, or if the timer/counter type or number is out of range (including hexadecimal data).

An end code of 16 (command not supported) will be returned if the specified instruction does not exist in the UM Area.

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
04	Address over
13	FCS error
14	Format error
15	Entry number data error
16	Command not supported
18	Frame length error
19	Not executable
21	Not executable due to CPU Unit CPU error.
23	User memory protected

4-3-21 TIMER/COUNTER SV CHANGE 2 – – W$

From the specified program address onwards in cyclic task 0, TIMER/ COUNTER SV CHANGE 2 finds the specified timer/counter instruction and changes the 4-digit constant SV (BCD) that is set, or the word address where the SV is stored, to a newly designated constant SV or storage word address.

Command Format

Instruction name	Timer/counter type				Timer/counter number
	Char-acter 1	Char-acter 2	Char-acter 3	Char-acter 4	
HIGH-SPEED TIMER WAIT	T	M	H	W	0000 to 2047
TIMER WAIT	T	I	M	W	
COUNTER WAIT	C	N	T	W	
HIGH-SPEED TIMER	T	I	M	H	
TOTALIZING TIMER	T	T	I	M	
REVERSIBLE COUNTER	C	N	T	R	
TIMER	T	I	M	(SP)	
COUNTER	C	N	T	(SP)	

Note "SP" represents a space (20 Hex).

Classification	Constant/area classification				SV or word address (BCD)
	Charac-ter 1	Charac-ter 2	Charac-ter 3	Charac-ter 4	
Constant	C	O	N	(SP)	0000 to 9999
CIO	C	I	O	(SP)	0000 to 6143
AR	A	R	(SP)	(SP)	0000 to 0959
HR	H	R	(SP)	(SP)	0000 to 0511
WR	W	R	(SP)	(SP)	0000 to 0511
Timer	T	I	M	(SP)	0000 to 2047
Counter	C	N	T	(SP)	0000 to 2047
DM	D	M	(SP)	(SP)	0000 to 9999
DM (indirect)	D	M	∗	(SP)	0000 to 9999
EM current bank	E	M	(SP)	(SP)	0000 to 9999
EM (indirect) current bank	E	M	∗	(SP)	0000 to 9999
EM banks 0 to C	E	M	0 to C	(SP)	0000 to 9999
EM (indirect) 0 to C	E	M	0 to C	∗	0000 to 9999
Data register	D	R	(SP)	(SP)	0000 to 0015
Index register	,	I	R	(SP)	0000 to 0015

Note "SP" represents a space (20 Hex).

Response Format

Unit No. (BCD)   Header code   End code   FCS   Terminator

Parameters

Program Address (Command)
Designate the program address in four digits decimal (BCD) for beginning the search for the specified timer/counter instruction.

Timer/Counter Type (Command)
Designate the timer/counter instruction type for changing the constant SV or the word address in which it is stored.

Timer/Counter Number (Command)
Designate the timer/counter instruction number for reading the constant SV. (Index register designation is not possible.) The range that can be designated is the same as for R#.

Constant/Area Classification (Command)
Designate the ASCII characters to express the new SV area classification or constant.

New SV/Word Address (Command)
Designate the newly set constant SV or the word address in which it is stored.

Limitations

Timers T2048 to T4095 and counters C2048 to C4095 cannot be read.

The SV of the first timer/counter found after the designated program address will be read.

If the SV is outside of range for the timer/counter type or number, an end code of 16 (command not supported) will be returned.

If the SV is a DM or EM indirect address, only indirect BCD designations will be read and an end code of 16 (command not supported) will be returned if the indirect designation is not BCD.

The SV can be changed only in cyclic task 0.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	**No**	OK	**No**	**No**	OK	OK	**No**	**No**

End Codes   An end code of 14 (format error) will be returned if the length of the command is incorrect.

An end code of 15 (entry number data error) will be returned if the program address is not BCD, or if the timer/counter type or number is out of range (including hexadecimal data).

An end code of 16 (command not supported) will be returned if the specified instruction does not exist in the UM Area.

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
04	Address over
13	FCS error
14	Format error
15	Entry number data error
16	Command not supported
18	Frame length error
19	Not executable
21	Not executable due to CPU Unit CPU error.
23	User memory protected

4-3-22 TIMER/COUNTER SV CHANGE 3 – – W%

From the specified program address onwards in cyclic task 0, TIMER/ COUNTER SV CHANGE 3 finds the specified timer/counter instruction and changes the 4-digit constant SV (BCD) that is set, or the word address where the SV is stored, to a newly designated constant SV or storage word address.

Command Format

Instruction name	Timer/counter type				Timer/counter number
	Char-acter 1	Char-acter 2	Char-acter 3	Char-acter 4	
HIGH-SPEED TIMER WAIT	T	M	H	W	0000 to 2047
TIMER WAIT	T	I	M	W	
COUNTER WAIT	C	N	T	W	
HIGH-SPEED TIMER	T	I	M	H	
TOTALIZING TIMER	T	T	I	M	
REVERSIBLE COUNTER	C	N	T	R	
TIMER	T	I	M	(SP)	
COUNTER	C	N	T	(SP)	

Note "SP" represents a space (20 Hex).

Classification	Constant/area classification				SV or word address (BCD)
	Charac-ter 1	Charac-ter 2	Charac-ter 3	Charac-ter 4	
Constant	C	O	N	(SP)	0000 to 9999
CIO	C	I	O	(SP)	0000 to 6143
AR	A	R	(SP)	(SP)	0000 to 0959
HR	H	R	(SP)	(SP)	0000 to 0511
WR	W	R	(SP)	(SP)	0000 to 0511
Timer	T	I	M	(SP)	0000 to 2047
Counter	C	N	T	(SP)	0000 to 2047
DM	D	M	(SP)	(SP)	0000 to 9999
DM (indirect)	D	M	∗	(SP)	0000 to 9999
EM current bank	E	M	(SP)	(SP)	0000 to 9999
EM (indirect) current bank	E	M	∗	(SP)	0000 to 9999
EM banks 0 to C	E	M	0 to C	(SP)	0000 to 9999
EM (indirect) 0 to C	E	M	0 to C	∗	0000 to 9999
Data register	D	R	(SP)	(SP)	0000 to 0015
Index register	,	I	R	(SP)	0000 to 0015

Note "SP" represents a space (20 Hex).

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Response Format

| @ | x 10¹ | x 10⁰ | W | % | x 16¹ | x 16⁰ | | ∗ | ↵ |

Unit No. (BCD)   Header code   End code   FCS   Terminator

Parameters

Program Address (Command)
Designate the program address in six digits decimal (BCD) for beginning the search for the specified timer/counter instruction.

Timer/Counter Type (Command)
Designate the timer/counter instruction type, in ASCII, for changing the constant SV or the word address in which it is stored.

Timer/Counter Number (Command)
Designate in four digits BCD the timer/counter instruction number for reading the constant SV. (Index register designation is not possible.)

Constant/Area Classification (Command)
Designate the ASCII characters to express the constant or area classification.

New SV/Word Address (Command)
Designate the newly set constant SV or the word address in which it is stored.

Limitations

Timers T2048 to T4095 and counters C2048 to C4095 cannot be changed.

If the SV is a DM or EM indirect address, only indirect BCD designations will be read and an end code of 16 (command not supported) will be returned if the indirect designation is not BCD.

The SV can be changed only in cyclic task 0.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	**No**	OK	**No**	**No**	OK	OK	**No**	**No**

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect.

An end code of 15 (entry number data error) will be returned if the program address is not BCD, or if the timer/counter type or number is out of range (including hexadecimal data).

An end code of 15 (entry number data error) will be returned if a constant or area classification is out of range (including hexadecimal data).

An end code of 16 (command not supported) will be returned if the specified instruction does not exist in the UM Area.

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
04	Address over
13	FCS error
14	Format error
15	Entry number data error
16	Command not supported
18	Frame length error
19	Not executable
21	Not executable due to CPU Unit CPU error.
23	User memory protected

4-3-23 STATUS READ – – MS

Reads the operating conditions (status) of the CPU Unit.

Command Format

Unit No. (BCD)   Header code   FCS   Terminator

Response Format

Unit No. (BCD)   Header code   End code   Status data   Message   FCS   Terminator
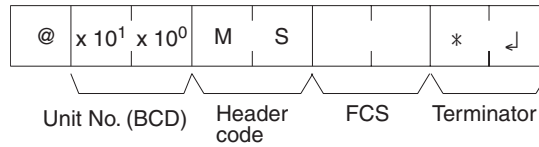
The message is attached only when there is a FAL/FALS message (always 16 characters)

"Status data" consists of four digits (two bytes) hexadecimal. The leftmost byte indicates the CPU Unit operation mode, and the rightmost byte indicates the size of the program area.
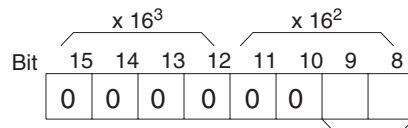
Bit		Operation mode
9	8	
0	0	PROGRAM mode
1	0	RUN mode
1	1	MONITOR mode

1: UM not write-protected
0: UM write-protected
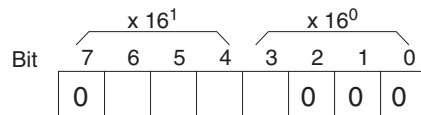
Bit			Program area
6	5	4	
0	0	1	10K steps
0	1	0	20K steps
0	1	1	30K steps
1	0	0	60K steps
1	0	1	120K steps
1	1	0	250K steps

Parameters

Message (Response)

The message for any FAL/FALS occurring during command execution will be returned.

Limitations RUN mode and MONITOR mode designations differ from those in STATUS WRITE.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	**No**	OK	**No**	OK	OK	OK	OK	OK

End Codes An end code of 14 (format error) will be returned if the length of the command is incorrect.

End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-24 STATUS CHANGE – – SC

Changes the CPU Unit operating mode.

Command Format

Unit No. (BCD) Header code Mode data FCS Terminator
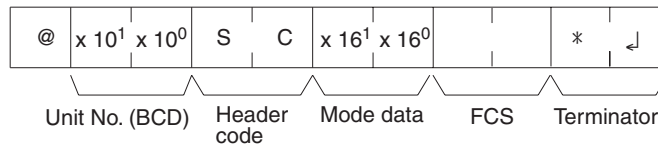
"Mode data" consists of two digits (one byte) hexadecimal. With the leftmost two bits, specify the CPU Unit operating mode. Set all of the remaining bits to "0."
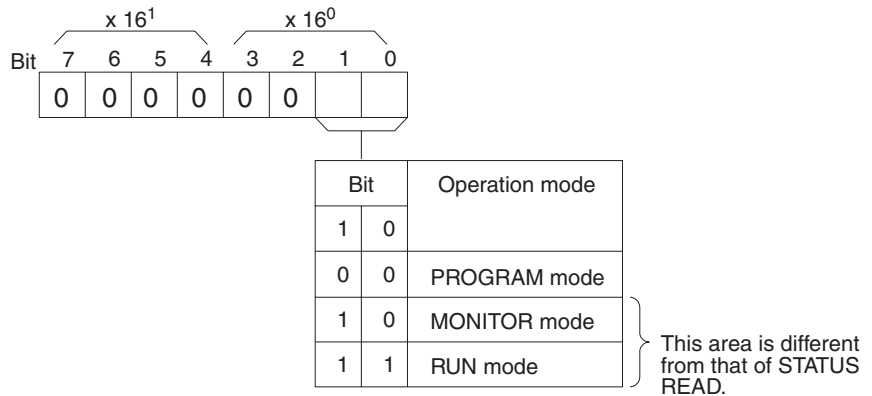
Bit		Operation mode
1	0	
0	0	PROGRAM mode
1	0	MONITOR mode
1	1	RUN mode

This area is different from that of STATUS READ.

Response Format

Unit No. (BCD) Header code End code FCS Terminator
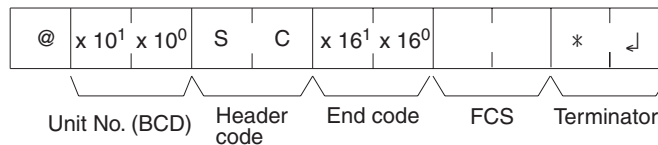
Limitations RUN mode and MONITOR mode designations differ from those in STATUS READ.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	**No**	OK	**No**	OK	OK	OK	OK	OK

End Codes　　　　　　　　An end code of 14 (format error) will be returned if the length of the command is incorrect.

An end code of 15 (entry number data error) will be returned if the mode data is out of range.

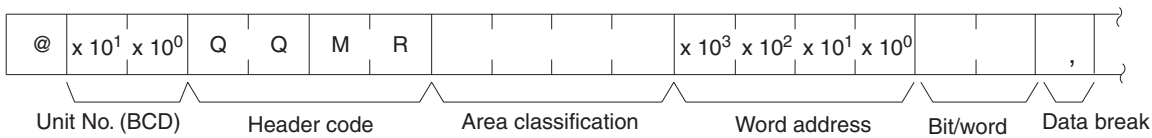| End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
19	Not executable
21	Not executable due to CPU Unit CPU error.

4-3-25 ERROR READ – – MF

Reads CPU Unit error information.

Command Format

@	x 10¹ x 10⁰	M F	x 10¹ x 10⁰		*	↵

Unit No. (BCD)　Header code　Error clear　FCS　Terminator
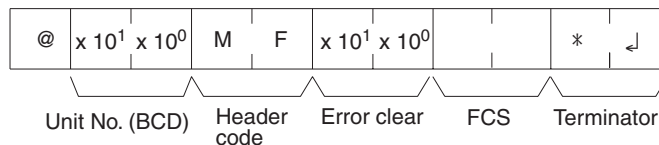
For the "error clear" parameter, specify 01 to clear errors and 00 to not clear errors (BCD).

Response Format

@	x 10¹ x 10⁰	M F	x 16¹ x 16⁰	x 16³ x 16² x 16¹ x 16⁰	x 16³ x 16² x 16¹ x 16⁰		*	↵

Unit No. (BCD)　Header code　End code　Error information (1st word)　Error information (2nd word)　FCS　Terminator

1st word

2nd word
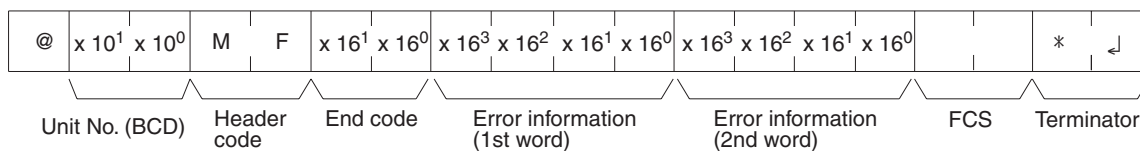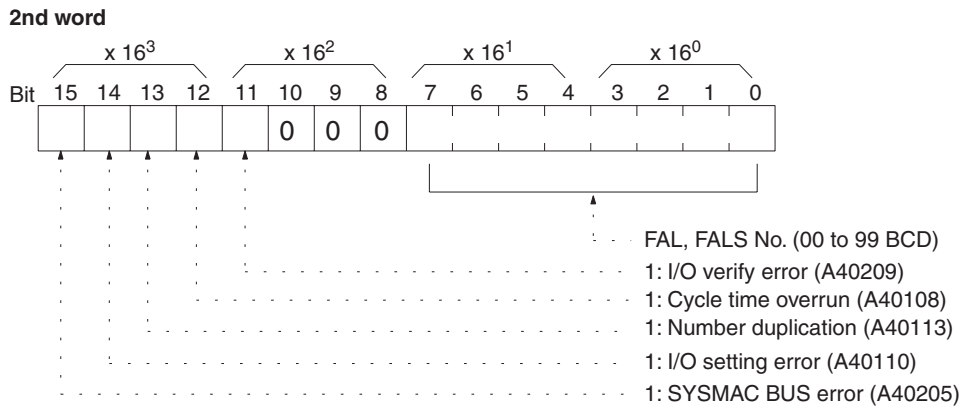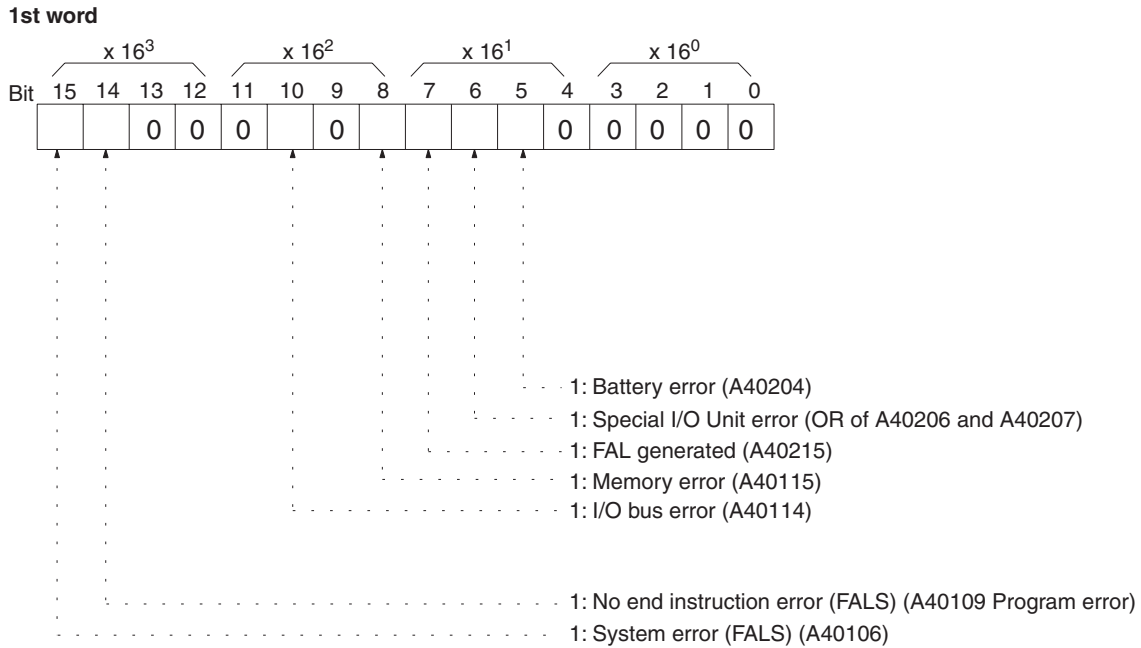
Limitations

Only FAL and FALS numbers 0 to 99 can be read. For numbers 100 to 511, FAL/FALS number 00 will be set.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	**No**	OK	**No**	OK	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect.

An end code of 15 (entry number data error) will be returned if the error clear parameter is not set to 00 or 01.

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
02	Not executable in MONITOR mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error

End code (Hex)	Contents
19	Not executable
21	Not executable due to CPU Unit CPU error.

4-3-26 FORCED SET – – KS

Force sets the operating status of operands. (Only one bit at a time can be force set.)

Command Format

@	x 10¹	x 10⁰	K	S	OP1	OP2	OP3	OP4	x 10³	x 10²	x 10¹	x 10⁰	x 10¹	x 10⁰			✳	↵

Unit No. (BCD)   Header code   Area classification   Word address   Bit   FCS   Terminator

Classifica-tion	Area classification				Word address	Bit
	Charac-ter 1	Charac-ter 2	Charac-ter 3	Charac-ter 4		
CIO	C	I	O	(SP)	0000 to 6143	00 to 15
LR	L	R	(SP)	(SP)	0000 to 0199	00 to 15
WR	W	R	(SP)	(SP)	0000 to 0511	00 to15
HR	H	R	(SP)	(SP)	0000 to 0511	00 to 15
Timer	T	I	M	(SP)	0000 to 2047	Always 00
Counter	C	N	T	(SP)	0000 to 2047	Always 00

Note "SP" represents a space (20 Hex).

Response Format

@	x 10¹	x 10⁰	K	S	x 16¹	x 16⁰			✳	↵

Unit No. (BCD)   Header code   End code   FCS   Terminator

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	No	OK	No	No	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect, or if the bit is designated as other than 00 by the TIM/CNT designation.

An end code of 15 (entry number data error) will be returned if the area classification, word address, or bit parameter setting is out of range (including hexadecimal data).

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

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4-3-27 FORCED RESET – – KR

Force resets the operating status of operands. (Only one bit at a time can be force set.)

Command Format

| @ | x 10¹ | x 10⁰ | K | R | OP1 | OP2 | OP3 | OP4 | x 10³ | x 10² | x 10¹ | x 10⁰ | x 10¹ | x 10⁰ | | | ∗ | ↵ |

Unit No. (BCD) — Header code — Area classification — Word address — Bit — FCS — Terminator

Classifica-tion	Area classification				Word address	Bit
	Charac-ter 1	Charac-ter 2	Charac-ter 3	Charac-ter 4		
CIO	C	I	O	(SP)	0000 to 6143	00 to 15
LR	L	R	(SP)	(SP)	0000 to 0199	00 to 15
WR	W	R	(SP)	(SP)	0000 to 0511	00 to15
HR	H	R	(SP)	(SP)	0000 to 0511	00 to 15
Timer	T	I	M	(SP)	0000 to 2047	Always 00
Counter	C	N	T	(SP)	0000 to 2047	Always 00

Note "SP" represents a space (20 Hex).

Response Format

| @ | x 10¹ | x 10⁰ | K | R | x 16¹ | x 16⁰ | | | ∗ | ↵ |

Unit No. (BCD) — Header code — End code — FCS — Terminator

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	**No**	OK	**No**	**No**	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect, or if the bit is designated as other than 00 by the TIM/CNT designation.

An end code of 15 (entry number data error) will be returned if the area classification, word address, or bit parameter setting is out of range (including hexadecimal data).

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-28 MULTIPLE FORCED SET/RESET – – FK

Force sets, resets, or cancels the operating status of operands. (Multiple bits can be simultaneously force set, reset, or canceled.)

Command Format
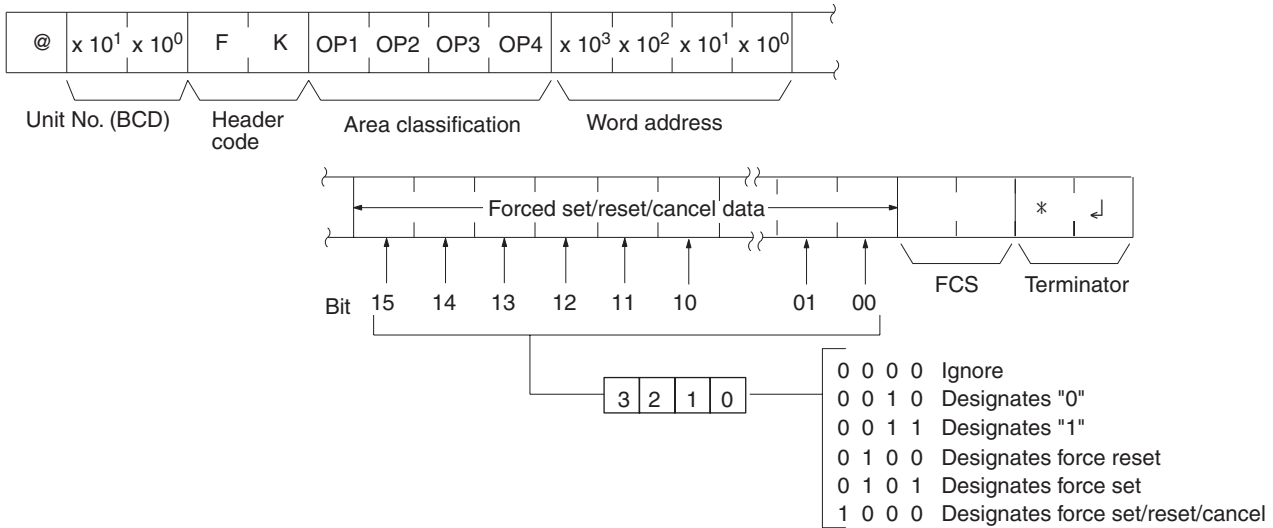
Classification	Area classification				Word address
	Character 1	Character 2	Character 3	Character 4	
CIO	C	I	O	(SP)	0000 to 6143
LR	L	R	(SP)	(SP)	0000 to 0199
WR	W	R	(SP)	(SP)	0000 to 0511
HR	H	R	(SP)	(SP)	0000 to 0511
Timer	T	I	M	(SP)	0000 to 2047
Counter	C	N	T	(SP)	0000 to 2047

Note "SP" represents a space (20 Hex).

Response Format
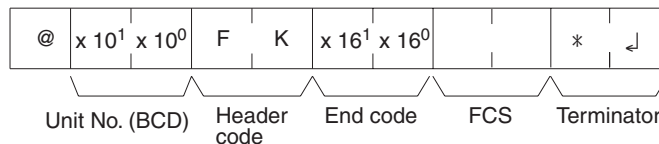
Limitations   Only 15 timers/counters can be set/reset.

LR 0000 to LR 0199 correspond to data link bits CIO 1000 to CIO 1199.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	No	OK	No	No	OK	OK	OK	OK

End Codes   An end code of 14 (format error) will be returned if the length of the command is incorrect. (The forced set/reset/cancel data is 16 bytes long.)

An end code of 15 (entry number data error) will be returned if the area classification, word address, or bit parameter setting is incorrect. An end code of 15

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will also be returned if the a data specification of 0 or 1 is used when a timer or counter is designated.

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-29 FORCED SET/RESET CANCEL – – KC

Cancels all forced set and forced reset bits (including those set by FORCED SET, FORCED RESET, and MULTIPLE FORCED SET/RESET).

Command Format
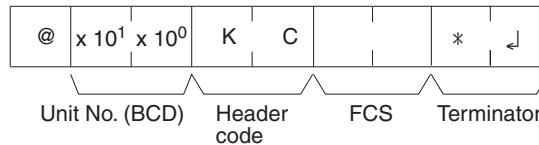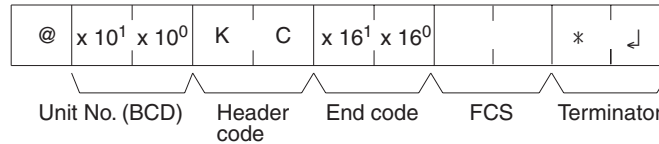
$$@ \quad x\,10^1 \quad x\,10^0 \quad K \quad C \quad | \quad * \quad \leftarrow$$

Unit No. (BCD)   Header code   FCS   Terminator

Response Format

$$@ \quad x\,10^1 \quad x\,10^0 \quad K \quad C \quad x\,16^1 \quad x\,16^0 \quad | \quad * \quad \leftarrow$$

Unit No. (BCD)   Header code   End code   FCS   Terminator

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	No	OK	No	No	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect. (The forced set/reset/cancel data can be 16 bytes long.)

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-30 PLC MODEL READ – – MM

Reads the model code of the CPU Unit.

Command Format

| @ | x 10¹ | x 10⁰ | M | M | | * | ↵ |

Unit No. (BCD) — Header code — FCS — Terminator

Response Format

| @ | x 10¹ | x 10⁰ | M | M | x 16¹ | x 16⁰ | x 16¹ | x 16⁰ | | * | ↵ |

Unit No. (BCD) — Header code — End code — Model code — FCS — Terminator
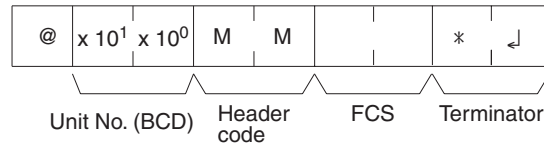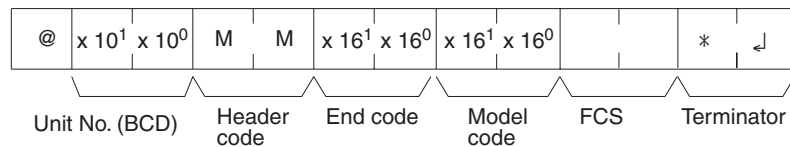
"Model code" indicates the model in two digits hexadecimal.

Model code	Model
30	CS/CJ
01	C250
02	C500
03	C120/C50
09	C250F
0A	C500F
0B	C120F
0E	C2000
10	C1000H
11	C2000H/CQM1/CPM1
12	C20H/C28H/C40H, C200H, C200HS, C200HX/HG/HE (-ZE)
20	CV500
21	CV1000
22	CV2000
40	CVM1-CPU01-E
41	CVM1-CPU11-E
42	CVM1-CPU21-E

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	**No**	OK	**No**	OK	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect.

End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-31 TEST– – TS

Returns, unaltered, one block of data transmitted from the host computer.

Command Format

Specify any characters other than the carriage return.

| @ | x 10¹ | x 10⁰ | T | S | 122 characters max. | | * | ↵ |

Unit No. (BCD) Header code Characters FCS Terminator
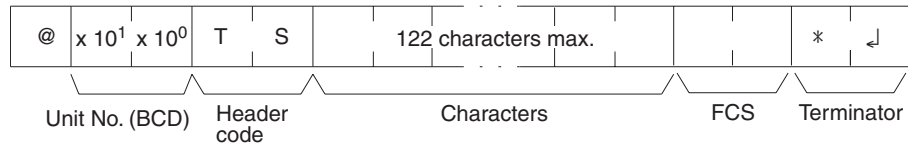
Response Format

The same characters specified in the command will be returned unaltered if the test is successful.

| @ | x 10¹ | x 10⁰ | T | S | 122 characters max. | | * | ↵ |

Unit No. (BCD) Header code Characters FCS Terminator
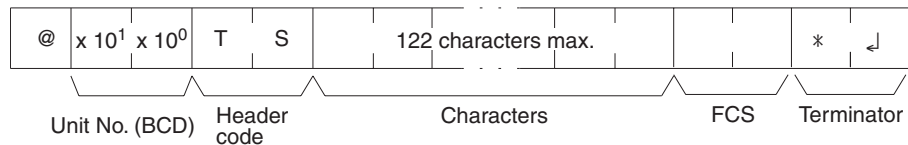
Limitations

Between 0 and 122 characters can be sent.

If the command is correct, no end code will be returned.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	**No**	OK	**No**	OK	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if a terminator is not received in the first frame.

End code (Hex)	Contents
13	FCS error
14	Format error
18	Frame length error
21	Not executable due to CPU Unit CPU error.

4-3-32 PROGRAM READ – – RP

Reads the contents of the CPU Unit user's program area in machine language. The contents are read as a block, from the beginning to the end.

Command Format

| @ | x 10¹ | x 10⁰ | R | P | | * | ↵ |

Unit No. (BCD) Header code FCS Terminator

Response Format

| @ | x 10¹ | x 10⁰ | R | P | x 16¹ | x 16⁰ | | * | ↵ |

Unit No. (BCD) Header code End code Complete program FCS Terminator
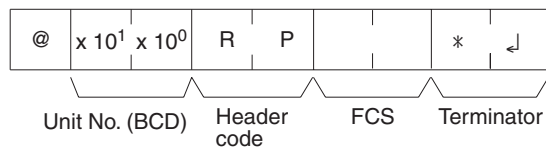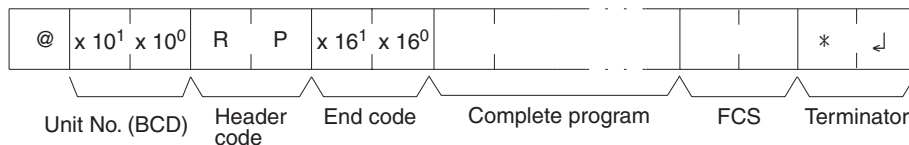
Limitations

The command cannot be executed if the UM Area is read-protected.

Data is read from the beginning of the UM Area to the maximum limit of the program area.

The response's first frame will contain 30 words of program data. The second and later frames will contain 31 words except for the last frame, which will contain up to 31 words.

The INITIALIZE and ABORT commands can be sent instead of the delimiter for multiple responses for this command. If other commands are sent, they will be treated as delimiters.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	**No**	OK	OK	OK	OK	OK	OK	**No**

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect.

End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
18	Frame length error
19	Not executable
21	Not executable due to CPU Unit CPU error.
23	User memory protected

4-3-33 PROGRAM WRITE – – WP

Writes to the CPU Unit user's program area the machine language program transmitted from the host computer. The contents are written as a block, from the beginning.

Command Format
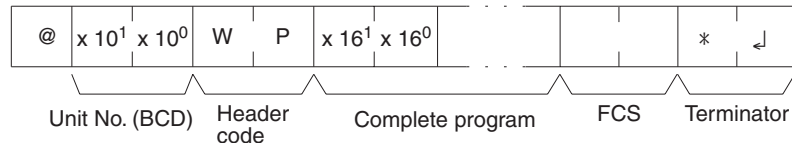
Response Format
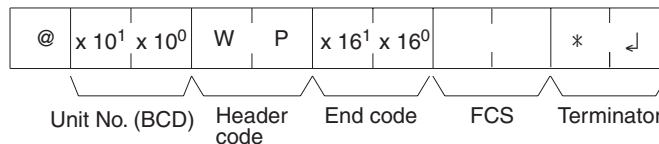
Limitations

The command cannot be executed while the UM Area is write-protected.

Data is written from the beginning of the UM Area to the maximum limit of the program area.

An error will not occur if the command attempts to write program data beyond the maximum size of the program area.

The program data can be divided into multiple frames in units of 4 characters.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	OK	OK	**No**	**No**	**No**	OK	**No**	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect (the total size of the program is not a multiple of 8 bytes) or the first frame contains no program data.

An end code of 15 (entry number data error) will be returned if the specified write data is not hexadecimal.

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
02	Not executable in MONITOR mode
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
19	Not executable
21	Not executable due to CPU Unit CPU error.
23	User memory protected
A3	Aborted due to FCS error in transmit data
A4	Aborted due to format error in transmit data
A5	Aborted due to entry number data error in transmit data
A8	Aborted due to frame length error in transmit data

4-3-34 I/O TABLE GENERATE – – MI

Corrects the registered I/O table to match the actual I/O table.

Command Format

@	x 10^1 x 10^0	M I		*	↵

Unit No. (BCD)   Header code   FCS   Terminator

Response Format

@	x 10^1 x 10^0	M I	x 16^1 x 16^0		*	↵

Unit No. (BCD)   Header code   End code   FCS   Terminator
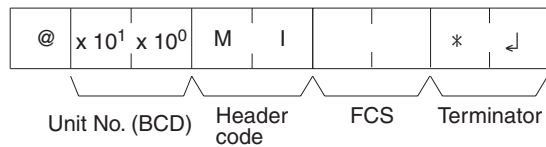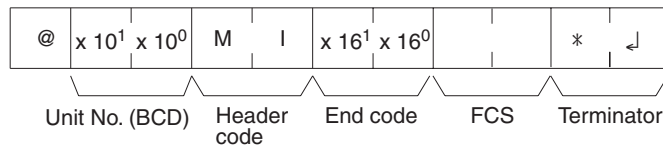
Limitations

The write-protected end code for this command is different from that of the other commands.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	No	OK	No	No	No	OK	No	OK

End Codes

An end code of 14 (format error) will be returned if the length of the command is incorrect.

End code (Hex)	Contents
00	Normal completion
01	Not executable in RUN mode
02	Not executable in MONITOR mode
03	UM write-protected
13	FCS error

End code (Hex)	Contents
14	Format error
18	Frame length error
19	Not executable
20	Could not create I/O table
21	Not executable due to CPU Unit CPU error.

4-3-35 REGISTER I/O MEMORY – – QQMR

Pre-registers to the table all of the I/O memory area bits, words, and timers/counters that are to be read. The registered contents are retained until they are overwritten or until the power is cut off, so they can be read by QQIR. (Refer to *4-3-36 READ I/O MEMORY – – QQIR.*)

Command Format

@	x 10¹ x 10⁰	Q Q	M R		x 10³ x 10² x 10¹ x 10⁰		,

Unit No. (BCD) Header code Area classification Word address Bit/word Data break

Bit/word
00 to 15: Bit designation (BCD)
Word: Word data designation (ON/OFF data only when other than word is designated by T/C.)

,	OP1 OP2 OP3 OP4	x 10³ x 10² x 10¹ x 10⁰	OP1 OP2		*	↵

Data break Area classification Word address Bit/word FCS Terminator
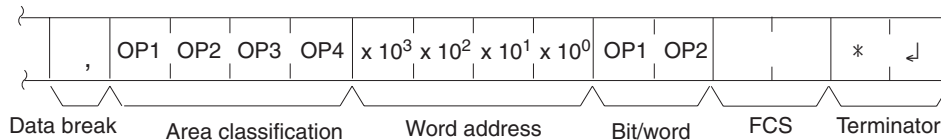
Classification	Area classification				Word address (BCD)
	Character 1	Character 2	Character 3	Character 4	
CIO	C	I	O	(SP)	0000 to 6143
LR	L	R	(SP)	(SP)	0000 to 0199
AR	A	R	(SP)	(SP)	0000 to 0959
HR	H	R	(SP)	(SP)	0000 to 0511
WR	W	R	(SP)	(SP)	0000 to 0511
Timer	T	I	M	(SP)	0000 to 2047
Counter	C	N	T	(SP)	0000 to 2047
DM	D	M	(SP)	(SP)	0000 to 9999
EM current bank	E	M	(SP)	(SP)	0000 to 9999
EM banks 0 to C	E	M	0	0	0000 to 9999
		to			
	E	M	0	C	

Note "SP" represents a space (20 Hex).

Response Format

@	x 10¹ x 10⁰	Q Q	M R	x 16¹ x 16⁰		*	↵

Unit No. (BCD) Header code End code FCS Terminator
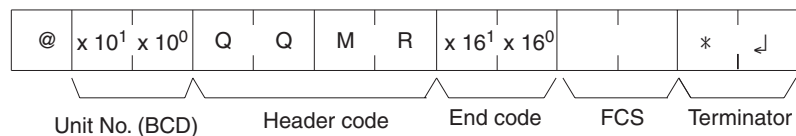
Limitations LR 0000 to LR 0199 correspond to data link bits CIO 1000 to CIO 1199.

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The maximum number of items that can be registered is 128, and timer/counter word designation is counted as two items.

If all of the registered data is correct, it will be registered to the table.

EM can be read through the current bank or bank designation.

Bits and words can be specified in any order and they will be registered in the order that they were specified.

The data can be divided into multiple frames.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	Multiple	Single	Multiple	RUN	MON	PROG	Write-protected	Read-protected
OK	OK	OK	**No**	OK	OK	OK	OK	OK

End Codes

An end code of 14 (format error) will be returned if the "," data break between two items is omitted. (The command will be considered correct if there is a "," data break just before the FCS or at the beginning of a multiple-frame command.)

An end code of 15 (entry number data error) will be returned if the area classification, word address, or bit/word setting is out of range (including hexadecimal data).

End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
15	Entry number data error
18	Frame length error
19	Not executable
A3	Aborted due to FCS error in transmit data
A4	Aborted due to format error in transmit data
A5	Aborted due to entry number data error in transmit data
A8	Aborted due to frame length error in transmit data

4-3-36 READ I/O MEMORY – – QQIR

Reads the word and bit data, from multiple I/O memory areas, that was registered with QQMR.

Command Format

@	x 10^1	x 10^0	Q	Q	I	R			*	↵

Unit No. (BCD) Header code FCS Terminator
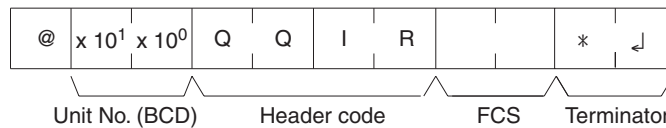
Response Format
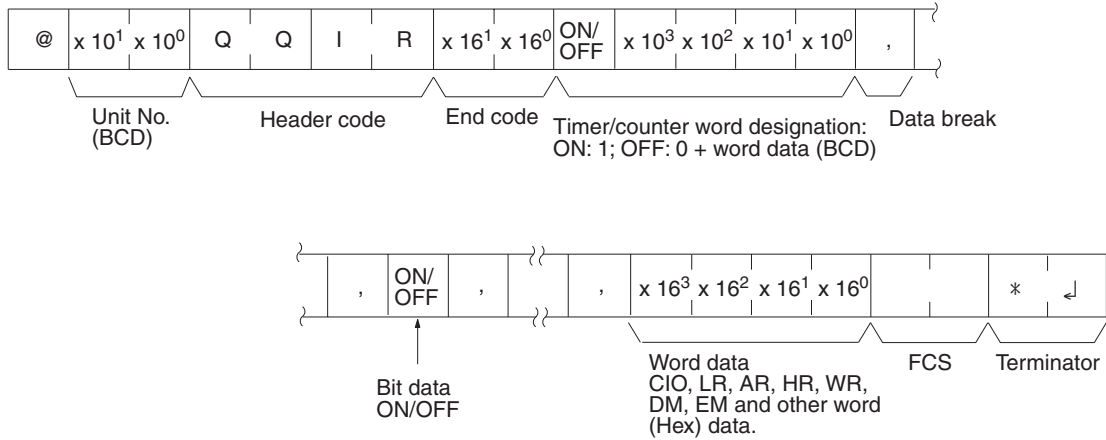
Limitations   The data is read in the same order in which it was registered with QQMR.

Execution Conditions

Commands		Responses		PLC Mode			UM Area	
Single	**Multiple**	**Single**	**Multiple**	**RUN**	**MON**	**PROG**	**Write-protected**	**Read-protected**
OK	**No**	OK	OK	OK	OK	OK	OK	OK

End Codes   An end code of 14 (format error) will be returned if the length of the command is incorrect.

An end code of 19 (not executable) will be returned if there is no registered data.

End code (Hex)	Contents
00	Normal completion
13	FCS error
14	Format error
18	Frame length error
19	Not executable
21	Not executable due to CPU Unit CPU error.

4-3-37 ABORT – – XZ

Aborts the Host Link command that is currently being processed, allowing the next command to be received.

Command Format
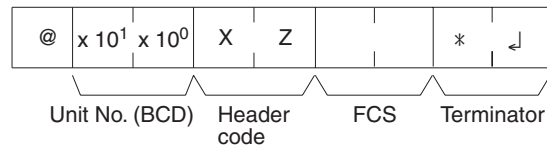
Limitations   Multiple responses to a command can be cancelled with this command.

An FCS code and terminator are required.

End Codes

The ABORT command does not receive a response.

End Codes　　There are no end codes with this command. (There is no response).

If the ABORT command (XZ) is received when data is being sent from a serial port to a host, the send operation will be stopped even in the middle of a frame.

4-3-38　INITIALIZE – – ✳✳

Initializes the transmission control procedure of the Units at all the unit numbers.

Command Format

@	✳	✳	↵
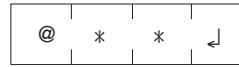
Limitations　　Multiple responses to a command can be cancelled with this command.

The INITIALIZE command does not receive a response.

End Codes　　There are no end codes with this command. (There is no response).

4-3-39　Undefined Command – – IC

This response is returned if the header code of a command cannot be decoded.

Response Format

@	x 10^1	x 10^0	I	C		✳	↵

Unit No. (BCD)　Header code　FCS　Terminator
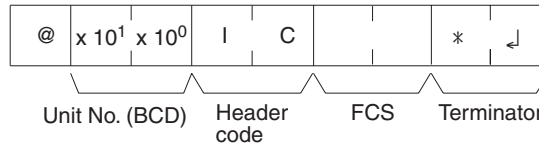
Limitations　　This response will be returned as an error for illegal header codes.

This response will be returned for error frames as well.

There is no command associated with IC.

End Codes　　There are no end codes with this command.

This section provides detailed descriptions of the FINS commands.

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5-1   Command Lists

5-1-1   FINS Commands

The following table lists the FINS commands.

Type	Command code		Name	Function
	MR	**SR**		
I/O memory area access	01	01	MEMORY AREA READ	Reads the contents of consecutive I/O memory area words.
	01	02	MEMORY AREA WRITE (See note.)	Writes the contents of consecutive I/O memory area words.
	01	03	MEMORY AREA FILL (See note.)	Writes the same data to the specified range of I/O memory area words.
	01	04	MULTIPLE MEMORY AREA READ	Reads the contents of specified non-consecutive I/O memory area words.
	01	05	MEMORY AREA TRANSFER (See note.)	Copies the contents of consecutive I/O memory area words to another I/O memory area.
Parameter area access	02	01	PARAMETER AREA READ	Reads the contents of consecutive parameter area words.
	02	02	PARAMETER AREA WRITE (See note.)	Writes the contents of consecutive parameter area words.
	02	03	PARAMETER AREA FILL (CLEAR) (See note.)	Writes the same data to the specified range of parameter area words.
Program area access	03	06	PROGRAM AREA READ	Reads the UM (User Memory) area.
	03	07	PROGRAM AREA WRITE (See note.)	Writes to the UM (User Memory) area.
	03	08	PROGRAM AREA CLEAR (See note.)	Clears the UM (User Memory) area.
Operating mode changes	04	01	RUN (See note.)	Changes the CPU Unit's operating mode to RUN or MONITOR.
	04	02	STOP (See note.)	Changes the CPU Unit's operating mode to PROGRAM.
Machine configuration reading	05	01	CPU UNIT DATA READ	Reads CPU Unit data.
	05	02	CONNECTION DATA READ	Reads the model numbers of the device corresponding to addresses.
Status reading	06	01	CPU UNIT STATUS READ	Reads the status of the CPU Unit.
	06	20	CYCLE TIME READ	Reads the maximum, minimum, and average cycle time.
Time data access	07	01	CLOCK READ	Reads the present year, month, date, minute, second, and day of the week.
	07	02	CLOCK WRITE (See note.)	Changes the present year, month, date, minute, second, or day of the week.
Message display	09	20	MESSAGE READ/CLEAR	Reads and clears messages, and reads FAL/FALS messages.
Access rights	0C	01	ACCESS RIGHT ACQUIRE (See note.)	Acquires the access right as long as no other device holds it.
	0C	02	ACCESS RIGHT FORCED ACQUIRE	Acquires the access right even if another device already holds it.
	0C	03	ACCESS RIGHT RELEASE	Releases the access right that has been acquired.
Error log	21	01	ERROR CLEAR (See note.)	Clears errors or error messages.
	21	02	ERROR LOG READ	Reads the error log.
	21	03	ERROR LOG CLEAR (See note.)	Clears the error log pointer.

Type	Command code		Name	Function
	MR	**SR**		
FINS write access log	21	40	FINS WRITE ACCESS LOG READ	The CPU Unit automatically keeps a log of any access for FINS write commands. This command reads this log.
	21	41	FINS WRITE ACCESS LOG CLEAR (See note.)	Clears the FINS write access log.
File memory	22	01	FILE NAME READ	Reads file memory data.
	22	02	SINGLE FILE READ	Reads a specified length of file data from a specified position within a single file.
	22	03	SINGLE FILE WRITE (See note.)	Writes a specified length of file data from a specified position within a single file.
	22	04	FILE MEMORY FORMAT (See note.)	Formats (initializes) the file memory.
	22	05	FILE DELETE (See note.)	Deletes specified files stored in the file memory.
	22	07	FILE COPY (See note.)	Copies files from one file memory to another file memory in the same system.
	22	08	FILE NAME CHANGE (See note.)	Changes a file name.
	22	0A	MEMORY AREA–FILE TRANSFER (See note.)	Transfers or compares data between the I/O memory area and the file memory.
	22	0B	PARAMETER AREA–FILE TRANSFER (See note.)	Transfers or compares data between the parameter area and the file memory.
	22	0C	PROGRAM AREA–FILE TRANSFER (See note.)	Transfers or compares data between the UM (User Memory) area and the file memory.
	22	15	DIRECTORY CREATE/DELETE (See note.)	Creates or deletes a directory.
	22	20	MEMORY CASSETTE TRANSFER (CP-series CPU Units only)	Transfers and verifies data between a Memory Cassette and the CPU Unit.
Debugging	23	01	FORCED SET/RESET (See note.)	Force-sets or force-resets bits, or releases force-set status.
	23	02	FORCED SET/RESET CANCEL (See note.)	Cancels all bits that have been force-set or force-reset.
Serial Gateway functions	28	03	CONVERT TO COMPOWAY/F COMMAND	Encapsulates a CompoWay/F command in a FINS command and sends it to a serial port. (The CompoWay/F command is extracted and sent through the serial port at the receiving end.)
	28	04	CONVERT TO MODBUS-RTU COMMAND	Encapsulates a Modbus-RTU command in a FINS command and sends it to a serial port. (The Modbus-RTU command is extracted and sent through the serial port at the receiving end.)
	28	05	CONVERT TO MODBUS-ASCII COMMAND	Encapsulates a Modbus-ASCII command in a FINS command and sends it to a serial port. (The Modbus-ASCII command is extracted and sent through the serial port at the receiving end.)
	Any	Any	CONVERT TO HOST LINK FINS COMMAND (See note 2.)	Sends any FINS command to a PLC connected to the serial port of a Serial Communications Board or Unit (Ver. 1.2 or later only).

Note 1. These commands will not be accepted and an end code of 2102 hex (cannot write due to protection) will be returned if the *Write Protection from*

FINS Commands Sent to CPU Units via Networks option is selected in the PLC Setup for a CS/CJ-series CPU Unit with unit version 2.0 or later, CP-series CPU Unit, or NSJ Controller.

2. The Serial Gateway function can be used with Host Link FINS commands only under the following conditions.
For more details, refer to *3-5 FINS Commands with Host Link Protocol* and the *CS/CJ Series Serial Communications Boards and Serial Communications Units Operation Manual* (W336-E1-05).

Connecting to the Destination PLC

Connect the destination PLC to the serial port of a Serial Communications Unit or Board (Ver. 1.2 or later) as a Host Link Slave and use the serial gateway mode or protocol macro mode communications.

Specifying the Destination PLC's FINS Address

- Destination Network Address (DNA):
    - When a routing table is created to treat the serial communications path as a network, the routing table associates this network address with the Serial Communications Unit or Board's serial port.
    - When a routing table is **not** created to treat the serial communications path as a network, this is the unit address of the Serial Communications Unit or Board's serial port.
- Destination Node Address (DA1):
    - When a routing table is created to treat the serial communications path as a network, the node address is the Host Link unit number + 1 (values 1 to 32).
    - When a routing table is **not** created to treat the serial communications path as a network, the node address is still the Host Link unit number + 1 (values 1 to 32).
- Destination Unit Address (DA2):
Specifies any unit address other than the serial port. (The destination of a FINS message must be an address other than the Serial Communications Unit or Board's serial port.)

5-1-2   FINS Command Restrictions

Type	Command code		Name	PLC status						
	MR	SR		RUN mode	MONI-TOR mode	PRO-GRAM mode	Access right	Read protec-tion	DIP switch UM pro-tection	Write-pro-tected from network
I/O memory area access	01	01	MEMORY AREA READ	OK	OK	OK	OK	OK	OK	OK
		02	MEMORY AREA WRITE	OK	OK	OK	OK	OK	OK	Disabled
		03	MEMORY AREA FILL	OK	OK	OK	OK	OK	OK	Disabled
		04	MULTIPLE MEMORY AREA READ	OK	OK	OK	OK	OK	OK	OK
		05	MEMORY AREA TRANSFER	OK	OK	OK	OK	OK	OK	Disabled
Parameter area access	02	01	PARAMETER AREA READ	OK	OK	OK	OK	OK	OK	OK
		02	PARAMETER AREA WRITE	OK	OK	OK	Disabled	OK	Disabled	Disabled
		03	PARAMETER AREA CLEAR	OK	OK	OK	Disabled	OK	Disabled	Disabled

Type	Command code MR	SR	Name	PLC status RUN mode	MONITOR mode	PROGRAM mode	Access right	Read protection	DIP switch UM protection	Write-protected from network
Program area access	03	06	PROGRAM AREA READ	OK	OK	OK	OK	Disabled	OK	OK
		07	PROGRAM AREA WRITE	Disabled	Disabled	OK	Disabled	OK	Disabled	Disabled
		08	PROGRAM AREA CLEAR	Disabled	Disabled	OK	Disabled	OK	Disabled	Disabled
Operating mode changes	04	01	RUN	OK	OK	OK	Disabled	OK	OK	Disabled
		02	STOP	OK	OK	OK	Disabled	OK	OK	Disabled
Machine configuration reading	05	01	CPU UNIT DATA READ	OK	OK	OK	OK	OK	OK	OK
		02	CONNECTION DATA READ	OK	OK	OK	OK	OK	OK	OK
Status reading	06	01	CPU UNIT STATUS READ	OK	OK	OK	OK	OK	OK	OK
		20	CYCLE TIME READ	OK	OK	Disabled	OK	OK	OK	OK
Time data access	07	01	CLOCK READ	OK	OK	OK	OK	OK	OK	OK
		02	CLOCK WRITE	OK	OK	OK	Disabled	OK	OK	
Message display	09	20	MESSAGE READ/ CLEAR	OK	OK	OK	Disabled (MESSAGE CLEAR only)	OK	OK	Disabled
Access rights	0C	01	ACCESS RIGHT ACQUIRE	OK	OK	OK	Disabled	OK	OK	Disabled
		02	ACCESS RIGHT FORCED ACQUIRE	OK	OK	OK	OK	OK	OK	OK
		03	ACCESS RIGHT RELEASE	OK	OK	OK	OK	OK	OK	OK
Error log	21	01	ERROR CLEAR	OK	OK	OK	Disabled	OK	OK	Disabled
		02	ERROR LOG READ	OK	OK	OK	OK	OK	OK	OK
		03	ERROR LOG CLEAR	OK	OK	OK	OK	OK	OK	Disabled
FINS write access log	21	40	FINS WRITE ACCESS LOG READ	OK	OK	OK	OK	OK	OK	OK
	21	41	FINS WRITE ACCESS LOG CLEAR	OK	OK	OK	Disabled	OK	OK	Disabled

Type	Command code		Name	PLC status						
	MR	SR		RUN mode	MONI-TOR mode	PRO-GRAM mode	Access right	Read protec-tion	DIP switch UM pro-tection	Write-pro-tected from network
File memory	22	01	FILE NAME READ	OK	OK	OK	OK	OK	OK	OK
		02	SINGLE FILE READ	OK	OK	OK	OK	OK	OK	OK
		03	SINGLE FILE WRITE	OK	OK	OK	Disabled	OK	OK	Disabled
		04	FILE MEMORY FORMAT	OK	OK	OK	Disabled	OK	OK	Disabled
		05	FILE DELETE	OK	OK	OK	Disabled	OK	OK	Disabled
		07	FILE COPY	OK	OK	OK	Disabled	OK	OK	Disabled
		08	FILE NAME CHANGE	OK	OK	OK	Disabled	OK	OK	Disabled
		0A	MEMORY AREA–FILE TRANSFER	OK	OK	OK	Disabled	OK	OK	Disabled
		0B	PARAMETER AREA–FILE TRANSFER	OK (note 1)	OK (note 1)	OK	Disabled	OK	OK (note 1)	Disabled
		0C	PROGRAM AREA–FILE TRANSFER	OK (note 2)	OK (note 2)	OK	Disabled	OK	Dis-abled (note 3)	Disabled
		15	CREATE/DELETE DIRECTORY	OK	OK	OK	Disabled	OK	OK	Disabled
		20	MEMORY CASSETTE TRANSFER (CP-series CPU Units only)	Disabled	Disabled	OK	Disabled	OK	OK (note 4)	Disabled
Debugging	23	01	FORCED SET/RESET	Disabled	OK	OK	OK	OK	OK	Disabled
		02	FORCED SET/RESET CANCEL	Disabled	OK	OK	OK	OK	OK	Disabled
Serial Gate-way	28	03	CONVERT TO COMPO-WAY/F COMMAND	OK	OK	OK	OK	OK	OK	OK
	28	04	CONVERT TO MOD-BUS-RTU COMMAND	OK	OK	OK	OK	OK	OK	OK
	28	05	CONVERT TO MOD-BUS-ASCII COMMAND	OK	OK	OK	OK	OK	OK	OK
	Any	Any	CONVERT TO HOST LINK FINS COMMAND	Depends on the command code used.						

Note
1. File-to-memory area transfers are not possible
2. File-to-program area transfers are not possible
3. Program area-to-file transfers are possible
4. Memory Cassette contents cannot be transferred to the program area if program area data is included.
5. With CS/CJ-series CPU Units with unit version 2.0 or later, CP-series CPU Unit, NSJ Controller, an option is available in the PLC Setup (Write Protection from FINS Commands Sent to CPU Units via Networks) to not received FINS write commands from specified network nodes even if a FINS write command is sent to the CPU Unit. The FINS write commands are the ones listed as *Disabled* in the *Write-protected from network* column above. The enables creating a system in which write/control operations are possible only from specific nodes. For details, refer to *1-4-4 Write Protection from FINS Commands Sent to CPU Units via Networks* in the *CS Series PLC Operation Manual* or the *CJ Series PLC Operation Manual*.

5-1-3   End Codes

The following table lists the main codes and the sub-codes, which combine to form the end code (response code) returned for a FINS command. The probable cause and corrections for each error code are also given.

Depending on the command, the destination code will sometimes make a request of another node on a network. The other node is referred to as the third node.

Note In addition to the end codes listed in the following table, the specific flags in the end code word (bits 6, 7, and 15) may also be ON. If bit 15 is ON, an error has occurred during a network relay operation. If bit 6 or 7 is ON, an error has occurred in the destination CPU Unit. If this occurs, refer to the operation manuals for the CPU Unit where the error occurred and remove the cause of the error. The contents of the end code word are shown in the following diagram.

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1			Main code (MRES)								Sub-code (SRES)				

1: Fatal CPU Unit error ⌐

1: Non-fatal CPU Unit error

1: Network relay error (See following section for details)
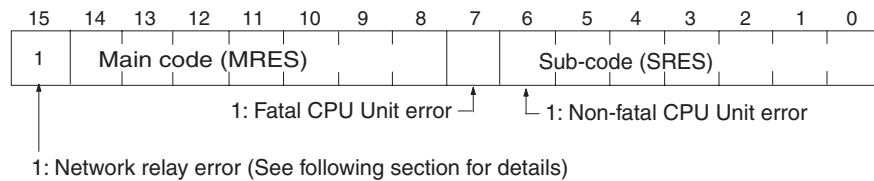
Main code	Sub-code	Check point	Probable cause	Correction
00: Normal completion	00: Normal completion	---	---	---
	01: Service canceled	---	Service was canceled.	Check the capacity of the destination area in the third node.
		Data link status	Service was canceled.	Check the status of the data link.
01: Local node error	01: Local node not in network	Network status of local node	Local node is not participating in the network.	Connect the node to the network.
	02: Token timeout	Maximum node address	Token does not arrive.	Set the local node to within the maximum node address.
	03: Retries failed	---	Send was not possible during the specified number of retries.	Execute a communications test between the nodes and re-examine the system environment if it fails.
	04: Too many send frames	Number of enabled send frames	Cannot send because maximum number of event frames exceeded.	Check event execution on the network and reduce the number of events per cycle. Increase the maximum number of event frames.
	05: Node address range error	Node address	Node address setting error occurred.	Check the settings of the rotary switches to be sure that the address is within range and that each address is set only once in the same network.
	06: Node address duplication	Node addresses	The same node address has been set twice in the same network.	Change the address of one of the nodes with the same address.

Main code	Sub-code	Check point	Probable cause	Correction
02: Destination node error	01: Destination node not in network	INS indicator on Unit	The destination node is not in the network.	Add the destination node to the network.
	02: Unit missing	Instruction control data	There is no Unit with the specified unit address.	Check the destination unit address.
	03: Third node missing	Instruction control data	The third node does not exist.	Check the unit address of the third node. Check the node address of the third node in the send data for CMND(490).
		Command data	Broadcasting was specified.	Specify only one node for the third node.
	04: Destination node busy	---	The destination node is busy.	Increase the number of retries or review the system so that the destination node does not receive so many messages.
	05: Response timeout	---	The message was destroyed by noise.	Increase the number of retries or test communications between nodes to see if there is too much noise.
		Instruction control data	The response monitor time is too short.	Increase the length of the response monitor time.
		Error history	The send/receive frame was discarded.	Take appropriate measures based on the error history.
03: Controller error	01: Communications controller error	Unit/Board indicators	An error occurred in the communications controller.	Take appropriate measures based on the operation manuals for the related Units/Boards.
	02: CPU Unit error	CPU Unit indicators at destination node	A CPU error occurred in the destination CPU Unit.	Clear the error from the CPU Unit based on its operation manuals.
	03: Controller error	Board indicators	A response was not returned because an error occurred in the Board.	Check network communications status and restart the Board. If the problem persists, replace the Board.
	04: Unit number error	Unit number	The unit number was set incorrectly.	Set the rotary switches correctly, being sure the unit numbers are within range and that each number is used only once.
04: Service unsupported	01: Undefined command	Command code	The Unit/Board does not support the specified command code.	Check the command code.
	02: Not supported by model/version	Unit model and version	The command cannot be executed because the model or version is incorrect.	Check the model number and version.
05: Routing table error	01: Destination address setting error	Routing table	The destination network or node address is not set in the routing tables.	Register the destination network and node in the routing tables.
	02: No routing tables	Routing table	Relaying is not possible because there are no routing tables.	Set routing tables in the source node, designation node, and relay nodes.
	03: Routing table error	Routing table	There is an error in the routing tables.	Set the routing tables correctly.
	04: Too many relays	Network configuration	An attempt was made to send to a network that was over 3 networks away	Reconstruct the networks or change the routing tables so that commands are sent within a range of 3 networks or less.

Main code	Sub-code	Check point	Probable cause	Correction
10: Command format error	01: Command too long	Command data	The command is longer than the maximum permissible length.	Check the command format and correct the command data.
	02: Command too short	Command data	The command is shorter than the minimum permissible length.	Check the command format and correct the command data.
	03: Elements/ data don't match	Command data	The designated number of elements differs from the number of write data items.	Check the number of elements and set data for each element.
	04: Command format error	Command data	An incorrect format was used.	Check the command format and correct the command data.
	05: Header error	Routing table	Either the relay table in the local node or the local network table in the relay node is incorrect.	Set the routing tables correctly.
11: Parameter error	01: Area classification missing	Memory area code in command data	The specified word does not exist in the memory area or there is no EM Area.	Check the memory areas and parameter codes in the command and correct the command data.
	02: Access size error	Access size specification in command data	The access size specification is incorrect or an odd word address is specified.	Check the memory areas and access size and correct the access size.
	03: Address range error	Starting address in command data	The start address in command process is beyond the accessible area.	Check the area being processed and set the correct range.
	04: Address range exceeded	Starting address and number of elements in command data	The end address in command process is beyond the accessible area.	Check the area being processed and set the correct range.
		Data link tables	The total number of words is beyond the limit.	Correct the data link tables.
	06: Program missing	Program number in command data	FFFF hex was not specified.	Specify FFFF hex.
	09: Relational error	Command data	A large–small relationship in the elements in the command data is incorrect.	Check the command data and correct the relationship between the elements.
		Data link table	A node not set in the common link parameters is set as a refresh parameter.	Correct the data link tables.
	0A: Duplicate data access	I/O access in CPU Unit	Differential monitoring was specified during data tracing or data tracing was specified during differential monitoring.	Abort the current process or wait until it ends before executing the command.
		Data link tables	The same node address is specified more than once.	Correct the data link tables.
	0B: Response too long	Number of elements in command data	The response format is longer than the maximum permissible length.	Check the command format and correct the number of elements.
	0C: Parameter error	Parameters in command data	There is an error in one of the parameter settings.	Check the command data and correct the parameters.
		Data link table file	There is an error in the file.	Check the contents of the file.

Main code	Sub-code	Check point	Probable cause	Correction
20: Read not possible	02: Protected	---	The program area is protected.	Release protection from a Programming Device and then execute the command.
	03: Table missing	Table	A table has not been registered.	Register a table.
			There is an error in the table.	Correct the table.
	04: Data missing	---	The search data does not exist.	---
	05: Program missing	Program number in command data	A non-existing program number has been specified.	Check the program numbers and specify a valid one.
	06: File missing	File name and file device	The file does not exist at the specified file device.	Check the path and file name, and correct them.
	07: Data mismatch	Contents of memory being compared	A data being compared is not the same.	Check memory contents and use the correct data.
		---	A file read operation failed.	Check the contents of the file.
21: Write not possible	01: Read-only	---	The specified area is read-only.	If the area is protected using a switch setting, release protection and then execute the command. If the area is permanently read-only, the command cannot be executed.
	02: Protected	---	The program area is protected.	Release protection from a Programming Device and then execute the command.
	Cannot write data link table	PLC Setup	Writing is not possible because automatic data link table generation has been specified.	Change the PLC Setup so that the data link tables can be manually written.
	03: Cannot register	Number of files in file device	The file cannot be created because the limit has been exceeded.	Delete any unnecessary files or create more file memory.
		Number of files open	The maximum number of files has already been opened for the system limit.	Close one or more files and then execute the command.
	05: Program missing	Program number in command data	A non-existing program number has been specified.	Check the program numbers and specify a valid one.
	06: File missing	File name	The file does not exist at the specified file device.	Correct the file name and then execute the command.
	07: File name already exists	File name	A file with the same name already exists in the specified file device.	Change the name of the file being written and then execute the command.
	08: Cannot change	Contents of memory being changed	The change cannot be made because doing so would create a problem.	---

Main code	Sub-code	Check point	Probable cause	Correction
22: Not execut-able in current mode	01: Not possi-ble during execution	---	The mode is incorrect.	Check the mode.
		Data link status	The data link is operating.	Check the status of the data links.
	02: Not possible while running	---	The mode is incorrect.	Check the mode.
		Data link status	The data links are active.	Check the status of the data links.
	03: Wrong PLC mode	---	The PLC is in PROGRAM mode.	Check the modes of the PLC and computer.
	04: Wrong PLC mode	---	The PLC is in DEBUG mode.	Check the modes of the PLC and computer.
	05: Wrong PLC mode	---	The PLC is in MONITOR mode.	Check the modes of the PLC and computer.
	06: Wrong PLC mode	---	The PLC is in RUN mode.	Check the modes of the PLC and computer.
	07: Specified node not polling node	---	The specified node is not the polling node.	Check node functioning as the polling node for the network.
	08: Step cannot be exe-cuted	---	The mode is incorrect.	Check step status.
23: No such device	01: File device missing	Unit configuration	The specified memory does not exist as a file device.	Mount memory or format EM as file memory.
	02: Memory missing	---	There is no file memory.	Check the file memory to see if it is mounted.
	03: Clock missing	---	There is no clock.	Check the model.
24: Cannot start/stop	01: Table missing	Data link tables	The data link tables have not been registered or they contain an error.	Set the data link tables.

Main code	Sub-code	Check point	Probable cause	Correction
25: Unit error	02: Memory error	Contents of memory being processed	The contents of memory contains an error.	Transfer the correct contents to memory.
	03: I/O setting error	I/O Unit configuration	The registered I/O tables do not agree with the actual I/O configuration.	Correct the I/O tables or the I/O configuration.
	04: Too many I/O points	Number of I/O in registered I/O tables	There are too many I/O points and remote I/O points registered.	Change the registered I/O table so that it is within the limit.
	05: CPU bus error	CPU bus line	An error occurred in data transfer between the CPU and a CPU Bus Unit.	Check Units, Boards, and cables to be sure they are connected correctly and then execute the ERROR CLEAR command.
	06: I/O duplication	Rack numbers, Unit numbers, and I/O addresses in PLC Setup	The same number/address was set more than once.	Check the PLC Setup and correct the numbers/addresses so that each is used only once.
	07: I/O bus error	I/O bus line	An error occurred in data transfer between the CPU and an I/O Unit.	Check Units, Boards, and cables to be sure they are connected correctly and then execute the ERROR CLEAR command.
	09: SYSMAC BUS/2 error	SYSMAC BUS/2 transmission path	An error occurred in data transfer on the SYSMAC BUS/2 line.	Check Units, Boards, and cables to be sure they are connected correctly and then execute the ERROR CLEAR command.
	0A: CPU Bus Unit error	CPU Bus Unit transmission path	An error occurred in data transfer for a CPU Bus Unit.	Check Units, Boards, and cables to be sure they are connected correctly and then execute the ERROR CLEAR command.
	0D: SYSMAC BUS No. duplication	Word settings	The same word is allocated more than once.	Check the I/O tables and correct the allocations.
	0F: Memory error	Status of memory being processed	A memory error has occurred in internal memory, a memory card, or EM file memory.	For internal memory, write the correct data and then execute the command. For a memory card or EM file memory, the file data has been destroyed. Execute the FILE MEMORY FORMAT command. If the problem persists, replace the memory.
	10: SYSMAC BUS terminator missing	---	Terminators have not been set.	Set the terminators correctly.

Main code	Sub-code	Check point	Probable cause	Correction
26: Command error	01: No protection	Command protection for program area	The specified area is not protected.	An attempt was made to clear protection on an area that is not protected, i.e., there is no reason to clear protection.
	02: Incorrect password	---	An incorrect password has been specified.	Specify the correct password.
	04: Protected	---	The specified area is protected.	Clear protection from a Programming Device and then execute the command.
		Number of commands being executed	The node receiving the command is already processing 5 commands.	Wait for current processing to end or force the end of a current process and then execute the command.
	05: Service already executing	---	The service is being executed.	Wait for the service to end or force the end of the service and then execute the command.
	06: Service stopped	---	The service is not being executed.	If necessary, start the service.
	07: No execution right	LNK indicator on Unit/Board	The right to execute the service has not been obtained.	The local node is not in the data link. Execute the command from a node that is participating in the data link.
		---	A response was not returned because a buffer error occurred.	Restart the Board. If the problem persists, replace the Board.
	08: Settings not complete	Settings required before execution	The settings required before executing the service have not been made.	Make the required settings.
	09: Necessary items not set	Command data	The required elements have not been set in the command data.	Check the command format and set the required elements in the command data.
	0A: Number already defined	Action numbers and transition numbers of program in program area	The specified action/ transition number has already been registered in a previous program.	Check the action/transition numbers to ones that are not being used and then execute the command.
	0B: Error will not clear	Cause of error being cleared	The cause of the error has not been removed.	Remove the cause of the error and then execute ERROR CLEAR.
30: Access right error	01: No access right	---	The access right is held by another device. (Online editing is being executed from another node or ACCESS RIGHT ACQUIRE or ACCESS RIGHT FORCE ACQUIRE has been executed by another node.)	Wait until the access right is released and then execute the command. ACCESS RIGHT ACQUIRE or ACCESS RIGHT FORCE ACQUIRE can be executed to obtain the access right, but this may adversely affect processing by the node that previously held the access right.
40: Abort	01: Service aborted	---	Service was aborted with ABORT command.	---

In addition to the above end codes, there are also specific flags in the end code word (bits 6, 7, and 15) that may also be ON. If bit 6 or 7 is ON, an error has occurred in the destination CPU Unit. If bit 15 is ON, an error has occurred during a network relay operation. The contents of the end code word are shown in the following diagram.

1: Network relay error (See following section for details)
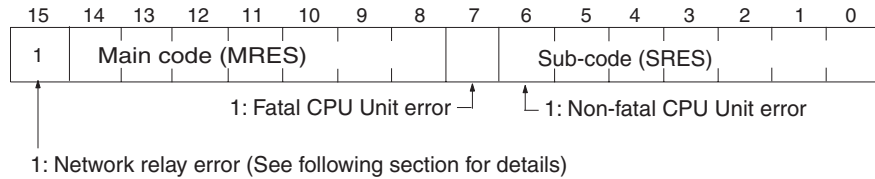
Handling Fatal and Non-fatal CPU Errors

If bit 6 or 7 is ON, an error has occurred in the destination CPU Unit. If this occurs, refer to the operation manuals for the CPU Unit where the error occurred and remove the cause of the error.

Example of a CPU Unit Error

For example, if a battery error occurs in the destination CPU Unit, bit 6 in the end code will be ON, because a battery error is a non-fatal CPU Unit error. Basically, the end code of a sent command that is completed normally is 0040.

Handling Network Relay Errors

If bit 15 is ON, an error has occurred during a network relay operation. The end code has an additional two-byte (one word) network relay error code, which can be used to determine the location of the relay error. The following diagram shows the response data when a network relay error occurs when CMND(490) is used.

Error network address: 00 to 7F (0 to 127)
Error Node Address
    Ethernet: 01 to 7E (1 to 128)
    SYSMAC NET: 01 to 7E (1 to 126)
    Controller Link: 01 to 20 (1 to 32)
    SYSMAC LINK: 01 to 3E (1 to 62)
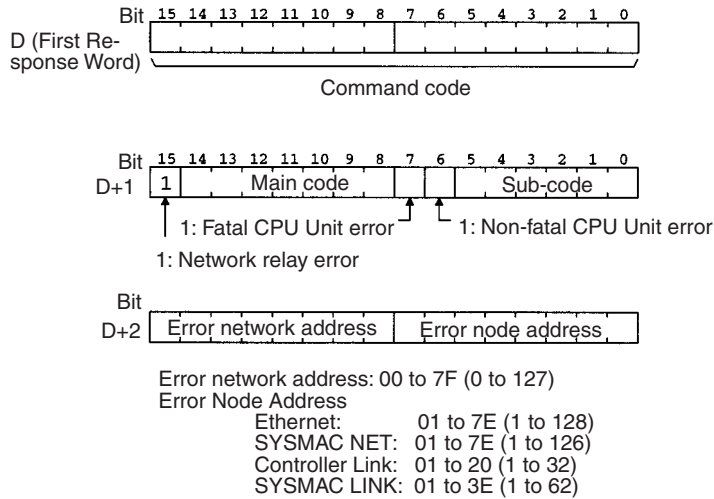
Use this information to determine the node where the error occurred and take appropriate measures.

Note When Using SEND(090) and RECV(098)

Check the path the command took using the routing tables. Check the end code and take appropriate measures for the relay node where the error occurred.

5-2 Designating Command Parameters

5-2-1 Designating I/O Memory (Variable) Area Addresses

When reading from and writing to the I/O memory (variable) area, designate I/O memory area addresses as described below.

I/O memory designation involves the designation of the memory area code and the address within the memory area code.

- Memory area codes are designated in one byte (two digits hexadecimal), as shown in the table in *5-2-2 I/O Memory Address Designations*.
- Addresses within memory area codes consist of a total of three bytes (six digits hexadecimal). Of these, two bytes (four digits hexadecimal) designate the word and one byte (two digits hexadecimal) designates the bit.

I/O memory address designation		Memory area code	Address within I/O memory area designation	
			Word	**Bit**
4 bytes (8 digits hexadecimal)	⇒	1 byte (2 digits hex)	2 bytes (4 digits hex)	1 byte (2 digits hex)
Memory area code + word + bit, in order		Set by classification (CIO, WR, etc.). Note: Also possible with forced status.	From 0000 hex (Upper limit depends on memory area code.)	00 to 0F hex Note: Always 00 hex for word address and Timer/Counter Completion Flags.
Example Bit 13 of CIO 0010: 30000A0D hex		Example CIO: 30 hex	Example 0010: 000A in hexadecimal	Example Bit 13: 0D in hexadecimal

Example: I/O memory reading
Bit 13 of CIO 0010, i.e., CIO 001013, is read.

01	01	30	00	0A	0D

- Read address
- I/O memory area designation (Area: CIO, Data type: Bit)
- Command code

Example: Reading W005

01	01	B1	0D	05	00

- Read address
- I/O memory designation (Area: WR, Data type: Word)
- Command code
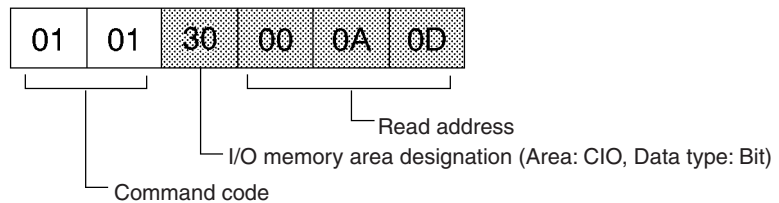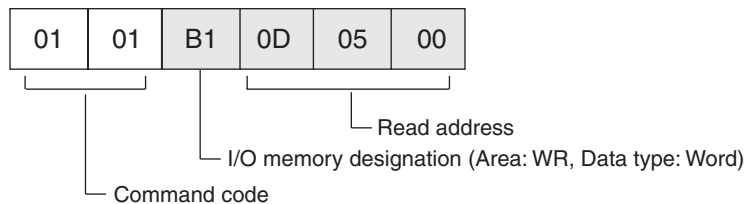
Element Data Configurations

Bit Designations

When bits are designated, each bit is considered a single element. The data for the element is expressed in one byte (ON: 01 hex; OFF: 00 hex). When data is written, this byte is transmitted. When data is read, this byte is returned.

- 00 Hex: OFF
- 01 Hex: ON

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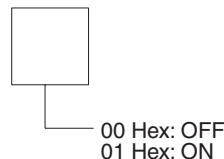
Bit Data with Forced Status

When bits are designated, each bit is considered as one element.

The data for each element is expressed in one byte (8 bits). Bit 00 indicates the specified bit data, and bit 01 indicates the forced status, When reading, this one byte is returned.

Bit 00
0: OFF
1: ON

Bit 01
0: No forced status
1: Forced status
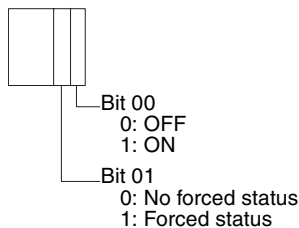
Word Designations

When words are designated, each word is considered a single element. The data for the element is expressed in two bytes. Bits 0 to 15 correspond to bits 0 to 15 of each word. When data is written, these two bytes are transmitted for each word. When data is read, these two bytes are returned.

Bits 0 to 7

Bits 8 to 15
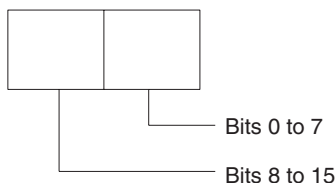
Word Data With Forced Status Data, Present Value (4 Bytes)

Word data, PV bits 0 to 7 (4th byte)

Word data, PV bits 8 to 15 (3rd byte)

Word data, PV bits 0 to 7 forced status (2nd byte)

Word data, PV bits 8 to 15 forced status (1st byte)
0: Not forced
1: Forced
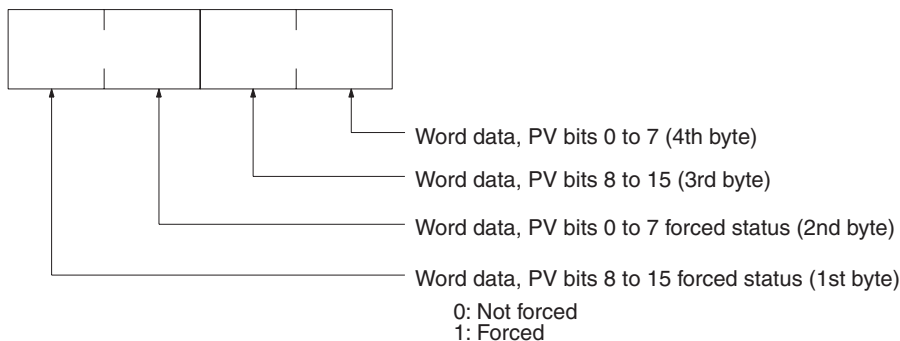
Current EM Bank Number (2 Bytes)

Bit 15   0: EM not used or all banks converted to file memory.
1: EM used.

Bits 0 to 7 (2nd byte)   Bits 0 to 14:   Current bank number

Bits 8 to 15 (1st byte)
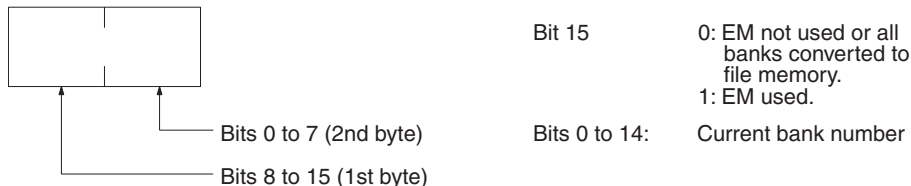
5-2-2   I/O Memory Address Designations

Area		Data type	CS/CJ mode			CV mode			Length per element
			Memory area code (hex)	Memory area address	Memory address	Memory area code (hex)	Memory area address	Memory address	
CIO Area	CIO	Bit	30	CIO 000000 to CIO 614315	000000 to 17FF0F	00	CIO 000000 to CIO 255515	000000 to 09FB0F	1
Work Area	WR		31	W00000 to W51115	000000 to 01FF0F	---	---	---	
Holding Bit Area	HR		32	H00000 to H51115	000000 to 01FF0F	---	---	---	
Auxiliary Bit Area	AR		33	A00000 to A44715 (read only)	000000 to 01BF0F	00	A00000 to A44715 (read only)	0B0000 to 0CBF0F	
				A44800 to A95915 (read/write)	01C000 to 03BF0F		A44800 to A95915 (read/write)	0CC000 to 0EBF0F	
CIO Area	CIO	Bit with forced status	70	CIO 000000 to CIO 614315	000000 to 17FF0F	40	CIO 000000 to CIO 255515	000000 to 09FB0F	1
Work Area	WR		71	W00000 to W51115	000000 to 01FF0F	---	---	---	
Holding Bit Area	HR		72	H00000 to H51115	000000 to 01FF0F	---	---	---	
CIO Area	CIO	Word	B0	CIO 0000 to CIO 6143	000000 to 17FF00	80	CIO 0000 to CIO 2555	000000 to 09FB00	2
Work Area	WR		B1	W000 to W511	000000 to 01FF00	---	---	---	
Holding Bit Area	HR		B2	H000 to H511	000000 to 01FF00	---	---	---	
Auxiliary Bit Area	AR		B3	A000 to A447 (read only)	000000 to 01BF00	80	A000 to A447 (read only)	0B0000 to 0CBF00	
				A448 to A959 (read/write)	01C000 to 03BF00		A448 to A959 (read/write)	0CC000 to 0EBF00	
CIO Area	CIO	Word with forced status	F0	CIO 0000 to CIO 6143	000000 to 17FF00	C0	CIO 000000 to CIO 255515	000000 to 09FB00	4
Work Area	WR		F1	W000 to W511	000000 to 01FF00	---	---	---	
Holding Bit Area	HR		F2	H000 to H511	000000 to 01FF00	---	---	---	
Timer Area	TIM	Completion Flag	09	T0000 to T4095	000000 to 0FFF00	01	T0000 to T2047 (T0000 to T1023)	000000 to 07FF00 (000000 to 03FF00)	1
Counter Area	CNT			C0000 to C4095	800000 to 8FFF00		C0000 to C2047 (C0000 to C1023)	080000 to 0FFF00 (080000 to 0BFF00)	

Area		Data type	CS/CJ mode			CV mode			Length per element
			Memory area code (hex)	Memory area address	Memory address	Memory area code (hex)	Memory area address	Memory address	
Timer Area	TIM	Completion Flag with forced status	49	T0000 to T4095	000000 to 0FFF00	41	T0000 to T2047 (T0000 to T1023)	000000 to 07FF00 (000000 to 03FF00)	1
Counter Area	CNT			C0000 to C4095	800000 to 8FFF00		C0000 to C2047 (C0000 to C1023)	080000 to 0FFF00 (080000 to 0BFF00)	
Timer Area	TIM	PV	89	T0000 to T4095	000000 to 0FFF00	81	T0000 to T2047 (T0000 to T1023)	000000 to 07FF00 (000000 to 03FF00)	2
Counter Area	CNT			C0000 to C4095	800000 to 8FFF00		C0000 to C2047 (C0000 to C1023)	080000 to 0FFF00 (080000 to 0BFF00)	
DM Area	DM	Bit	02	D000000 to D3276715	000000 to 7FFF0F	---	---	---	1
	DM	Word	82	D00000 to D32767	000000 to 7FFF00	82	D00000 to D32767	000000 to 7FFF00	2
EM Area	EM (Bank 0 to C)	Bit	20 to 2C	E0_0000000 to E0_3276715 to EC_0000000 to EC_3276715	000000 to 7FFF0F	---	---	---	1
	EM (Bank 0 to C)	Word	A0 to AC	E0_00000 to E0_32767 to EC_00000 to EC_32767	000000 to 7FFF00 to 000000 to 7FFF00	90 to 97	E0_00000 to E0_32767 to E7_00000 to E7_32767	000000 to 7FFF00 to 000000 to 7FFF00	2
	EM (Current bank)	Word	98	E00000 to E32767	000000 to 7FFF00	98	E00000 to E32767	000000 to 7FFF00	2
	EM (Current bank No.)	EM (Current bank No.)	BC	---	0F0000	9C	---	000600	2
Task Flag	TK	Bit	06	TK0000 to TK0031	000000 to 001F00	---	---	---	1
	TK	Status	46	TK0000 to TK0031	000000 to 001F00	---	---	---	1
Index Register	IR	PV	DC	IR00 to IR15	010000 to 010F00	---	---	---	4
Data Register	DR	PV	BC	DR00 to DR15	020000 to 020F00	9C	DR0 to DR2	000300 to 000500	2

Area	Data type	CS/CJ mode			CV mode			Length per element
		Memory area code (hex)	Memory area address	Memory address	Memory area code (hex)	Memory area address	Memory address	
Clock Pulses	Bit	07	1-min clock pulse	000000	---	---	---	1
			1-s clock pulse	000100				
			0.2-s clock pulse	000200				
			0.1-s clock pulse	000300				
			0.02-s clock pulse	000400				
Condition Flags	Bit		Error Flag (ER)	100000	---	---	---	1
			Carry Flag (CY)	100100				
			Greater Than Flag (>)	100200				
			Equals Flag (=)	100300				
			Less Than Flag (<)	100400				
			Negative Flag (N)	100500				
			Overflow Flag (OF)	100600				
			Underflow Flag (UF)	100700				
			Greater Than or Equals Flag (>=)	100800				
			Not Equal Flag (<>)	100900				
			Less Than or Equals Flag (<=)	100A00				
			Always OFF Flag (ON)	100E00				
			Always ON Flag (OFF)	100F00				
			Access Error Flag	200100	---	---	---	1

Note The only current EM bank that can be read with FINS commands is the current EM bank that is set at the end of the cycle.

Examples

Example	Designation	Contents		
		Memory area code	Address within memory area code	
			Word	Bit
CIO 0010	B0000A00 hex	B0 hex	000A hex	00 hex
CIO 001013 (bit 13 of CIO 0010)	30000A0D hex	30 hex	000A hex	0D hex
W010	B10000A00 hex	B1 hex	000A hex	00 hex
W01013 (bit 13 of W010)	31000A0D hex	31 hex	000A hex	0D hex
H010	B2000A00 hex	B2 hex	000A hex	00 hex
H01013 (bit 13 of H010)	32000A0D hex	32 hex	000A hex	0D hex
CIO 001013 (bit 13 of CIO 0010), with forced status	70000A0D hex	70 hex	000A hex	0D hex
CIO 0010, with forced status	F0000A0D hex	F0 hex	000A hex	0D hex
T0010 Completion Flag	09000A00 hex	09 hex	000A hex	00 hex
D00010 value	82000A00 hex	82 hex	000A hex	00 hex
E_3_00010 value	A3000A00 hex	A3 hex	000A hex	00 hex
Current EM bank 00010 value	98000A00 hex	98 hex	000A hex	00 hex

Number of Elements for I/O MEMORY AREA READ (0101) and I/O MEMORY AREA WRITE (0102)

The maximum number of elements that can be specified for reading or writing with I/O MEMORY AREA READ (0101) and I/O MEMORY AREA WRITE (0102) depends on the network that must be passed through.

Network	Max. number of read elements	Max. number of write elements
SYSWAY	269 words	267 words
Ethernet	999 words	996 words
Controller Link	999 words	996 words
SYSMAC LINK	269 words	267 words
DeviceNet	269 words	267 words

If more than one network is passed through to read or write data, the value for the network with the smallest limit will apply.

Volume Labels and File Names

Volume labels are names registered in file memory. File names consist of 12 bytes, as shown below. Be sure to follow this configuration when designating a file name by means of command parameters.

8 bytes	1 byte	3 bytes
Volume label/file name (directory name)	2E Hex	Extension
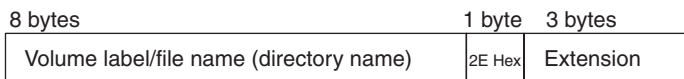
Delimiter

Start the file name and extension in the most-significant bytes respectively and then fill in any unused bytes with 20 hex.

If the file name or extension in response data is less than 8 or 3 bytes respectively, unused bytes will be filled with 20 hex.

It is not permissible to specify 00 (hex) or E5 (hex) at the beginning of a file name. (Codes of 00 hex or E5 hex means "erased" in DOS.) It is also not per-

missible to specify 7E hex (–) at the first and second characters (consecutive) of a file name.

If a file name has no extension, fill both the period (2E hex) and the extension with 20 hex.

If the file name in response data has no extension, both the period (2E hex) and the extension will be filled with 20 hex.

5-3 FINS Commands

5-3-1 About this Section

This section describes the command and response formats for FINS commands. For each format, the data is arranged in order from left to right.

Command and Response Formats

Using CMND(490)

When CMND(490) is used to send a FINS command, the command is stored in I/O memory from the rightmost word to the leftmost word, with a single word represented as two boxes (four digits hexadecimal) in the format diagram.

In the following example, five words of data are written from D00010.

Command Format
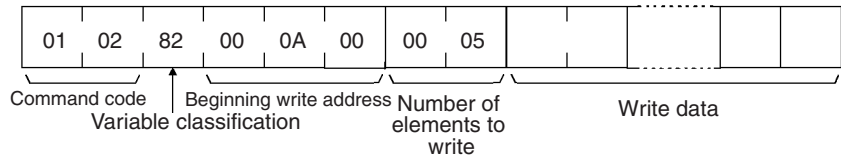
The command format data is stored in the order shown below when CMND(490) is used.
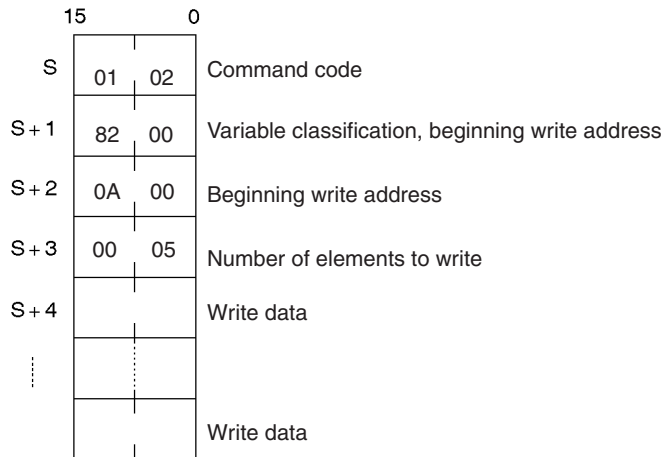
Response Format
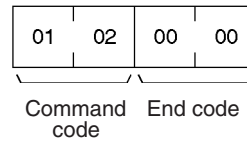
The response format data is stored in the order shown below when CMND(490) is used.
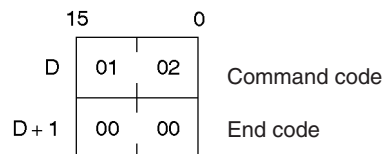
Using Host Link Communications
When a FINS command is sent using Host Link communications, the Host Link header, response wait time, destination node address, and source node address are all placed before the command format, and the frame check sequence (FCS) and terminator are placed after the command format before sending the command from the host computer.

Execution Conditions

The *Execution Conditions* tables given for each command tell whether the CPU Unit can or cannot receive commands when it is in RUN, MONITOR, or PROGRAM mode, when another device has the access right, when command protection is in effect, and when the DIP switch is protected.

Access Right at Other Device
The *Access right at other device* column tells whether the CPU Unit can or cannot receive a command when another device has the access right to the CPU Unit.

Note The access right is the exclusive right of access to a particular device (the CPU Unit in this case) which prevents interruption by another device (i.e., another Peripheral Device or Unit) when multiple commands are executed. When another device has the access right, the local device cannot execute commands marked by a "No" in the "Access right at other device" column. Conversely, other devices cannot execute this command when the local device has the access right.

UM Read Protection
The *UM read protection* column tells whether the CPU Unit can or cannot receive the command when UM (user memory) is protected from a Peripheral Device.

DIP Switch UM Protection
The *DIP switch UM protection* column tells whether the CPU Unit can or cannot receive a command when UM is write-protected by turning ON pin 1 of the DIP switch on the CPU Unit's front panel.

5-3-2 MEMORY AREA READ: 01 01

Reads the contents of the specified number of consecutive memory area words starting from the specified word.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

Command code
I/O Memory area code
Beginning address
No. of items (binary)

Response Format

Command code
End code
Data (for number of items)

Parameters

I/O memory area code, beginning address, number of items (command)

Specify the type of data read, the beginning address of the data to be read, and the number of items of data to be read (2 digits hexadecimal).

The memory areas that can be read are given in the following table (*I/O Memory Area Codes*). Refer to *5-2-2 I/O Memory Address Designations* for the specific addresses that can be used.

Data (response)

Indicates the data from the specified I/O memory area is returned in sequence starting from the beginning address. The required number of bytes in total is calculated as follows:

Number of bytes required by each item x number of items

For details regarding data configuration, refer to *Element Data Configurations* on page 163.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Note 1. If the specified number of elements is 0000 hex, nothing will be read and a normal response will be returned.

2. I/O memory can be read regardless of the operating mode of the CPU Unit.

I/O Memory Area Codes

Area		Data type	CS/CJ mode memory area code (hex)	CV mode memory area code (hex)	Bytes per element
CIO Area	CIO	Bit	30	00	1
Work Area	WR		31	---	
Holding Bit Area	HR		32	---	
Auxiliary Bit Area	AR		33	00	
CIO Area	CIO	Word	B0	80	2
Work Area	WR		B1	---	
Holding Bit Area	HR		B2	---	
Auxiliary Bit Area	AR		B3	80	
Timer Area	TIM	Completion Flag	09	01	1
Counter Area	CNT				
Timer Area	TIM	PV	89	81	2
Counter Area	CNT				
DM Area	DM	Bit	02	---	1
	DM	Word	82	82	2
EM Area	EM bank 0 to bank C	Bit	20 to 2C	---	1
	EM bank 0 to bank C	Word	A0 to AC	90 to 97	2
	EM current bank	Word	98	98	2
	EM current bank No.	EM current bank No.	BC	9C	2
Task Flag	TK	Bit	06	---	1
	TK	Status	46	---	1
Index Register	IR	PV	DC	---	4
Data Register	DR	PV	BC	9C	2
Clock Pulses		Bit	07	---	1
Condition Flags		Bit			1

5-3-3   MEMORY AREA WRITE: 01 02

Writes data to the specified number of consecutive words starting from the specified word.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

Command code
I/O memory area code
Beginning address
No. of items (binary)
Data (for number of items)

Response Format

Command code   End code

Parameters

I/O memory area code, beginning address, number of items (command)
Specify the type of data written, the beginning address of the data to be written, and the number of items of data to be written (2 digits hexadecimal).

The memory areas that can be written are given in the following table (*I/O Memory Area Codes*). Refer to *5-2-2 I/O Memory Address Designations* for the specific addresses that can be used.

Data (command)
The data from the specified I/O memory area is returned in sequence starting from the beginning address. The required number of bytes in total is calculated as follows:

   Number of bytes required by each item x number of items

For details regarding data configuration, refer to *Element Data Configurations* on page 163.

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments

If the number of items is designated as 0000 (hex), a normal completion end code will be returned without the write operation being executed.

The MEMORY AREA WRITE command can be executed regardless of the CPU Unit's operating mode. It is the user's responsibility to program steps to prohibit this command from being executed when the CPU Unit is in RUN mode if such protection is necessary. Execute CPU UNIT STATUS READ (command code 0601) to read the CPU Unit's mode. (Refer to *5-3-17 CPU UNIT STATUS READ: 06 01.*)

When data is written to the Timer/Counter PV Area, the Completion Flags will not be turned OFF (0).

I/O Memory Area Codes

Area		Data type	CS/CJ mode memory area code (hex)	CV mode memory area code (hex)	Bytes per element
CIO Area	CIO	Bit	30	---	1
Work Area	WR		31	---	
Holding Bit Area	HR		32	---	
Auxiliary Bit Area	AR		33	---	
CIO Area	CIO	Word	B0	80	2
Work Area	WR		B1	---	
Holding Bit Area	HR		B2	---	
Auxiliary Bit Area	AR		B3	80	
Timer Area	TIM	PV	89	81	2
Counter Area	CNT				
DM Area	DM	Bit	02	---	1
	DM	Word	82	82	2
EM Area	EM bank 0 to bank C	Bit	20 to 2C	---	1
	EM bank 0 to bank C	Word	A0 to AC	90 to 97	2
	EM current bank	Word	98	98	2
Index Register	IR	PV	DC	---	4
Data Register	DR	PV	BC	9C	2

5-3-4   MEMORY AREA FILL: 01 03

Writes the same data to the specified number of consecutive memory area words.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

Command code

I/O memory area code

Beginning address   No. of items (binary)   Data

Response Format

Command code   End code

Parameters   **I/O memory area code, beginning address, number of items (command)**
Specify the type of data written, the beginning address of the data to be written, and the number of items of data to be written (2 digits hexadecimal).

The memory areas that can be written are given in the following table (*I/O Memory Area Codes*). Refer to *5-2-2 I/O Memory Address Designations* for the specific addresses that can be used.

Data (command)

Specify the data to be written to the memory area starting from the beginning address. The data to be written should consist of two bytes.

For details regarding data configuration, refer to *Element Data Configurations* on page 163.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments   If the number of items is designated as 0000 (hex), a normal completion end code will be returned without the write operation being executed.

The MEMORY AREA FILL command can be executed regardless of the CPU Unit's operating mode. It is the user's responsibility to program steps to prohibit this command from being executed when the CPU Unit is in RUN mode if such protection is necessary. Execute CPU UNIT STATUS READ (command code 0601) to read the CPU Unit's mode. (Refer to *5-3-17 CPU UNIT STATUS READ: 06 01*.)

When data is written to the Timer/Counter PV Area, the Completion Flags will be turned OFF (0).

Data cannot be written if the address is out of range.

If the specified area is force set or reset, clear the force set/reset to write the data.

I/O Memory Area Codes

Area		Data type	CS/CJ mode memory area code (hex)	CV mode memory area code (hex)	Bytes per element
CIO Area	CIO	Word	B0	80	2
Work Area	WR		B1	---	
Holding Bit Area	HR		B2	---	
Auxiliary Bit Area	AR		B3	80	
Timer Area	TIM	PV	89	81	2
Counter Area	CNT				
DM Area	DM	Word	82	82	2
EM Area	EM bank 0 to bank C	Word	A0 to AC	90 to 97	2
	EM current bank	Word	98	98	2

5-3-5   MULTIPLE MEMORY AREA READ: 01 04

Reads in one batch the contents of the specified number of non-consecutive I/O memory area words, starting from the specified word.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

Response Format
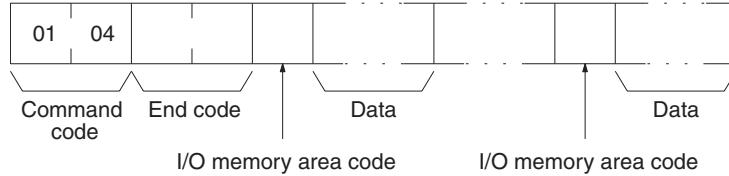
Parameters

I/O memory area code (command)

Specify the type of data to read.

The memory areas that can be read are given in the following table (*I/O Memory Area Codes*). Refer to *5-2-2 I/O Memory Address Designations* for the specific addresses that can be used.

Beginning address (command)

Specify the first word/bit/flag to read.

I/O memory area code, data (response)

Indicates the data type and contents of the designated I/O memory area(s). The data in the designated memory area(s) will be returned in the sequence specified by the command.

The number of bytes that can be read for each item depends on the I/O memory area that is read. For details regarding data configuration, refer to *Element Data Configurations* on page 163.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

The maximum number of elements that can be read with each command depends on the network as shown in the following table.

Network	Maximum number of elements
Controller Link Ethernet	167
SYSMAC LINK DeviceNet	89

If nothing is specified after the command code, a normal response will be returned, but nothing will be read.

If there is an error in the I/O memory area code or beginning address, the I/O memory area will not be read.

I/O Memory Area Codes

Area		Data type	CS/CJ mode memory area code (hex)	CV mode memory area code (hex)	Bytes per element
CIO Area	CIO	Bit	30	00	1
Work Area	WR		31	---	
Holding Bit Area	HR		32	---	
Auxiliary Bit Area	AR		33	00	
CIO Area	CIO	Bit with forced status	70	40	1
Work Area	WR		71	---	
Holding Bit Area	HR		72	---	

Area		Data type	CS/CJ mode memory area code (hex)	CV mode memory area code (hex)	Bytes per element
CIO Area	CIO	Word	B0	80	2
Work Area	WR		B1	---	
Holding Bit Area	HR		B2	---	
Auxiliary Bit Area	AR		B3	80	
CIO Area	CIO	Word with forced status	F0	C0	4
Work Area	WR		F1	---	
Holding Bit Area	HR		F2	---	
Timer Area	TIM	Completion Flag	09	01	1
Counter Area	CNT				
Timer Area	TIM	Completion Flag with forced status	49	41	1
Counter Area	CNT				
Timer Area	TIM	PV	89	81	2
Counter Area	CNT				
DM Area	DM	Bit	02	---	1
	DM	Word	82	82	2
EM Area	EM bank 0 to bank C	Bit	20 to 2C	---	1
	EM bank 0 to bank C	Word	A0 to AC	90 to 97	2
	EM current bank	Word	98	98	2
	EM current bank No.	EM current bank No.	BC	9C	2
Task Flag	TK	Bit	06	---	1
	TK	Status	46	---	1
Index Register	IR	PV	DC	---	4
Data Register	DR	PV	BC	9C	2
Clock Pulses		Bit	07	---	1
Condition Flags		Bit			1

5-3-6   MEMORY AREA TRANSFER: 01 05

Copies and transfers the contents of the specified number of consecutive I/O memory area words to the specified I/O memory area.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

Response Format

```
01    05
```

Command   End code
code
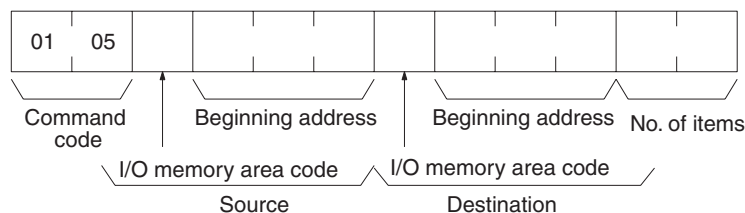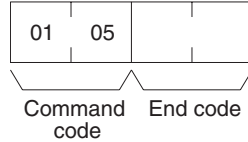
Parameters

I/O memory area code and Beginning address (command)

Specify the data area to transfer from and the data area to transfer to and specify the positions for beginning the data transfer.

The memory areas that can be transferred are given in the following table (*I/O Memory Area Codes*). Refer to *5-2-2 I/O Memory Address Designations* for the specific addresses that can be used.

Number of items (command)

Specify the number of words of data to transfer. (Each word consists of two bytes.) The specified number of words will be transferred in sequence from the source beginning address onwards to the destination beginning address onwards.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

If the number of items is designated as 0000 (hex), a normal completion end code will be returned without the copy operation being executed.

It is the user's responsibility to program steps to prohibit this command from being executed when the CPU Unit is in RUN mode if such protection is necessary. Execute CPU UNIT STATUS READ (command code 0601) to read the CPU Unit's mode. (Refer to *5-3-17 CPU UNIT STATUS READ: 06 01.*)

Even if data is written to the Timer/Counter PV Area, the Completion Flags will not be turned OFF (0).

I/O Memory Area Codes

Area		Data type	CS/CJ mode memory area code (hex)	CV mode memory area code (hex)	Bytes per element
CIO Area	CIO	Word	B0	80	2
Work Area	WR		B1	---	
Holding Bit Area	HR		B2	---	
Auxiliary Bit Area	AR		B3	80	
Timer Area	TIM	PV	89	81	2
Counter Area	CNT				
DM Area	DM	Word	82	82	2
EM Area	EM bank 0 to bank C	Word	A0 to AC	90 to 97	2
	EM current bank	Word	98	98	2

5-3-7 PARAMETER AREA READ: 02 01

Reads the contents of the specified number of consecutive CPU Unit parameter area words starting from the specified word.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

| 02 | 01 | 80 | | | |

Command code / Parameter area code / Beginning word / No. of words

Response Format

| 02 | 01 | | | | | |

Command code / End code / Parameter area code / Beginning word / No. of words / Data

Parameters

Parameter area code (command and response)
Specify the parameter area to read. The parameter area code is designated in two bytes. The leftmost byte is always 80 (hex) and the rightmost byte specifies the parameter area.

Beginning word (command and response)
Specify the first word to read. The beginning word address specifies the relative word address, with the beginning of the designated area as 0000 (hex).

Parameter Areas
The areas that can be read are shown below, along with their parameter area codes.

	Parameter area code	Address range (Hex)	Parameter area code	Address range (Hex)
PLC Setup Area	8010	0000 to 01FF (512 words)		
I/O Table Registration Area	8012	0000 to 04FF (1,280 words)	8000	0000 to 1F3F 8000 words)
Routing Table Area	8013	0000 to 01FF (512 words)		
CPU Bus Unit Setup Area	8002	0000 to 143F (5184 words)		

Number of words (command and response)
Bits 0 to 14 are used to specify the number of words to be read. (Each word consists of 16 bits.) Bit 15 must be OFF (0) in the command format. When the content in the response format contains the last word of data in the specified parameter area, bit 15 will be ON (1). For example, it would indicate that the 512th word of data is contained in the PLC Setup area.

Data (response)
The data in the specified parameter area will be returned in sequence starting from the beginning word. The leftmost bits (bits 8 to 15) of each word are read

first, followed by the rightmost bits (bits 0 to 7). The required number of bytes in total for each read is calculated as follows:

Number of words x 2 (each word consists of 16 bits)

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

All words in the specified parameter area must be read at the same time to ensure complete data. A maximum of 498 words can be read with each command. (One word = 16 bits.) To read larger parameter areas, use multiple commands and specify the beginning word and number of words for each.

If more than 498 words is specified as the number of elements, the maximum number of words will be read and returned with a response code of 1108 hex.

If the beginning word plus the number of words specified to read exceeds the capacity of the specified area, the data read through the end of the area and the actual number of words read will be returned with a response of 1104 hex.

Except for the routing table area, each area must be read or written in its entirety.

5-3-8 PARAMETER AREA WRITE: 02 02

Writes data to the specified number of consecutive CPU Unit parameter area words starting from the specified word.

Data can be written to the I/O table only when the CPU Unit is in PROGRAM mode.

Note Some PLC Setup parameters cannot be written in RUN or MONITOR mode.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	**No**

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

| 02 | 02 | | | | | | | |

Command code   Parameter area code   Beginning word   No. of words   Data

Response Format

| 02 | 02 | |

Command code   End code

Parameters

Parameter area code (command and response)

Specify the parameter area to write. The parameter area code is designated in two bytes. The leftmost byte is always 80 (hex) and the rightmost byte specifies the parameter area.

Beginning word (command and response)

Specify the first word to write. The beginning word address specifies the relative word address, with the beginning of the designated area as 0000 (hex).

Parameter Areas

The areas that can be written to are shown below, along with their parameter area codes.

	Parameter area code	Address range (Hex)	Parameter area code	Address range (Hex)
PLC Setup Area	8010	0000 to 01FF (512 words)	8000	0000 to 1F3F 8000 words)
I/O Table Registration Area	8012	0000 to 04FF (1,280 words)		
Routing Table Area	8013	0000 to 01FF (512 words)		
CPU Bus Unit Setup Area	8002	0000 to 143F (5184 words)		

Number of words (command)

Bits 0 to 14 are used to specify the number of words to be written. (Each word consists of two bytes.) Bit 15 must be ON (1) when data is written to the last word in the specified parameter area or no data will be written. If the number of write words is set to 0000, no words will be written and a normal end code will be returned.
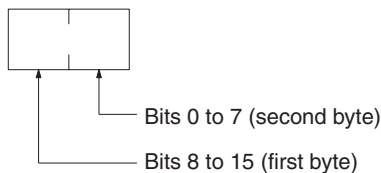
Bit 15 OFF (0): Without last word data to be written.
Bit 15 ON (1): With last word data to be written.
Bits 0 to 14: No. of words to be written

Bits 0 to 7 (second byte)
Bits 8 to 15 (first byte)

Data (command)

The data to be written. The leftmost bits (bits 15 to 8) of each word must be specified first, followed by the rightmost bits (bits 7 to 0). The required number of bytes in total for each write can be calculated as follows:

No. of words x 2 (each word consists of two bytes)

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

Parameters will be written regardless of the operating mode of the CPU Unit. There are some settings in the PLC Setup that cannot and will not be written if the CPU Unit is in RUN mode, but the end code will be 0000 nevertheless. It is the user's responsibility to program steps to prohibit this command from being executed when the CPU Unit is in the RUN mode if such protection is necessary. Execute CPU UNIT STATUS READ (command code 0601) to read the CPU Unit's mode. (Refer to *5-3-17 CPU UNIT STATUS READ: 06 01*.)

Data can only be written to the I/O registration table when the CPU Unit is in PROGRAM mode.

All words in the specified parameter area must be written at the same time to ensure complete data. A maximum of 498 words can be written with each command. Nothing will be written if more than 498 words are specified. To write larger parameter areas, use multiple commands and specify the beginning word for each.

Except for the routing table area, each area must be read or written in its entirety.

5-3-9 PARAMETER AREA CLEAR: 02 03

Writes all zeros to the specified number of consecutive parameter area words to clear the previous data. The I/O table can be cleared only when the CPU Unit is in PROGRAM mode.

Note Some PLC Setup parameters cannot be written in RUN or MONITOR mode.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	**No**

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

```
02  03        00  00        00  00
```
Command code | Parameter area code | Beginning word | No. of words | Data

Response Format

```
02  03
```
Command code | End code

Parameters

Parameter area code (command)
Specify the parameter area to clear.

Beginning word (command)
Always 0000.

Number of words (command)
Specify the number of words to clear. (One word = 16 bits.) If the number of write words is set to 0000, no words will be written and a normal end code will be returned.

Parameter Areas
The areas that can be written to are shown below, along with their parameter area codes.

	Parameter area code	Address range (Hex)	Parameter area code	Address range (Hex)
PLC Setup Area	8010	0000 to 01FF (512 words)		
I/O Table Registration Area	8012	0000 to 04FF (1,280 words)	8000	0000 to 1F3F 8000 words)
Routing Table Area	8013	0000 to 01FF (512 words)		
CPU Bus Unit Setup Area	8002	0000 to 143F (5184 words)		

Data (command)
Set to 0000. The number of words to be cleared is specified by the number of words in the command format. This parameter has two bytes (one word) of data.

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments
The PARAMETER AREA CLEAR command can be executed regardless of the CPU Unit's mode. It is the user's responsibility to program steps to prohibit this command from being executed when the CPU Unit is in the RUN mode if such protection is necessary. Execute CPU UNIT STATUS READ (command code 0601) to read the CPU Unit's mode. (Refer to *5-3-17 CPU UNIT STATUS READ: 06 01.*)

Data can only be cleared from the I/O registration table when the CPU Unit is in PROGRAM mode. When data is cleared from the I/O registration table for CJ-series CPU Units, the CPU Unit enters the status where I/O is automatically allocated at power-ON and the status of mounted Units is reflected in the I/O registration table. It is not simply cleared to 0000 hex.

Each parameter area must be cleared in its entirety.

5-3-10 PROGRAM AREA READ: 03 06

Reads the contents of the specified number of consecutive program area words starting from the specified word.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	**No**	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

03	06	FF	FF			

Command code — Program No. — Beginning word — No. of bytes

Response Format

03	06		FF	FF				

Command code — End code — Program No. — Beginning address — No. of bytes — Data
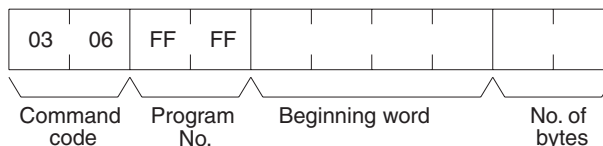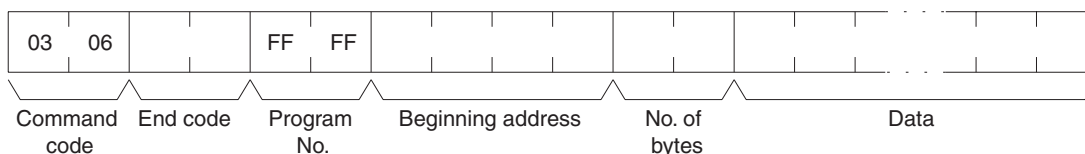
Parameters

<u>Program No. (command and response)</u>
Set to FFFF (hex).

<u>Beginning address (command and response)</u>
For the beginning address, the beginning of the program area is specified as a relative address of 00000000 (hex). The beginning address must be a multiple of four.

<u>Number of bytes (command and response)</u>
The number of bytes must be a multiple of four, and no greater than 992. The leftmost bit (bit 15) indicates whether the data at the last address in the program area is included. If bit 15 is ON (1) when the response is returned, it indicates that the data at the last address in the program area is included in the read data. Bit 15 must be OFF (0) in the command format.
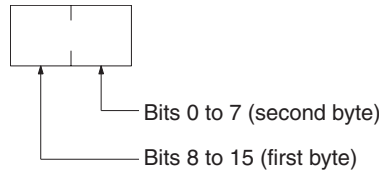
Bit 15 OFF (0): Without last address data
Bit 15 ON (1): With last address data
Bits 0 to 14: Number of bytes read

Bits 0 to 7 (second byte)

Bits 8 to 15 (first byte)

Data (response)
The data in the specified program area will be returned in sequence starting from the beginning word.

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments

A maximum of 992 bytes can be read with each command. Partition the data into units of 992 bytes or less and use as many commands as necessary to read from 00000000 (hex) to the final address.

5-3-11 PROGRAM AREA WRITE: 03 07

Writes data to the specified number of consecutive program area words starting from the specified word.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	**No**

RUN mode	MONITOR mode	PROGRAM mode
No	**No**	OK

Command Format

03	07	FF	FF				

Command code | Program No. | Beginning word | No. of bytes | Data

Response Format

03	07		FF	FF			

Command code | End code | Program No. | Beginning word | No. of bytes

Parameters

Program No. (command and response)
Always FFFF (hex).

Beginning word (command and response)
For the beginning address, the beginning of the program area is specified as a relative address of 00000000 (hex). The beginning address must be a multiple of four.

Number of bytes (command and response)
Specify the number of bytes of data to write. The number of bytes must be a multiple of 4 and 996 or less. The leftmost bit (bit 15) is used to indicate when program area writing is completed. Bit 15 must be ON (1) the last word of data.

Bit 15 OFF (0): Not last word of data
Bit 15 ON (1): Last word of data
Bits 0 to 14: Number of bytes written

Bits 0 to 7 (second byte)

Bits 8 to 15 (first byte)
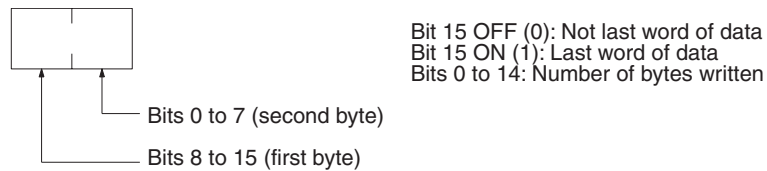
Data (command)

Specify the data to be written by designating the beginning address and the number of bytes.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

The PROGRAM AREA WRITE command can be executed only when the CPU Unit is in PROGRAM mode.

A maximum of 996 bytes can be written with each command. Partition the data into units of 996 bytes or less and use as many commands as necessary to write from 00000000 (hex) to the final address.

5-3-12 PROGRAM AREA CLEAR: 03 08

Completely initializes the contents of the program area, from the beginning of the program area to the final program address.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	**No**

RUN mode	MONITOR mode	PROGRAM mode
No	**No**	OK

Command Format

03	08	FF	FF	

Command code | Program No. | Clear code

Response Format

03	08	

Command code | End code

Parameters

Program No. (command)
Set to FFFF (hex).

Clear code (command)
Without interrupt tasks: 00 (hex)
With interrupt tasks: 10 (hex)

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments

The program area can be cleared even if it is read-protected from a Programming Device. When the program area is cleared, protection will also be cleared.

Without Interrupt Tasks

In this mode, only one single cyclic task 0 is set up.

Name	Number	Task No.
Power interrupt task	0	---
Scheduled interrupt task	0	---
I/O interrupt task	0	---
Cyclic task	1	0

With Interrupt Tasks

In this mode, one single cyclic task 0 and one or several interrupt tasks are set up.

Name	Number	Task No.
Power interrupt task	1	1
Scheduled interrupt task	2	2
		3
I/O interrupt task	32	100
		.
		.
		131
Cyclic task	1	0

Note Interrupt tasks and cyclic tasks contain only one END(001) instruction after execution.

5-3-13 RUN: 04 01

Changes the CPU Unit's operating mode to MONITOR or RUN, enabling the PLC to execute its program.

Note The CPU Unit will start operation when RUN is executed. You must confirm the safety of the system before executing RUN.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

```
┌─────┬─────┬─────┬─────┬ ─ ─ ┐
│ 04  │ 01  │ FF  │ FF  ┊     ┊
└─────┴─────┴─────┴─────┴ ─ ─ ┘
 \____  ____/ \____  ____/  ↑
 Command      Program     Mode
  code          No.
```

Response Format

```
┌─────┬─────┬─────────────┐
│ 04  │ 01  │             │
└─────┴─────┴─────────────┘
 \____  ____/ \____  ____/
 Command      End code
  code
```
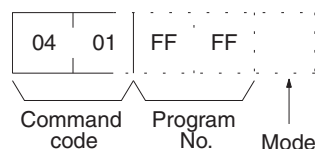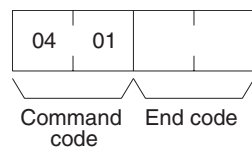
Parameters   **Program number (command)**
                              Always FFFF (hex).

Mode (command)
Set the CPU Unit's operating mode as follows:

02 (hex):   Change to MONITOR mode.

04 (hex):   Change to RUN mode.

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments

If only the command code or only the command code and program number are sent, the mode will be changed to MONITOR mode.

If the CPU Unit's operating mode has already been changed to the intended mode when this command is sent, a normal completion will be returned.

5-3-14 STOP: 04 02

Changes the CPU Unit's operating mode to PROGRAM, stopping program execution.

Note The CPU Unit will stop operation when STOP is executed. You must confirm the safety of the system before executing STOP.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

```
 04   02  | FF : FF 
```

Command   Program
code   No.

Response Format

```
 04   02  |     |     
```

Command   End code
code

Parameters

Program number (command)
Always FFFF (hex).

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments

If the CPU Unit's operating mode has already been changed to the intended mode when this command is sent, a normal completion will be returned.

If only the command code or only the command code and program number are to be sent, the operating mode will be changed to the PROGRAM mode.

5-3-15 CPU UNIT DATA READ: 05 01

Reads the following data:

- CPU Unit model
- CPU Bus Unit configuration
- CPU Unit internal system version
- Remote I/O data
- Area data
- CPU Unit information

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format
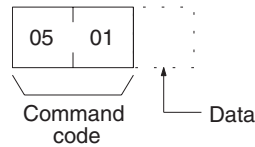
Response Format

The format is as shown below if 00 (hex) is specified as the data to be read, i.e., from the CPU Unit model to the area data.
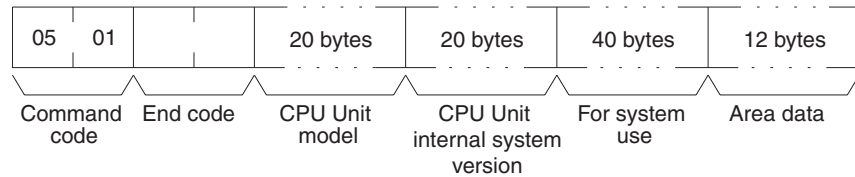
The format is as shown below if 01 (hex) is specified as the data to be read, i.e., from the CPU Bus Unit configuration to the CPU Unit information.
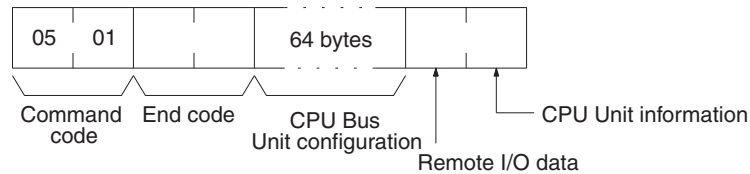
The format is as shown below if nothing is entered as the data to be read, i.e., all data from the CPU Unit model to the CPU Unit information.
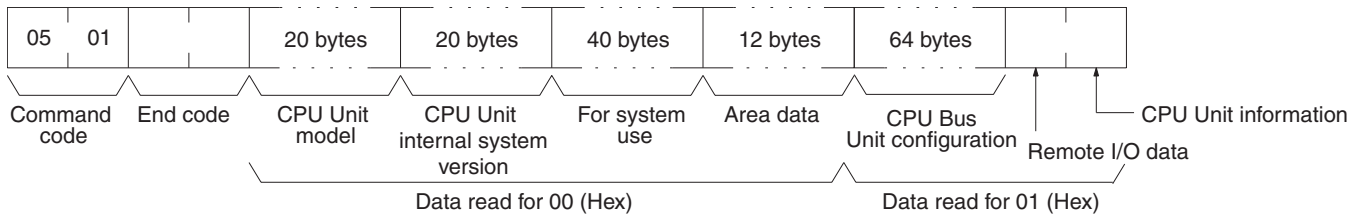
Parameters   **Data (command)**

Specify the data to be read as follows:

Value	00	01
Data to be read	CPU Unit model CPU Unit internal system version Area data	CPU Bus Unit configuration Remote I/O data CPU Unit information

CPU Unit model and internal system version (response)

Each is returned in not more than 20 bytes in ASCII (i.e. 20 ASCII characters). If the model or internal system version requires less than 20 characters, the model field will be filled with spaces and the internal system version field will be filled with null codes.

For system use (response)

Reserved for system use.
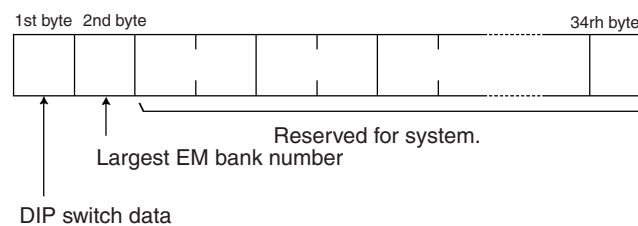
Item	Meaning	Unit
DIP switch data	Status of DIP switch on front panel of CPU Unit: Pins 0 to 7 correspond to bits 0 to 7 (ON: 1; OFF: 0)	---
Largest EM bank number	Largest number, 0 to D, in CPU Unit's EM area.	Bank

Area data (response)

The area data is configured as follows:
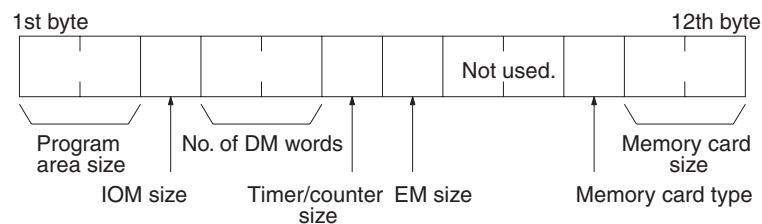
Item	Meaning	Unit
Program area size	The size of PLC Setup and program area	K words (1K words = 1,024 words)
IOM size	The size of the area (CIO, WR, HR, AR, timer/counter completion flags, TN) in which bit commands can be used (always 23).	K bytes (1K bytes = 1,024 bytes)
Number of DM words	Total words in the DM area (always 32,768)	Words
Timer/counter size	Maximum number of timers/counters available (always 8)	x 1,024
EM non-file memory size	Among the banks in the EM area, the number of banks (0 to D) without file memory.	Banks (1 bank = 32,768 words)
Memory card type	00: No memory card 04: Flash memory	---
Memory card size	Size of the memory card (0000 if there is no memory card)	K byte (1 word = 2 bytes)

CPU Bus Unit configuration (response)

Each CPU Bus Unit has a code assigned to it consisting of two ASCII charac-

ters (two bytes). These codes are given in the numerical order according to the unit number of the CPU Bus Units (unit 0 to 15).

1st byte   32nd byte   64th byte

ID for No. 0 ID for No. 1   ID for No. 15   All always 20 (32 bytes).

ID Format

Bits 00 to 14: Model ID
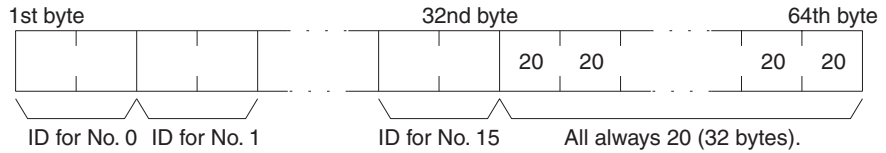
Bit 15: Unit presence (1: Present, 0: Not present)
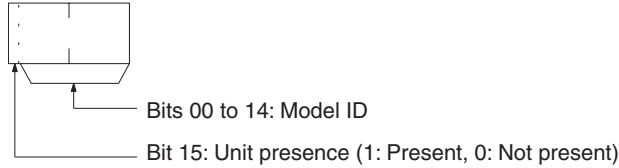
Remote I/O data (response)

The number of SYSMAC BUS Master Units mounted in remote I/O systems is returned in a single byte (00 to 02 hex) as follows:

No. of SYSMAC BUS Masters mounted (second byte)

Always 00 Hex (first byte)
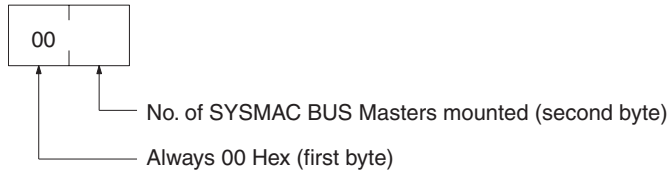
CPU Unit information (response)

The total number of racks (CPU Racks + Expansion I/O Racks) connected to the CPU Unit is returned in a single byte (8 bits) of data in the configuration shown below.

Bit 7 6 5 4 3 2 1 0

Not used.   Number of Racks connected to the CPU Unit
= CPU Rack + Expansion I/O Racks (1 to 8 Hex).
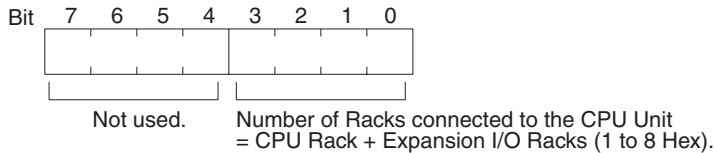
End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

5-3-16 CONNECTION DATA READ: 05 02

Reads the model number of the specified Units.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

Command Format

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

| 05 | 02 |

Command code

Unit address

Number of items
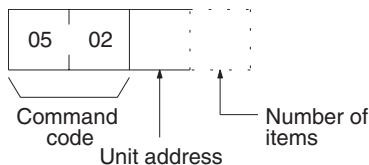
Response Format
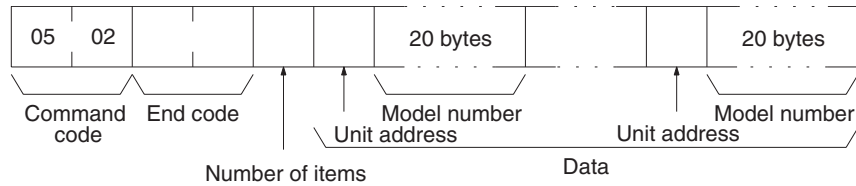
Parameters

Unit address (command and response)

Specify the unit address of the first Unit whose connection data is to be read. If the specified Unit does not exist, the connection data is read from the next Unit. Specify the following for the unit address.

CPU Unit: 00 (hex)
CPU Bus Unit: 10 + unit number (10 to 1F hex)
Special I/O Unit: 20 + unit number (20 to 7F hex)
Inner Board: E1 (hex)

Number of items (command)

Specify the number of items to be read. The number of items will be returned in order for the number specified, beginning with the unit address set in the "unit address" parameter. Any number between 01 and 19 (hexadecimal) can be specified. If the number of items is not specified, 19 hex (25) will be used.

Number of Units (response)

The number of Units for which the connection data is being returned. If bit 7 is ON (1), it means that the data for the last Unit is being returned. The maximum setting is 19 hex (25). If the number of items is not specified, 19 hex (25) will be used.

Unit address and model number (response)

These response parameters show the unit address and model number. The model number is provided in up to 20 ASCII characters.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

5-3-17 CPU UNIT STATUS READ: 06 01

Reads the operating status of the CPU Unit.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format
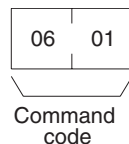
Response Format

Parameters

Status (response)

The operating status of the CPU Unit is as shown below. Bits 3 to 6 are undefined. Always mask these bits before accessing them.
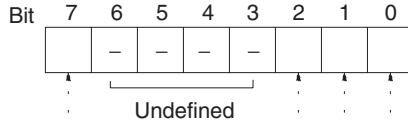
Status
0: Stop (user program is not being executed)
1: Run (user program is being executed)
Built-in flash memory access (CS1-H, CJ1-H, CJ1M, CP1H, NSJ, and CS1D only)
0: Not writing, 1: Writing

Battery status (CS1-H, CJ1-H, CJ1M, CP1H, NSJ, and CS1D only)
0: No battery, 1: Battery present

CPU status
0: Normal
1: CPU on standby
(waiting for a signal from a device,
such as a SYSMAC BUS Remote I/O Slave Unit).

Mode (response)

The CPU Unit operating mode is as follows:

00: PROGRAM

02: MONITOR

04: RUN

Fatal error data (response)

Fatal error data for the CPU Unit is configured as follows:

1: FALS error

1: Cycle time over
1: Program error
1: I/O setting error
1: I/O point overflow
1: Fatal Inner Board error
1: Duplication error
1: I/O bus error
1: Memory error
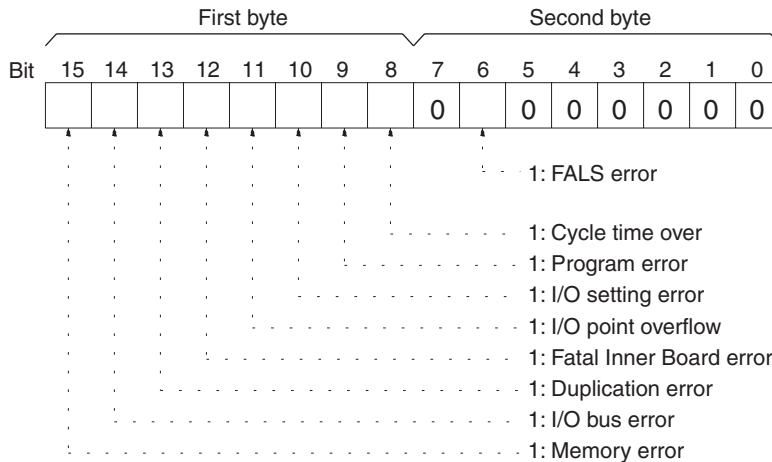
Non-fatal error data (response)

Non-fatal error data for the CPU Unit is configured as follows:

First byte | Second byte

Bit 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

- Other non-fatal errors
- Reserved for system.
- 1: Special I/O Unit setting error
- 1: CS1 CPU Bus Unit setting error
- 1: Battery error
- 1: SYSMAC BUS error
- 1: Special I/O Unit error
- 1: CPU Bus Unit error
- 1: Inner Board error
- 1: I/O verification error
- 1: PLC Setup error
- Reserved for system.
- 1: Basic I/O Unit error
- 1: Interrupt task error
- 1: Duplex error
- 1: FAL error
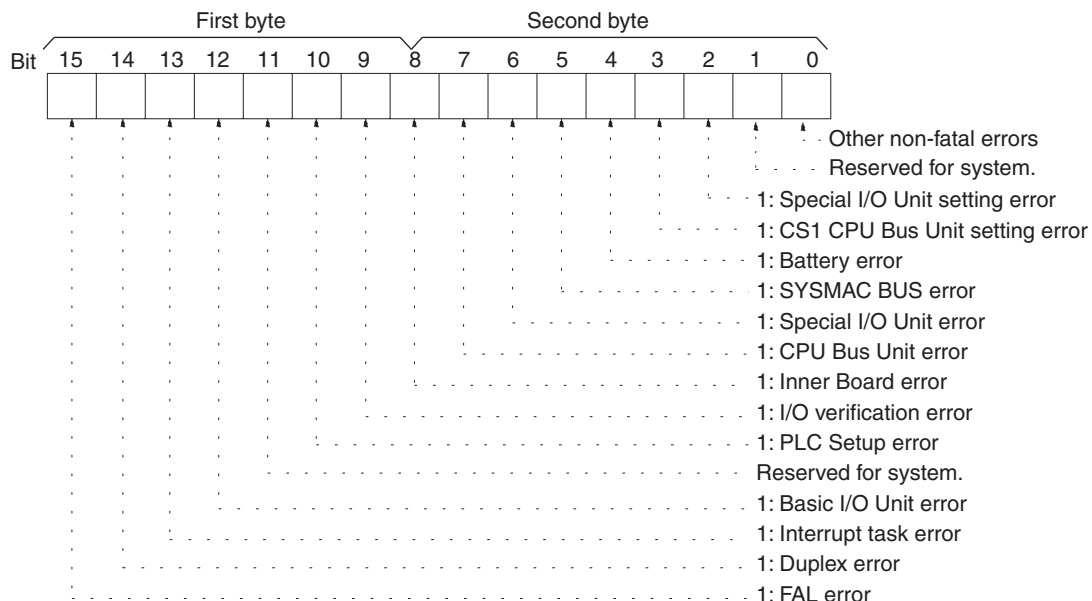
Note For details, refer to the CPU Unit's operation manual.

Message yes/no (response)

If MSG(046) has been executed, the bit corresponding to the message number will be ON (1) as shown below. To read the messages generated by MSG(195), execute MESSAGE READ (command code 0920). Refer to *5-3-21 MESSAGE READ: 09 20*.

First byte | Second byte

Bit 15 ⁚⁚ 8 7 6 5 4 3 2 1 0

0 | 0

Always 0.

- Message No. 0 (0: no/1: yes)
- Message No. 1 (0: no/1: yes)
- Message No. 2 (0: no/1: yes)
- Message No. 3 (0: no/1: yes)
- Message No. 4 (0: no/1: yes)
- Message No. 5 (0: no/1: yes)
- Message No. 6 (0: no/1: yes)
- Message No. 7 (0: no/1: yes)
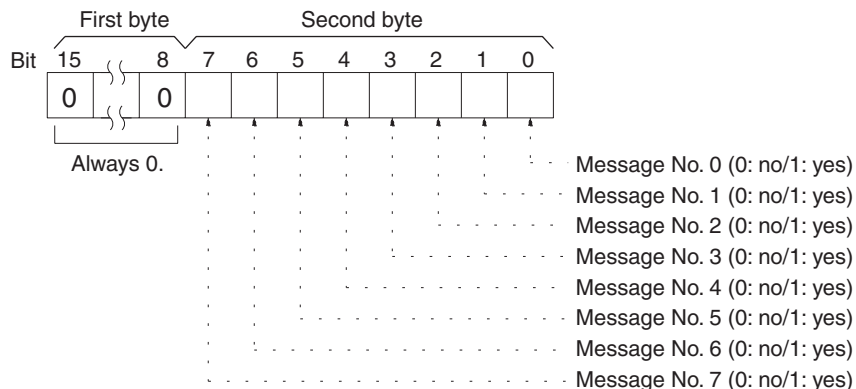
Error code (response)

Among errors that occur when the command is executed, the error code indicates the most serious. If there are no errors, it will be 0000 (hex).

Error message (response)

Indicates messages from execution of FAL(006) or FALS(007). If there is no error message, or if FAL(006) or FALS(007) are not being executed, 16 spaces (ASCII 20) will be returned.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments To read the error log, read the appropriate Auxiliary Area words or execute ERROR LOG READ command (command code 2102). Refer to *5-3-28 ERROR LOG READ: 21 02*.

5-3-18 CYCLE TIME READ: 06 20

Initializes the PLC's cycle time history or reads the average, maximum, and minimum cycle time.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	**No**

Command Format
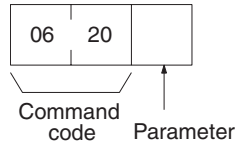
```
┌────┬────┬────┐
│ 06 │ 20 │    │
└────┴────┴────┘
  └──┬──┘   ↑
  Command  Parameter
   code
```

Response Format

The response format is as follows when the parameter is 00 hex:

```
┌────┬────┬────┐
│ 06 │ 20 │    │
└────┴────┴────┘
  └──┬──┘ └─┬─┘
  Command  End code
   code
```
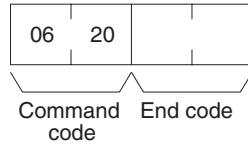
The response format is as follows when the parameter is 01 hex (read):

```
┌────┬────┬────┬──────────────┬──────────────┬──────────────┐
│ 06 │ 20 │    │              │              │              │
└────┴────┴────┴──────────────┴──────────────┴──────────────┘
  └──┬──┘ └─┬─┘ └──────┬──────┘ └─────┬──────┘ └─────┬──────┘
 Command  End code  Average cycle   Max. cycle time  Min. cycle time
  code                  time
```
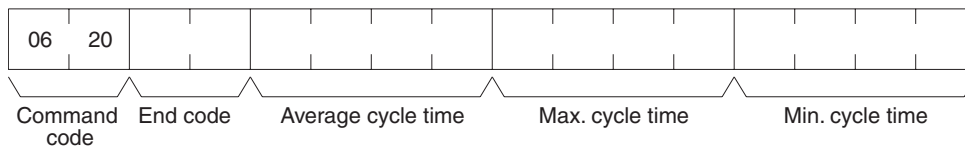
Parameters

Parameter code (command)
Specify the operations for this command as follows:

00 (hex): Initializes the cycle time.

01 (hex): Reads the average, maximum, and minimum cycle time.

Average cycle time (response)
The CPU Unit continuously calculates the cycle time, and remembers the previous eight cycle times. The "average cycle times" is the average of these eight cycle times, expressed as four bytes of binary data in 0.1-ms increments.

The average cycle time is obtained as follows:

Average cycle time = (Sum of 8 previous cycle times)/8

In the following example the average cycle time is 65.0 ms.

```
┌────┬────┬────┬────┐
│ 00 │ 00 │ 02 │ 8A │
└────┴────┴────┴────┘
```
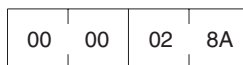
Maximum cycle time
The maximum cycle time is the maximum value, of the cycle time measured after the cycle time initialize request is received. It is expressed in four binary bytes, in increments of 0.1 ms.

Minimum cycle time
The minimum cycle time is found in the same way as the maximum cycle time described above.

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments   The maximum and minimum cycle times are initialized when operation is started.

5-3-19   CLOCK READ: 07 01

Reads clock information.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

```
┌────┬────┐
│ 07 │ 01 │
└────┴────┘
   Command
    code
```

Response Format

```
┌────┬────┬────┬───┬───┬───┬───┬───┬───┬───┐
│ 07 │ 01 │    │   │   │   │   │   │   │   │
└────┴────┴────┴───┴───┴───┴───┴───┴───┴───┘
  Command   End code  Year Month Day Hour Minute Second Day of week
   code
```

Parameters   **Year, month, day, hour, minute, second, day of week (response)**
The year, month, day of month, hour, minute, and second are expressed in BCD.

Year: The rightmost two digits of the year. (1998, 1999, and 2000 are expressed as 98, 99, and 00 respectively. 2096 and 2097 will be expressed as 96 and 97.)

Hour: 00 to 23 (BCD).

Day of week: As follows:

Value (hex)	00	01	02	03	04	05	06
Day of week	Sun	Mon	Tues	Wed	Thur	Fri	Sat

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

5-3-20   CLOCK WRITE: 07 02

Writes clock information.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format
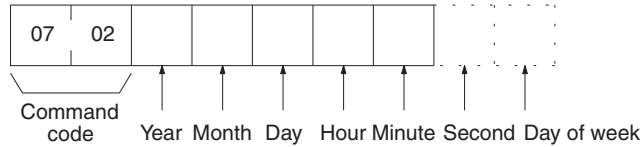
Response Format

Parameters

Year, month, day, hour, minute, second, day of week (response)

The year, month, day of month, hour, minute, and second are expressed in BCD.

Year: The rightmost two digits of the year. (1998, 1999, and 2000 are expressed as 98, 99, and 00 respectively. 2096 and 2097 will be expressed as 96 and 97.)

Hour: 00 to 23 (BCD).

Day of week: As follows:

Value (hex)	00	01	02	03	04	05	06
Day of week	Sun	Mon	Tues	Wed	Thur	Fri	Sat

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

If the second and the day of week are not specified, 00 (BCD) will be set as the second and the previous value will be kept for the day.

If the second is specified, but the day of week is omitted, the previous setting will not be changed.

The PLC does not check the day of week from the day of month. This means that no error will occur even if the day of month and the day of week do not agree.

The PLC automatically checks the range of the specified data. If any portion of the data is incorrect, the clock will not be set.

5-3-21 MESSAGE READ: 09 20

Reads messages generated by MSG(195).

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK
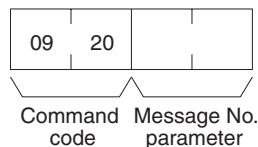
Command Format
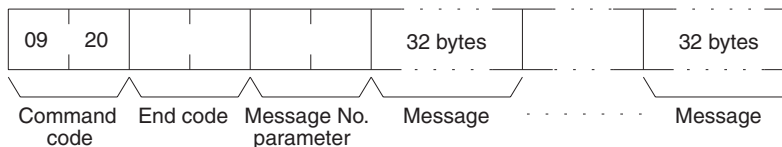
Response Format

Parameters

Message number parameter (command and response)

In the command format, turn ON (1) the bits of the messages to be read. In the response format, the bits of the messages being returned will be ON (1). If no bits are turned ON in the command format, all bits will be OFF (0) in the response format and no further data will be returned.
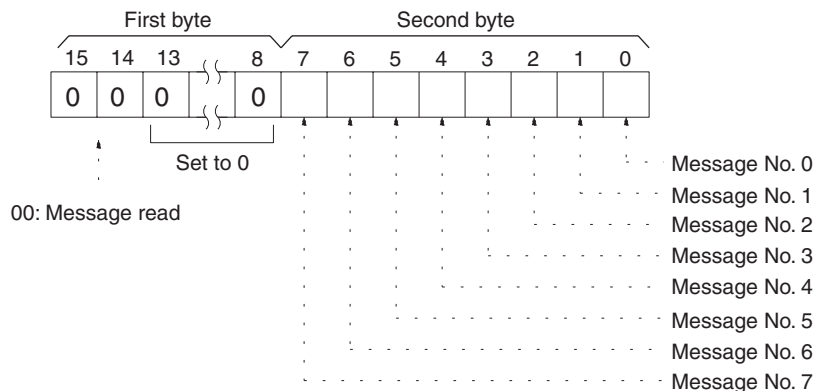
Message (response)

Each message is returned in numerical order, from smaller to larger, according to the message number. Each message consists of 32 ASCII characters (32 bytes). The total number of bytes of the messages is calculated as follows:

The number of messages read × 32 bytes

If a message consists of less than 32 bytes, the remainder will be filled with spaces (20 hex). If no message has been registered for a message number that has been requested, 32 bytes of spaces (20 hex) will be returned.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

The MESSAGE READ, MESSAGE CLEAR (refer to *5-3-22 MESSAGE CLEAR: 09 20*), and FAL/FALS READ (refer to *5-3-23 FAL/FALS READ: 09 20*) commands share the same command code (0920). They are distinguished by bits 14 and 15 of the two-byte parameter following the command code. To read MSG(195) messages, bits 14 and 15 must be OFF (0).

5-3-22 MESSAGE CLEAR: 09 20

Clears messages generated with MSG(195).

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No (when clearing messages)	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

```
 09 | 20 |   |
```
Command code   Message No.

Response Format

```
 09 | 20 |   |
```
Command code   End code
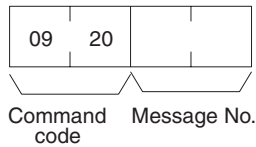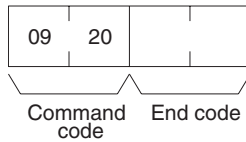
Parameters

Message number (command)
Turn ON the bits of the messages to be cleared. Multiple messages can be cleared at one time.
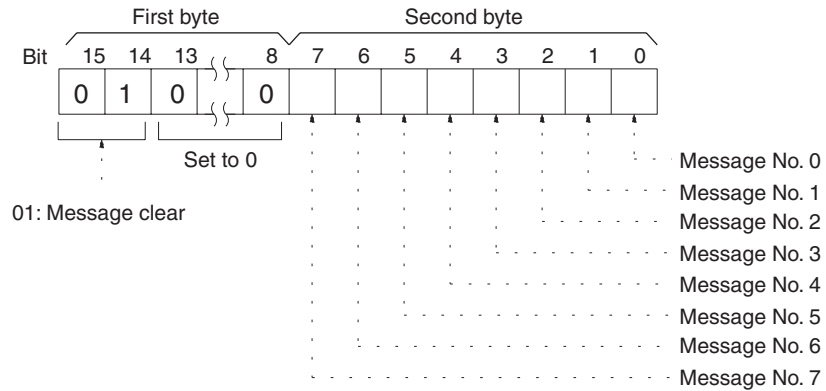
First byte   Second byte

Bit	15	14	13	8	7	6	5	4	3	2	1	0
	0	1	0	0								

Set to 0

01: Message clear

Message No. 0
Message No. 1
Message No. 2
Message No. 3
Message No. 4
Message No. 5
Message No. 6
Message No. 7

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments
The MESSAGE READ, MESSAGE CLEAR (refer to *5-3-22 MESSAGE CLEAR: 09 20*), and FAL/FALS READ (refer to *5-3-23 FAL/FALS READ: 09 20*) commands share the same command code (0920). They are distinguished by bits 14 and 15 of the two-byte parameter following the command code. To clear messages, bit 14 must be ON (0) and bit 15 must be OFF (0).

5-3-23 FAL/FALS READ: 09 20

Reads FAL(006)/FALS(007) error messages.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

Command code   FAL/FALS No.

Response Format

Command code   End code   FAL/FALS No.   Error message

Parameters

FAL/FALS No. (command and response)

In the command format, specify in hexadecimal in bits 0 to 13 the FAL or FALS number to be read as shown below. In the response format, the FAL or FALS number is returned.
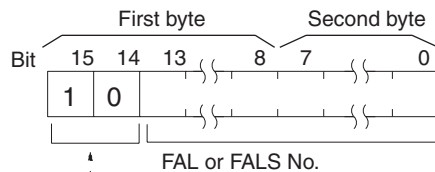
10: FAL/FALS READ (returned as 00 in the response)

Error message (response)

The error message specified in the FAL(006) or FALS(007) instruction.

A single error message consists of 16 ASCII characters.

If a message consists of less than 16 bytes, spaces (20 hex) will be returned for the remainder. If no message has been registered for a message number that has been requested, 16 bytes of spaces (20 hex) will be returned.

Message data will be returned as is even if a control code such as CR (0D hex) is included in the message data.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

The MESSAGE READ, MESSAGE CLEAR (refer to *5-3-22 MESSAGE CLEAR: 09 20*), and FAL/FALS READ (refer to *5-3-23 FAL/FALS READ: 09 20*) commands share the same command code (0920). They are distinguished by bits 14 and 15 of the two-byte parameter following the command code. To read FAL/FALS messages, bit 14 must be OFF (0) and bit 15 must be ON (1).

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5-3-24 ACCESS RIGHT ACQUIRE: 0C 01

Acquires the access right as long as no other device holds it. Execute the ACCESS RIGHT ACQUIRE command when you need to execute commands continuously without being interrupted by other devices. As soon as the execution of the commands has been completed, execute ACCESS RIGHT RELEASE (command code 0C03) to release the access right. (Refer to *5-3-26 ACCESS RIGHT RELEASE: 0C 03*.) If another devices holds the access right, the device will be identified in the response.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

```
0C   01   FF   FF
```
Command code — Program No.

Response Format

```
0C   01
```
Command code — End code

Unit address of Unit with access right
Node number of device with access right
Network address of device with access right

If any other device holds the access right, the device will be identified.

Parameters

Program No. (command)
Always FFFF (hex).

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments

If any other device has the access right, the access right cannot be acquired with this command; use ACCESS RIGHT FORCED ACQUIRE (command code 0C01). (Refer to *5-3-25 ACCESS RIGHT FORCED ACQUIRE: 0C 02*.)

When ACCESS RIGHT ACQUIRE (command code 0C01) is executed while any other device has the access right, subsequent commands cannot be executed from the other device. This command should generally not be used during normal processing.

The following table shows which FINS commands can be executed even when another device holds the access right.

Command code	Command name	Command execution while another device has access right
0101	MEMORY AREA READ	Yes
0102	MEMORY AREA WRITE	Yes
0103	MEMORY AREA FILL	Yes
0104	MULTIPLE MEMORY AREA READ	Yes
0105	MEMORY AREA TRANSFER	Yes
0201	PARAMETER AREA READ	Yes
0202	PARAMETER AREA WRITE	**No**
0203	PARAMETER AREA CLEAR	**No**
0306	PROGRAM AREA READ	Yes
0307	PROGRAM AREA WRITE	**No**
0308	PROGRAM AREA 5CLEAR	**No**
0401	RUN	**No**
0402	STOP	**No**
0501	CPU UNIT DATA READ	Yes
0502	CONNECTION DATA READ	Yes
0601	CPU UNIT STATUS READ	Yes
0620	CYCLE TIME READ	Yes
0701	CLOCK READ	Yes
0702	CLOCK WRITE	**No**
0920	MESSAGE READ/CLEAR	**No**
0C01	ACCESS RIGHT ACQUIRE	**No**
0C02	ACCESS RIGHT FORCED ACQUIRE	Yes
0C03	ACCESS RIGHT RELEASE	Yes
2101	ERROR CLEAR	**No**
2102	ERROR LOG READ	Yes
2103	ERROR LOG CLEAR	**No**
2140	FINS WRITE ACCESS LOG READ	Yes
2141	FINS WRITE ACCESS LOG CLEAR	**No**
2201	FILE NAME READ	Yes
2202	SINGLE FILE READ	Yes
2203	SINGLE FILE WRITE	**No**
2204	FILE MEMORY FORMAT	**No**
2205	FILE DELETE	**No**
2207	FILE COPY	**No**
2208	FILE NAME CHANGE	**No**
220A	MEMORY AREA–FILE TRANSFER (I/O memory to file transfers only)	**No**
220B	PARAMETER AREA–FILE TRANSFER	**No**
220C	PROGRAM AREA–FILE TRANSFER	**No**
2215	CREATE/DELETE DIRECTORY	**No**
2220	MEMORY CASSETTE TRANSFER	**No**
2301	FORCED SET/RESET	Yes
2302	FORCED SET/RESET CANCEL	Yes

Note ACCESS RIGHT ACQUIRE is used to prevent Programming Devices or other Units from taking the access right when more than one command is to be executed in succession. When finished, always execute ACCESS RIGHT RELEASE (0C03).

5-3-25 ACCESS RIGHT FORCED ACQUIRE: 0C 02

Acquires the access right even if another device already holds it.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

0C	02	FF	FF

Command code / Program No.

Response Format

0C	02		
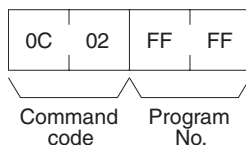
Command code / End code
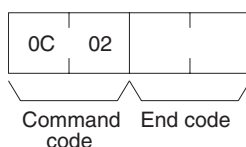
Parameters

Program number (command)
Always FFFF (hex).

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments

Even if any other device has the access right, the access right can be acquired with this command and a normal end code will be returned.

When ACCESS RIGHT FORCED ACQUIRE (command code 0C02) is executed while any other device has the access right, subsequent commands cannot be executed from the other device. This command should generally not be used during normal processing.

The following table shows which FINS commands can be executed even when another device holds the access right.

Command code	Command name	Command execution while another device has access right
0101	MEMORY AREA READ	Yes
0102	MEMORY AREA WRITE	Yes
0103	MEMORY AREA FILL	Yes
0104	MULTIPLE MEMORY AREA READ	Yes
0105	MEMORY AREA TRANSFER	Yes
0201	PARAMETER AREA READ	Yes
0202	PARAMETER AREA WRITE	**No**
0203	PARAMETER AREA CLEAR	**No**
0306	PROGRAM AREA READ	Yes
0307	PROGRAM AREA WRITE	**No**
0308	PROGRAM AREA CLEAR	**No**
0401	RUN	**No**
0402	STOP	**No**

Command code	Command name	Command execution while another device has access right
0501	CPU UNIT DATA READ	Yes
0502	CONNECTION DATA READ	Yes
0601	CPU UNIT STATUS READ	Yes
0620	CYCLE TIME READ	Yes
0701	CLOCK READ	Yes
0702	CLOCK WRITE	**No**
0920	MESSAGE CLEAR	**No**
0C01	ACCESS RIGHT ACQUIRE	**No**
0C02	ACCESS RIGHT FORCED ACQUIRE	Yes
0C03	ACCESS RIGHT RELEASE	Yes
2101	ERROR CLEAR	**No**
2102	ERROR LOG READ	Yes
2103	ERROR LOG CLEAR	**No**
2140	FINS WRITE ACCESS LOG READ	Yes
2141	FINS WRITE ACCESS LOG CLEAR	**No**
2201	FILE NAME READ	Yes
2202	SINGLE FILE READ	Yes
2203	SINGLE FILE WRITE	**No**
2204	FILE MEMORY FORMAT	**No**
2205	FILE DELETE	**No**
2207	FILE COPY	**No**
2208	FILE NAME CHANGE	**No**
220A	MEMORY AREA–FILE TRANSFER (I/O memory to file transfers only)	**No**
220B	PARAMETER AREA–FILE TRANSFER	**No**
220C	PROGRAM AREA–FILE TRANSFER	**No**
2215	CREATE/DELETE DIRECTORY	**No**
2220	MEMORY CASSETTE TRANSFER	**No**
2301	FORCED SET/RESET	Yes
2302	FORCED SET/RESET CANCEL	Yes

If this command is executed when another device holds the access right, any processing being executed by that other device will be aborted. If possible, wait until all processing has been completed and then execute ACCESS RIGHT ACQUIRE (command code 0C01). (Refer to *5-3-24 ACCESS RIGHT ACQUIRE: 0C 01*.)

When the access right is forcibly acquired by this command, the device losing the access right is not notified.

5-3-26 ACCESS RIGHT RELEASE: 0C 03

Releases the access right regardless of what device holds it.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

0C	03	FF	FF

Command code / Program No.

Response Format

0C	03		
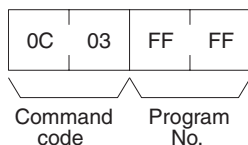
Command code / End code

Parameters

Program number (command)
Always FFFF (hex).

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments

The access right can be released by this command even when the access right is held by another device. In that case a normal end code will be returned. A normal end code will also be returned if this command is used when the access right is already released.

5-3-27 ERROR CLEAR: 21 01

Clears errors or error messages.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

21	01		

Command code / Error reset FAL No.
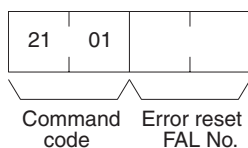
Response Format

Parameters

Error code to reset (command)

The code of the error to be reset.

The following codes can be used regardless of the operating mode of the CPU Unit:

Error code (hex)	Meaning
FFFF	All errors cleared. Resets the all errors that are currently recorded. (This code can be used in PROGRAM mode only.)
FFFE	Present error cleared. Resets the highest priority error.
0003	Duplex power supply error
0010	Duplex bus error
0011	Duplex verification error
008A	Built-in analog I/O error
008B	Interrupt task error
009A	Basic I/O error
009B	PLC Setup error
00A0 to 00A1	SYSMAC BUS error
00D1 to 00D2	Option Board error
00E7	I/O verification error • When the registered I/O tables differs from the actual I/O tables • When an I/O Unit has been added or removed
00F1	Flash memory error
00F7	Battery error
0200 to 020F	CPU Bus Unit error (The rightmost two digits are the unit number in binary of the Unit that has the error.) • When a error occurs during data transfer between the CPU Bus Unit and CPU Unit. • When the CPU Bus Unit has a watchdog timer error
02F0	Non-fatal Inner Board error
0300 to 035F	Special I/O Unit error (The rightmost two digits are the unit number in binary of the Unit that has the error.)
0400 to 040F	CPU Bus Unit setting error (The rightmost two digits are the unit number in binary of the Unit that has the error.)
0500 to 055F	Special I/O Unit setting error (The rightmost two digits are the unit number in binary of the Unit that has the error.)
0600 to 060F	Duplex communications error (The rightmost two digits are the unit number in binary of the Unit that has the error.)
4101 to 42FF	System error (FAL): FAL(006) was executed.

The following codes can be used only when the CPU Unit is in PROGRAM mode:

Error code (hex)	Meaning
FFFF	All errors cleared.
809F	Cycle time too long.

Error code (hex)	Meaning
80C0 to 80C7	I/O bus error. This error occurs when there is an error in an I/O bus check or a Unit has been removed or added when power is turned on to the PLC.
80E0	I/O setting error. This error occurs if the I/O table differs from actual I/O points in the System.
80E1	I/O points overflow
80E9	Duplication error. This error occurs if the same unit number is assigned to more than one Unit or the same word is allocated more than once.
80EA	Basic I/O word duplication resulting from rack first word settings.
80F0	Program error.
80F1	Memory error. This error occurs if an error is found in the user program, PLC Setup, Registered I/O Tables, routing tables, or CPU Bus Unit Setup memory.
82F0	Fatal Inner Board error.
C101 to C2FF	FALS(007) executed.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

If the specified error is not occurring, a normal end code will be returned.

If the present error is one that can only be cleared when the CPU Unit is in PROGRAM mode, it will not be possible to clear it in MONITOR or RUN mode.

The cause of the error must be removed before executing ERROR CLEAR (command code 2101) or the same error will immediately occur again after the command is executed.

5-3-28 ERROR LOG READ: 21 02

Reads the PLC's error log.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

Command Format

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command code / Beginning record No. / No. of records

Response Format

Command code / End code / Max. No. of stored records / No. of stored records / No. of records / Error log data / Error log data

Parameters

Beginning record number (command)
Specify the first record to be read. (The first record number is 0000 hex.)

Number of records (command, response)
Specify the number of records to read. The number of read records will be returned with the response.

Maximum number of stored records (response)
Indicates the maximum number of records that can be stored. (Always 20 records.)

Number of stored records (response)
Indicates the number of records recorded at the time the command is executed.

Error log data (response)
The specified error log records will be returned in sequence starting from the beginning record number. The total number of bytes required is calculated as follows:

    No. of records x 10 bytes

The configuration of each error record is as follows:
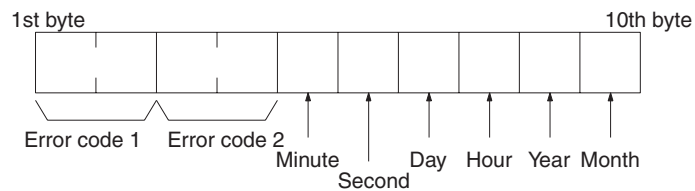
Error code 1, 2
Refer to *5-3-27 ERROR CLEAR: 21 01* for information on error codes. Refer to the relevant operation manual or installation guide for more details.

Each data record includes the minute, second, day of month, hour (0 to 23), year (the rightmost two digits), and month in BCD specifying the time that the error occurred.

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments

The response will contain only the command code and end code if the beginning record number is higher than the number of records contained in the PLC.

When the PLC does not have the specified number of records, all the records that have been stored in the PLC will be read and an address range overflow error will result.

If the data is too large and exceeds the permissible length of the response format, the part in excess will not be read and a normal response will be returned.

5-3-29 ERROR LOG CLEAR: 21 03

Clears all error log pointers to 0.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

```
┌──────┬──────┐
│  21  │  03  │
└──────┴──────┘
   ╲_____╱
   Command
   format
```

Response Format

```
┌──────┬──────┬──────────────┐
│  21  │  03  │              │
└──────┴──────┴──────────────┘
   ╲_____╱  ╲_____╱
   Command      End code
   format
```
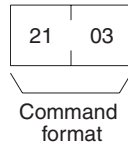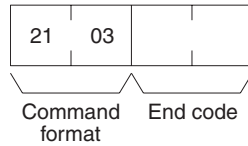
End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments   This command clears the number of error log records that are stored. It does not clear data from the error log area.

5-3-30 FINS WRITE ACCESS LOG READ: 21 40

The CPU Unit automatically keeps a log of any access for FINS write commands regardless of the setting. This command reads this log, which tells the nodes and time when there was access.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

```
┌──────┬──────┬──────┬──────┐
│  21  │  40  │      │      │
└──────┴──────┴──────┴──────┘
   ╲_____╱  ╲____╱  ╲____╱
   Command     Beginning  No. of
   code        record No. records
```

Response Format

```
┌──────┬──────┬──────┬──────┬──────┬─ ─ ─ ─ ─ ─┬────────┬─ ─ ─ ─┬──────────┐
│  21  │  40  │      │      │      │  12 bytes │        │       │ 12 bytes │
└──────┴──────┴──────┴──────┴──────┴─ ─ ─ ─ ─ ─┴────────┴─ ─ ─ ─┴──────────┘
   ╲_____╱  ╲____╱ ╲_____╱ ╲____╱ ╲_____╱  ╲_____╱        ╲_____╱
   Command    End code Max. No. of  No. of  No. of  Access log   · · · · · · ·  Access log
   code              stored records stored  records  data                     data
                                    records  read
```

Parameters   **Beginning record number (command)**
Specify the first record to be read. (The first record number is 0000 hex.)

Number of records (command, response)
Specify the number of records to read. The number of read records will be returned with the response.

Maximum number of stored records (response)
Indicates the maximum number of records that can be stored. (Always 20 records.)

Number of stored records (response)
Indicates the number of records recorded at the time the command is executed.

Access log data (response)
The specified access log records will be returned in sequence starting from the beginning record number. The total number of bytes required is calculated as follows:

No. of records x 12 bytes

The configuration of each error record is as follows:
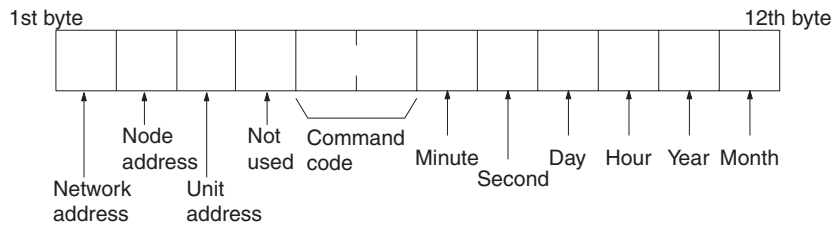
Network address
The network address of the node that sent the FINS write command.

Node address
The node address of the node that sent the FINS write command.

Unit address
The Unit address of the Unit that sent the FINS write command.

Command code
The command code of the FINS write command that was received (MR and MS).

Year, month, day, hour, minute, second, day of week
The year, month, day of month, hour, minute, and second are expressed in BCD.

Year: The rightmost two digits of the year. (1998, 1999, and 2000 are expressed as 98, 99, and 00 respectively. 2096 and 2097 will be expressed as 96 and 97.)

Hour: 00 to 23 (BCD).

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments

An end code of 1103 hex (address range overflow) will be returned if the beginning record number is higher than the number of records contained in the PLC.

When the PLC does not have the specified number of records, all the records that have been stored in the PLC will be read and a normal response will be returned.

If the data is too large and exceeds the permissible length of the response format, the part in excess will not be read and a normal response will be returned.

The following rules apply to records stored in the access log.

- If there is already a record for the same node, the old record will be overwritten with a new one.
- If there is not already a record for the same node, a new record will be created at the end of the log.
- If the log is full (i.e., 20 records have already been stored), the oldest record will be discarded and a new record will be created.

5-3-31 FINS WRITE ACCESS LOG CLEAR: 21 41

Clears the access log data.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

```
┌─────┬─────┐
│ 21  │ 41  │
└─────┴─────┘
   Command
    format
```

Response Format

```
┌─────┬─────┬─────┐
│ 21  │ 41  │     │
└─────┴─────┴─────┘
   Command   End code
    format
```
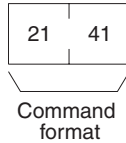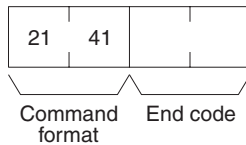
End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments   This command clears the access log data for FINS write commands.

5-3-32 FILE NAME READ: 22 01

Reads file data such as the names of files saved in file memory.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

```
┌─────┬─────┬─────┬─────┬─────┬─────┬ ─ ─ ─ ─ ─ ┐
│ 22  │ 01  │     │     │     │     │ . . . . . │
└─────┴─────┴─────┴─────┴─────┴─────┴ ─ ─ ─ ─ ─ ┘
  Command    Disk No.  Beginning  No. of  Directory  Absolute directory
   code              file position  files   length         path
```

Response Format

```
┌─────┬─────┬─────┬ ─ ─ ─ ─ ┬─────┬─────┬ ─ ─ ┬─────┐
│ 22  │ 01  │     │ 26 bytes│     │22 bytes│    │22 bytes│
└─────┴─────┴─────┴ ─ ─ ─ ─ ┴─────┴─────┴ ─ ─ ┴─────┘
  Command  End code  Disk data   No. of   File data  . . . . . . .  File data
   code                           files
                                          └─────────── Read file data ───────────┘
```
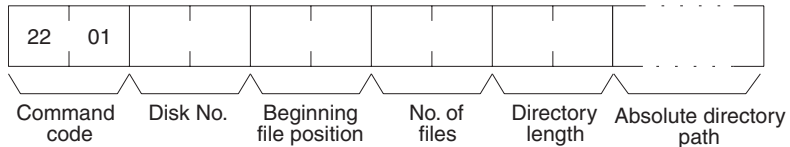
Parameters

<u>**Disk number (command)**</u>

The classification of the file memory with the file name to be read is specified as follows:

8000 (hex):   Memory card
8001 (hex):   EM file memory

<u>**Beginning file position (command)**</u>

The first file to be read. (The first file number is 0000 hex).

<u>**Number of files (command)**</u>

The number of file names to be read between 0001 and 0014 (hex). A maximum number of 20 file names can be read at one time. If there are more file names than that, add one to the number of response files when specifying the next beginning file position. To read disk data only, specify 0000 (hex) for both the beginning file position and the number of file names. A response will be returned for up to the number of files read.

<u>**Directory length**</u>

Indicates the length of the absolute directory path. The maximum number of characters is 65. To specify the root directory as the absolute directory path, specify 0000 (hex) as the directory length.

<u>**Absolute directory path**</u>

Indicates the absolute path from the root directory. It begins with \ (5C hex), and the drive name and colon (:) are not required. "\" is used to delimit the lower directory. It is not required at the end of the final absolute path. No setting is required to specify the root directory itself.

<u>**Disk data (response)**</u>

Indicates the file memory data. The configuration is as follows:
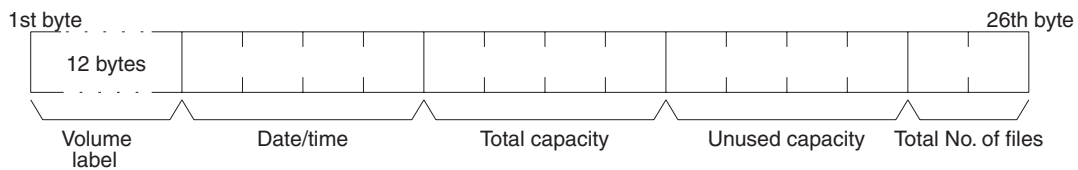
Volume Label

The volume label is the name registered with the file memory. For details on the configuration, refer to page 168.

Date and Time

The date and time show the date and time that the volume label was created.

Total Capacity and Open Capacity

The total capacity and open capacity show the total capacity of the file memory being used and the number of bytes still available (hexadecimal).

Total Number of Files

The number of files recorded in the absolute directory path. Volume labels, hidden files, system files, subdirectories, the current directory (indicated by .), and the parent directory (indicated by . .) are all counted as files. (The root directory can contain a volume label, but not a current directory or parent directory mark.)

Number of files (response)

The number of files that have been read. Bit 15 is ON (1) if the last file is included.

Bit 15 OFF (0): Without last file
Bit 15 ON (1): With last word file
Bits 0 to 14: No. of files read

Bits 0 to 7 (second byte)

Bits 8 to 15 (first byte)
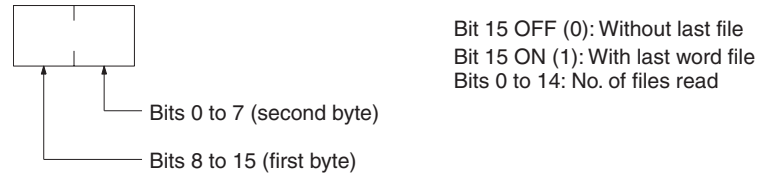
File data (response)

Each file data consists of 22 bytes. The specified files will be transmitted in sequence starting from the first file. The total number of bytes required is calculated as follows:

Number of read files x 22 bytes

The configuration for each file data is as follows:

1st byte
22nd byte
12 bytes

File name   Date/time   File capacity   Attribute
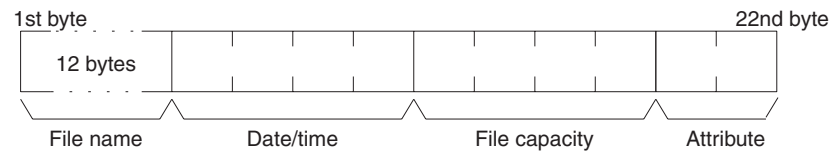
File Name

Specify the name of the file. Refer to *Volume Labels and File Names* on page 168 for the structure of file names.

Date and Time

Indicates the date and time at which the file was created. (See the note below for details of the configuration.)

File Capacity

Indicates the size (the number of bytes, in four digits hexadecimal) of the file.

Attribute

First byte   Second byte

Bit 15   8 7 6 5 4 3 2 1 0
     —   — — —

Reserved area

1: Read-only file
1: Hidden file
1: System file
1: Volume label
1: Subdirectory
1: Archive file
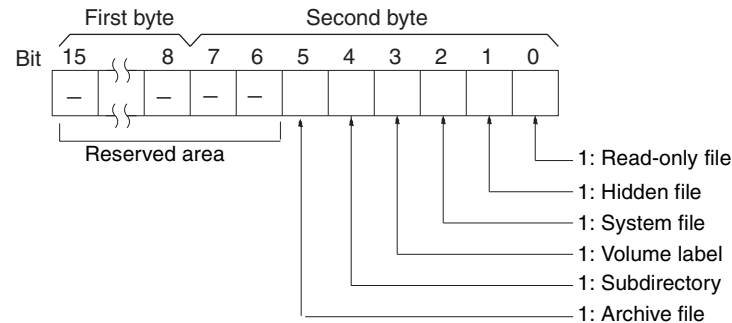
Note Date and Time Configuration:
The data and time consists of 4 bytes (32 bits) and is configured in the way shown below.

| | 1st byte | | 2nd byte | | 3rd byte | | 4th byte | |
| | Bit 31 to 25 | 24 to 21 | 20 to 16 | 15 to 11 | 10 to 5 | 4 to 0 |

Bit 31   to   25 24 to 21 20 to 16 15 to 11 10   to   5 4   to   0
     7 bits   4 bits   5 bits   5 bits   6 bits   5 bits

Year   Month   Day   Hour   Minute   Second
(0 to 119)   (1 to 12) (1 to 31)   (0 to 23)   (0 to 59)   (0 to 29)
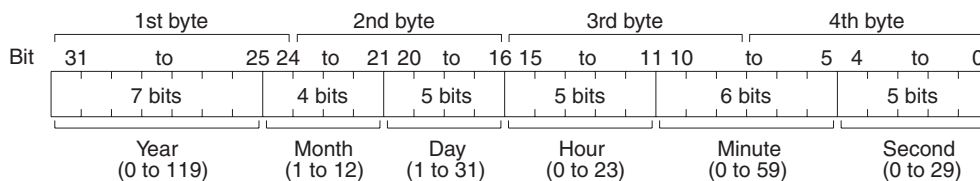
All data values are in binary.

Year: Add 1980 to the value returned. (The year is the number of years since 1980.)

Second: Multiply the value returned by two. (The value returned is expressed in units of two seconds.)

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

5-3-33 SINGLE FILE READ: 22 02

Reads the contents of a file stored in the file memory.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

22	02			12 bytes							

Command code · Disk No. · File name · File position · Data length · Directory length · Absolute directory path

Response Format

22	02								

Command code · End code · File capacity · File position · Data length · Data
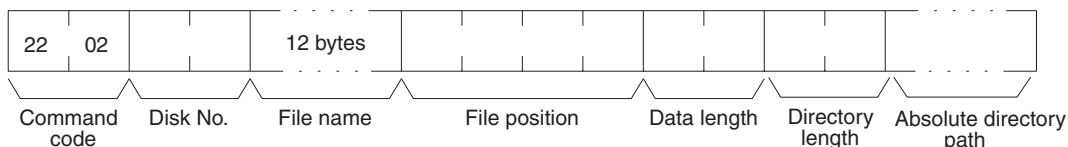
Parameters

Disk number (command)

The classification of the file memory with the file name to be read is specified as follows:

8000 (hex):   Memory card
8001 (hex):   EM file memory

File name (command)

Specify the name of the file to be read. For details on the configuration, refer to page 168.

File position (command)

Specify the number of bytes (the relative byte address) from the start of the file from which to start reading. (Files start at 00000000 hex.)

Data length (command)

Specify the number of bytes of data to read.

File capacity (response)

The capacity (bytes) of the file that was read is returned.

File position (response)

The position of the first data read is returned.

Data length (response)

The number of bytes of data read is returned. If the last data in the file is included, the leftmost bit in this parameter will be ON.

Data (response)

The specified data is returned in sequence starting from the specified byte.

Directory length

Indicates the length of the absolute directory path. The maximum number of characters is 65. To specify the root directory as the absolute directory path, specify 0000 (hex) as the directory length.

Absolute directory path

Indicates the absolute path from the root directory. It begins with \ (5C hex), and the drive name and colon (:) are not required. "\" is used to delimit the lower directory. It is not required at the end of the final absolute path. No setting is required to specify the root directory itself.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

By specifying 0000 (hex) as the file position and data length in the command, is possible to see if the file exists.

5-3-34 SINGLE FILE WRITE: 22 03

Writes a new file to the file memory or appends or overwrites an existing file stored in the file memory. Designation can be made to protect existing files if an attempt is made to create a new file of the same name as an existing file.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	**MONITOR mode**	**PROGRAM mode**
OK	OK	OK
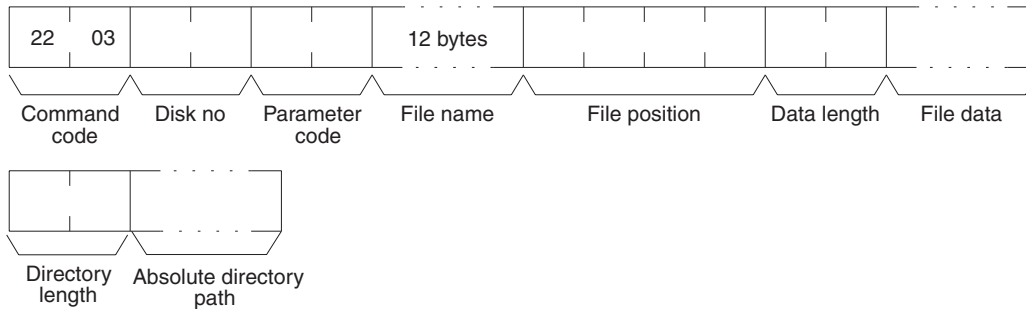
Command Format

Response Format
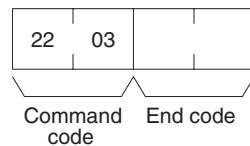
Parameters

Disk number (command)

The classification of the file memory with the file name to be read is specified as follows:
8000 (hex):   Memory card
8001 (hex):   EM file memory

Parameter code (command)
As follows:

0000 (hex)
Writes a new file. If a file with the same name already exists, the new file will not be created.

0001 (hex)
Writes a new file. If a file with the same name already exists, it will be overwritten

0002 (hex)
Adds data to an existing file.

0003 (hex)
Overwrites an existing file.

File name (command)
Specifies the name of the file to be written. For details on the configuration, refer to page 168.

File position (command)
Specifies the number of bytes from the start of the file from which to start writing. (Files start at 00000000.) To create a new file or add data to an existing file, specify 00000000 as the file position.

Data length (command)
Specifies the number of bytes to be written.

File data (command)
Specifies the data in sequence from the beginning position, in the amount specified in "data length."

Directory length (command)
Indicates the length of the absolute directory path. The maximum number of characters is 65. To specify the root directory as the absolute directory path, specify 0000 (hex) as the directory length.

Absolute directory path (command)
Indicates the absolute path from the root directory. It begins with \ (5C hex), and the drive name and colon (:) are not required. "\" is used to delimit the lower directory. It is not required at the end of the final absolute path. No setting is required to specify the root directory itself.

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments

Writing a new file or modifying an existing file must be done within the capacity of the file memory or the SINGLE FILE WRITE command cannot be executed.

When SINGLE FILE WRITE is executed, the clock data of the CPU Unit will be recorded as the date of the file.

5-3-35   FILE MEMORY FORMAT: 22 04

Formats file memory. Always execute FILE MEMORY FORMAT (command code 2204) before using a memory card or EM area as file memory.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

Command code 22 04

Disk No.

Response Format

Command code 22 04
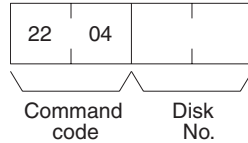
End code

Parameters

Disk number (command)
The classification of the file memory to be formatted is specified as follows:
8000 (hex): Memory card
8001 (hex): EM file memory

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

Comments

When FILE MEMORY FORMAT (command code 2204) is executed, all data registered to the file memory will be cleared. Before executing this command, check to be sure that it is okay to clear the data. Refer to file memory application procedures in the CPU Unit's operation manual for details on using file memory.

FILE MEMORY FORMAT is also used to return EM memory that has been converted to file memory back to its original form.

Even if only the size of the file memory is changed, the entire file memory will be formatted.

Note If the current EM bank is specified for file conversion in the PLC Setup when FILE MEMORY FORMAT is executed for the EM Area, an Area Missing error (end code 1101) will be returned and a PLC Setup setting error will occur in the CPU Unit. These errors, however, will not occur if the current bank is EM0.

5-3-36 FILE DELETE: 22 05

Deletes files registered to file memory.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

Command code 22 05

Disk No.

No. of files

File name 12 bytes

. . . .

File name 12 bytes

Directory length

Absolute directory path
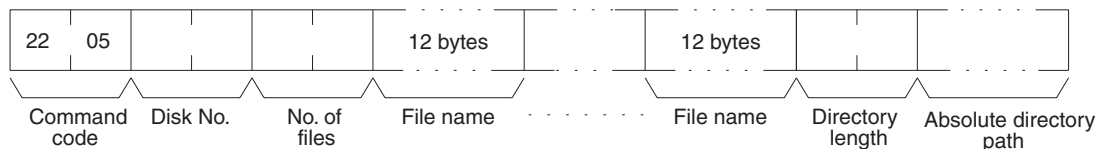
Response Format

Parameters

Disk number (command)

The classification of the file memory with the file to be deleted is specified as follows:

8000 (hex):   Memory card
8001 (hex):   EM file memory

Number of files (command)

Specify the number of files to be deleted.

File name (command)

Specify the name of the file to be deleted. For details on the configuration, refer to page 168.

Directory length

Indicates the length of the absolute directory path. The maximum number of characters is 65. To specify the root directory as the absolute directory path, specify 0000 (hex) as the directory length.

Absolute directory path

Indicates the absolute path from the root directory. It begins with \ (5C hex), and the drive name and colon (:) are not required. "\" is used to delimit the lower directory. It is not required at the end of the final absolute path. No setting is required to specify the root directory itself.

Number of files (response)

Indicates the number of files actually deleted.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

The specified files will be deleted in sequence. If non-existing file names have been specified, the PLC will ignore them and the operation will continue.

5-3-37 FILE COPY: 22 07

Copies a file from one file memory to another file memory connected to the same CPU Unit.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

Response Format

```
  22     07
```

Command code / End code

Parameters

Disk number (command)

The classification of the copy source and copy destination file memory is specified as follows:
8000 (hex):   Memory card
8001 (hex):   EM file memory

File name (command)

Specify the file to be copied and a new name for the copy destination file.

Directory length

Indicates the length of the absolute directory path. The maximum number of characters is 65. To specify the root directory as the absolute directory path, specify 0000 (hex) as the directory length.

Copy source and copy destination absolute directory path

Indicates the absolute path from the root directory. It begins with \ (5C hex), and the drive name and colon (:) are not required. "\" is used to delimit the lower directory. It is not required at the end of the final absolute path. No setting is required to specify the root directory itself.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

The file will not be copied if there is already a file of the same name at the destination.

The file will not be copied if an existing file name is given at the copy destination.

The copy destination file is given the same date as the copy source file.

5-3-38 FILE NAME CHANGE: 22 08

Changes a registered file name.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

```
  22     08              12 bytes     12 bytes
```

Command code / Disk No. / Old file name / New file name / Directory length / Absolute directory path

Response Format

```
  22     08
```

Command code / End code
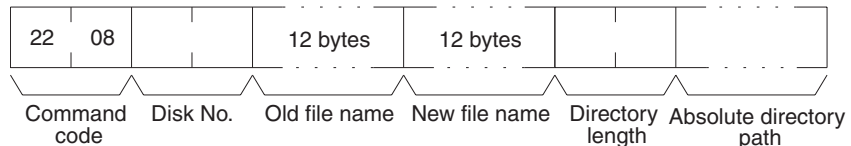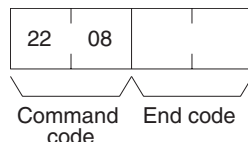
Parameters

Disk number (command)

The classification of the file memory where the file name to be changed is registered is specified as follows:

8000 (hex): Memory card

8001 (hex): EM file memory

Old and new file names (command)

Specify the original file name and a new name for the file. For details on the configuration, refer to page 168.

Directory length (command)

Indicates the length of the absolute directory path. The maximum number of characters is 65. To specify the root directory as the absolute directory path, specify 0000 (hex) as the directory length.

Absolute directory path (command)

Indicates the absolute path from the root directory. It begins with \ (5C hex), and the drive name and colon (:) are not required. "\" is used to delimit the lower directory. It is not required at the end of the final absolute path. No setting is required to specify the root directory itself.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

The file name will not be changed if an existing file name is specified for the new file.

Even if the name of a file is changed, the date of the file will remain unchanged.

Directory names can also be changed. Specify the directory name in place of the file name.

5-3-39 MEMORY AREA–FILE TRANSFER: 22 0A

Transfers or compares data between the I/O memory areas and the file memory.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK
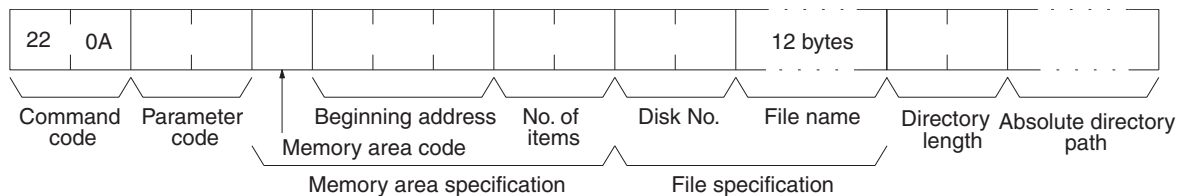
Command Format

Response Format

Parameters

Parameter code (command)
Specify the transfer/compare method as follows:

0000 (hex)
Data transfer from the I/O memory area to the file memory.

0001 (hex)
Data transfer from the file memory to the I/O memory area.

0002 (hex)
Data compared.

I/O memory area code, Beginning address (command)
The memory area to be used for data transfer or comparison, and the first address in the memory area to be transferred or compared.

The memory areas that can be written are given in the following table. Refer to *5-2-2 I/O Memory Address Designations* for the specific addresses that can be used.

Area		Data type	Mode memory area code (hex)	Bytes per element
CIO Area	CIO	Word	B0	2
Work Area	WR		B1	
Holding Bit Area	HR		B2	
Auxiliary Bit Area	AR		B3	
Timer Area	TIM	PV	89	2
Counter Area	CNT			
DM Area	DM	Word	82	2
EM Area	EM bank 0 to bank C	Word	A0 to AC	2
	EM current bank	Word	98	2

Number of items (command and response)
In the command format, specify the number of items, in word units, to be transferred or compared. In the response format, this parameter indicates the number of items transferred or successfully compared. Refer to *Element Data Configurations* on page 163 for the configuration of elements.

Disk number (command)
The classification of the file memory where the file to be transferred or compared is registered is specified as follows:
8000 (hex):   Memory card
8001 (hex):   EM file memory

File name (command)
Specify the file to be transferred or compared. For details on the configuration, refer to page 168.

Directory length
Indicates the length of the absolute directory path. The maximum number of characters is 65. To specify the root directory as the absolute directory path, specify 0000 (hex) as the directory length.

Absolute directory path
Indicates the absolute path from the root directory. It begins with \ (5C hex), and the drive name and colon (:) are not required. "\" is used to delimit the lower directory. It is not required at the end of the final absolute path. No setting is required to specify the root directory itself.

Comments
MEMORY AREA–FILE TRANSFER (command code 220A) can be executed regardless of the CPU Unit mode. It is the user's responsibility to program steps to prohibit this command from being executed when the CPU Unit is in RUN mode if such protection is necessary. Execute CPU UNIT STATUS READ (command code 0601) to read the CPU Unit's mode. (Refer to *5-3-17 CPU UNIT STATUS READ: 06 01.*)

If data is written to the Timer/Counter PV Area, the Completion Flags will not be turned OFF.

The CPU Unit clock data upon completion of MEMORY AREA–FILE TRANS-FER (command code 220A) will be recorded as the date of the file that has been transferred.

Files cannot be overwritten when transferring data from a memory area to file memory.

End code (response)
Refer to *5-1-3 End Codes* for information on end codes.

5-3-40 PARAMETER AREA–FILE TRANSFER: 22 0B

Compares or transfers data between the parameter area and the file memory.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK (See note.)

RUN mode	MONITOR mode	PROGRAM mode
OK (See note.)	OK (See note.)	OK

Note Data cannot be transferred from file memory to the parameter area.

Command Format
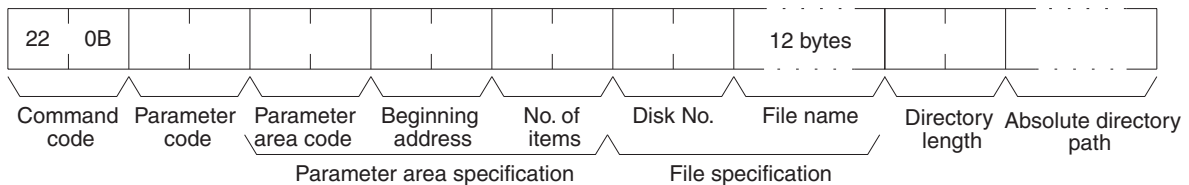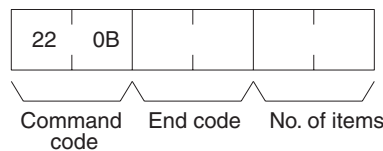
22	0B					12 bytes		

Command code · Parameter code · Parameter area code · Beginning address · No. of items · Disk No. · File name · Directory length · Absolute directory path

Parameter area specification   File specification

Response Format

22	0B		

Command code · End code · No. of items

Parameters
Parameter code (command)
Specify the transfer/compare method as follows:

0000 (hex)
Data transfer from the parameter area to the file memory.

0001 (hex)
Data transfer from the file memory to the parameter area.

0002 (hex)
Data compared.

Parameter area code (command)

Specify the parameter area to be used for data transfer or comparison. The rightmost byte is always 80 (hex), and the parameter area is specified with the leftmost byte.

Beginning address (command)

Specify the position in the parameter area for beginning the transfer or comparison. The beginning of each parameter area is always 0000.

Parameter Areas

There are six parameter areas, each of which has consecutive word addresses beginning from 0000. The areas that can be written to are shown below, along with their parameter area codes.

	Parameter area code	Address range (Hex)	Parameter area code	Address range (Hex)
PLC Setup Area	8010	0000 to 01FF (512 words)		
I/O Table Registration Area	8012	0000 to 04FF (1,280 words)	8000	0000 to 1F3F 8000 words)
Routing Table Area	8013	0000 to 01FF (512 words)		
CPU Bus Unit Setup Area	8002	0000 to 143F (5184 words)		

Number of items (command and response)

In the command format, the number of items is always FFFF (hex) so that the entire parameter area is specified. In the response format, the number of words transferred is indicated when data is transferred. When data is compared, the response format indicates the position at which a verification error occurs or the number of words compared.

Disk number (command)

The classification of the file memory where the file to be transferred or compared is registered is specified as follows:
8000 (hex):   Memory card
8001 (hex):   EM file memory

File name (command)

Specify the file to be transferred or compared. For details on the configuration, refer to page 168.

Directory length (command)

Indicates the length of the absolute directory path. The maximum number of characters is 65. To specify the root directory as the absolute directory path, specify 0000 (hex) as the directory length.

Absolute directory path (command)

Indicates the absolute path from the root directory. It begins with \ (5C hex), and the drive name and colon (:) are not required. "\" is used to delimit the lower directory. It is not required at the end of the final absolute path. No setting is required to specify the root directory itself.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

The clock data upon completion of a parameter area to file memory transfer will be recorded as the date of the file that has been transferred.

A file can be transferred to the I/O table only when the CPU Unit is in PROGRAM mode.

This command cannot be executed if any other device holds the access right.

Files cannot be overwritten when transferring data from the parameter area to file memory.

5-3-41 PROGRAM AREA–FILE TRANSFER: 22 0C

Compares or transfers data between the program area and the file memory.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	**No** (See Note 1.)

RUN mode	MONITOR mode	PROGRAM mode
OK (See note 2.)	OK (See note 2.)	OK

Note   1. Data can be transferred from the program area to the file memory.

2. Data cannot be transferred from file memory to the program area in these modes.

Command Format
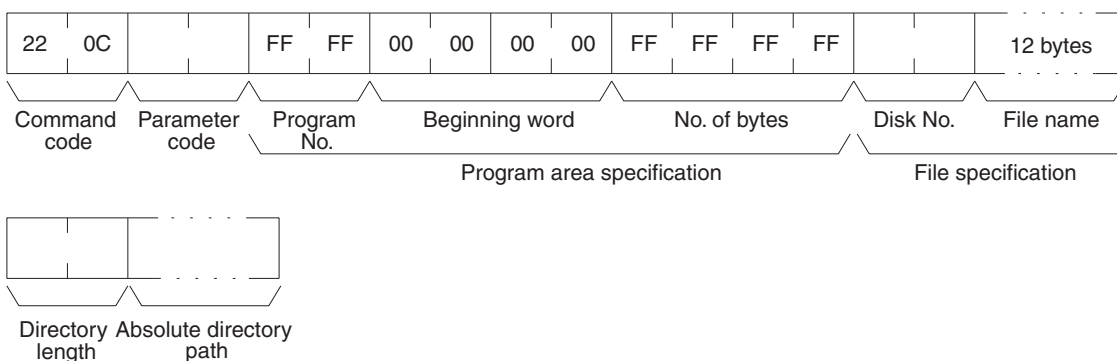
Response Format
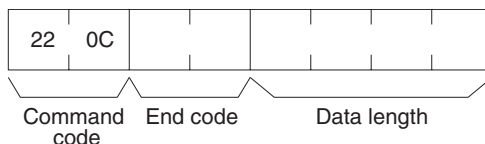
Parameters   **Parameter code (command)**
Specify the transfer/compare method as follows:

0000 (hex)
Data transfer from the program area to the file memory.

0001 (hex)
Data transfer from the file memory to the program area.

0002 (hex)
Data compared.

Program number and beginning word (command)
Always FFFF (hex).

Beginning word (command)
Always 00000000 (hex).

Number of bytes (command)
Specify the number of data bytes to be transferred or compared. Always FFFFFFFF (hex).

<u>**Disk number (command)**</u>
The classification of the file memory where the file to be transferred or compared is registered is specified as follows:
8000 (hex):   Memory card
8001 (hex):   EM file memory

<u>**File name (command)**</u>
Specify the name of the file to be transferred or compared. For details on the configuration, refer to page 168.

<u>**Data length (response)**</u>
When data is transferred, the data length parameter indicates the number of bytes that have been transferred. When data is compared, this parameter indicates the amount of data that was compared with no errors, or the number of bytes compared in a normal completion.

<u>**Directory length (response)**</u>
Indicates the length of the absolute directory path. The maximum number of characters is 65. To specify the root directory as the absolute directory path, specify 0000 (hex) as the directory length.

<u>**Absolute directory path (response)**</u>
Indicates the absolute path from the root directory. It begins with \ (5C hex), and the drive name and colon (:) are not required. "\" is used to delimit the lower directory. It is not required at the end of the final absolute path. No setting is required to specify the root directory itself.

<u>**End code (response)**</u>
Refer to *5-1-3 End Codes* for information on end codes.

Comments

The clock data upon completion of a program area to file memory transfer will be recorded as the date of the file that has been transferred.

This command cannot be executed if any other device holds the access right or when memory is write-protected via pin 1 of the DIP switch on the front panel of the CPU Unit.

PROGRAM AREA–FILE TRANSFER (command code 220C) cannot be executed when the CPU Unit is in the RUN or MONITOR mode.

Files cannot be overwritten when transferring data from the program area to file memory.

5-3-42 CREATE/DELETE DIRECTORY: 22 15

Creates or deletes a directory.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

Command code | Disk No. | Parameter | Directory name | Directory length | Absolute directory path
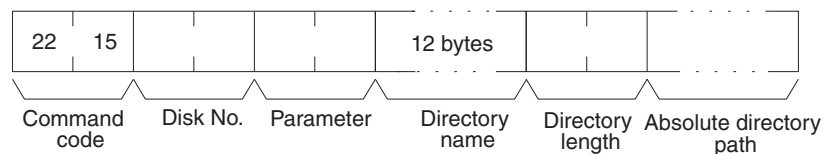
Response Format
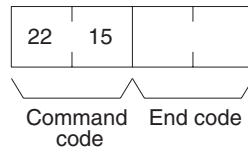
Parameters

Disk number (command)

The classification of the file memory where the directory is to be created or deleted is specified as follows:

8000 (hex): Memory card

8001 (hex): EM file memory

Parameter (command)

Specify either creation or deletion as follows:

0000 (hex): Create

0001 (hex): Delete

Directory name (command)

Specify the name of the directory to be created or deleted. For details on the configuration, refer to page 168. If the directory name is less than 12 bytes, fill unused bytes with 20 hex.

Directory length (command)

Indicates the length of the absolute directory path. The maximum number of characters is 65. To specify the root directory as the absolute directory path, specify 0000 (hex) as the directory length.

Absolute directory path (command)

Indicates the absolute path from the root directory. It begins with \ (5C hex), and the drive name and colon (:) are not required."\" is used to delimit the lower directory. It is not required at the end of the final absolute path. No setting is required to specify the root directory itself.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

The CPU Unit's clock data will be recorded as the date of any directory that is created.

5-3-43 MEMORY CASSETTE TRANSFER (CP-series CPU Units Only): 22 20

Transfers or verifies data between a Memory Cassette mounted in a CP-series CPU Unit (see note) and the memory areas in the CP-series CPU Unit. Transfers can go either direction.

Applicable data	Storage location in CPU Unit
User program	RAM (user program area)
Parameter area (PLC Setup, CPU Bus Unit settings, and routing tables)	RAM (parameter area)
Symbol table	Built-in flash memory (Comment Memory Area)
Comments (I/O comments, row comments, and annotations)	Built-in flash memory (Comment Memory Area)
Program indices (section names, section comments, and program comments)	Built-in flash memory (Comment Memory Area)
Function block sources	Built-in flash memory (Function Block Source Memory Area)
Data memory	RAM (DM Area D0 to D32767)
Data memory initial values	Built-in flash memory (Data memory initial value area)

Note This command is supported only by CP-series CPU Units.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
No	OK	OK (See note.)

RUN mode	MONITOR mode	PROGRAM mode
No	No	OK

Note Data cannot be transferred from the CPU Unit to the Memory Cassette when the user program is included and DIP switch UM protection is set.

Command Format
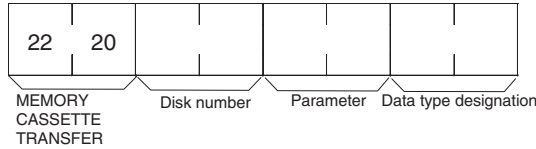
Response Format

Other Memory Cassette Operations (Parameter ≠ 8000 Hex)
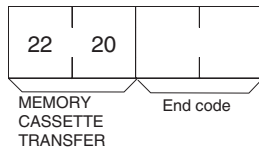
Reading the Data Type in the Memory Cassette (Parameter = 8000 Hex)
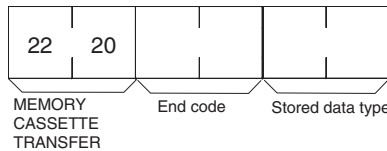
Parameters

Disk number (command)

Specify the disk for transfer or verification. Only the Memory Cassette can be specified.

8003 (hex):   Memory Cassette

Parameter (command)

Specify the transfer or verification method.

0000 (hex):   Transfer (CPU Unit to Memory Cassette)
0001 (hex):   Transfer (Memory Cassette to CPU Unit)
0002 (hex):   Verify (between CPU Unit and Memory Cassette)
0003 (hex):   Initialize Memory Cassette
8000 (hex):   Read data type in Memory Cassette

Data type designation (command)

Bit 15: All or individual area designation (OFF: All, ON: Individual areas)

OFF: All areas for bits 00 and 02 through 07 (See note.)

ON: Only areas specified by bits 00 and 02 through 07 (Multiple bits can be turned ON.)

Bits 14 to 08: Reserved
Bit 07: Data memory initial values
Bit 06: Data memory
Bit 05: Program indices
Bit 04: Comments
Bit 03: Symbol table
Bit 02: parameter area

Bit 01: Reserved

Bit 00: User program + Function block sources

Note If bit 15 is OFF and any of bit 02 or bits 02 to 07 is ON, an Other Parameter Error will occur and an end code of 110C hex will be returned.

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Stored data type (response)

When reading the data type in the Memory Cassette (parameter = 8000 hex), the following bits corresponding to the stored data will be turned ON. (More than one bit may be turned ON.)

Bit 07: Data memory initial values

Bit 06: Data memory

Bit 05: Program indices

Bit 04: Comments

Bit 03: Symbol table

Bit 02: Parameter area

Bit 01: Function block sources

Bit 00: User program

5-3-44 FORCED SET/RESET: 23 01

Force-sets (ON) or force-resets (OFF) bits/flags or releases force-set status. Bits/flags that are forced ON or OFF will remain ON or OFF and cannot be written to until the forced status is released.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
No	OK	OK

Note "Forced status" means that the ON/OFF status of the bit/flag is forcibly retained and writing is prohibited.

Command Format
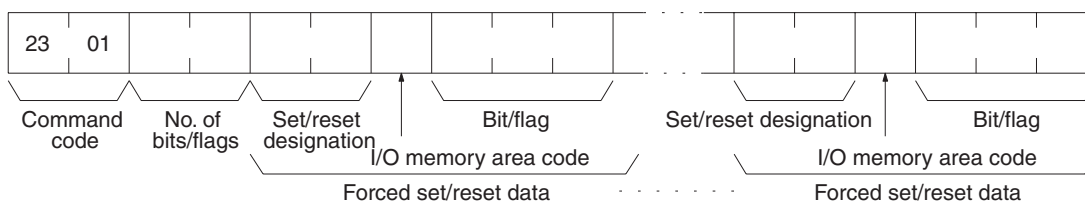
Response Format
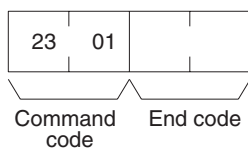
Parameters

Number of bits/flags (command)

Specify the number of bits/flags to be controlled.

Set/reset designation (command)

Specify the action to be taken for each bit/flag.

Value (hex)	Name	Operation
0000	Forced reset	Turns OFF (0) the bit/flag and places it in forced status. (See note.)
0001	Forced set	Turns ON (1) the bit/flag and places it in forced status.
8000	Forced set/reset OFF release	Turns OFF (0) the bit/flag and releases the forced status.
8001	Forced set/reset ON release	Turns ON (1) the bit/flag and releases the forced status.
FFFF	Forced set/reset release	Releases the forced status while retaining the ON/OFF status.

I/O memory area code (command)

Specify the I/O memory area of the bit or flag to be controlled.

Bit/Flag (command)

Specify the bit or flag to be controlled. The memory areas in which bits/flags can be controller are given in the following table. Refer to *5-2-2 I/O Memory Address Designations* for the specific addresses that can be used.

Area		Data type	CS/CJ mode memory area code (hex)	CV mode memory area code (hex)	Bytes per element
CIO Area	CIO	Bit	30	00	1
Work Area	WR		31	---	
Holding Bit Area	HR		32	---	
Timer Area	TIM	Completion Flag	09	01	1
Counter Area	CNT				

End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments   To force set/reset multiple bits/flags, specify the "set/reset designation," the "I/O memory area code," and the "bit/flag" parameters for the number of bits/flags set in the "number of bits/flags" parameter.

Note If "forced set/reset OFF release (8000)" or "forced set/reset ON release (8001)" is exceeded for a bit/flag that does not have forced status, only the bit/flag's ON/OFF status will be affected.

5-3-45 FORCED SET/RESET CANCEL: 23 02

Cancels all bits (flags) that have been forced ON or forced OFF.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
No	OK	OK

Command Format
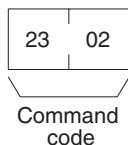
```
   23   02
   └────┘
   Command
   code
```

Response Format

```
   23   02    |    |
   └────┘ └────┘
   Command  End code
   code
```
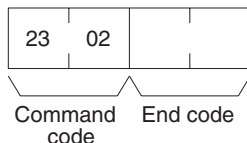
End code (response)

Refer to *5-1-3 End Codes* for information on end codes.

Comments

The bits/flags in the following memory areas can be forced set or forced reset, and canceled.

Memory area	Data
Relay areas	Bit status
Timer/Counter	Completion Flag status

5-3-46 CONVERT TO COMPOWAY/F COMMAND: 28 03

When this command is sent to a CS/CJ-series CPU Unit with unit version 3.0 or later, serial port C on the Controller Section of an NSJ Controller, serial port 1 or 2 on an Option Board of a CP-series CPU Unit, or a serial port on a Serial Communications Unit/Board (version 1.2 or later), the CPU Unit or Serial Communications Unit/Board removes the FINS header and sends the enclosed CompoWay/F command.

With this command, OMRON components connected to a PLC through CompoWay/F communications can be accessed from a PLC or PT by sending a FINS message containing a CompoWay/F command.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

```
   28   03    |    |    30   30   30    |    |    |    ┄┄┄┄
   └────┘ └────┘ └───────────┘ └────┘ └────┘

   Command   Node     Subaddress: CompoWay/ CompoWay/F  CompoWay/F
   code      number   00          F         command     text
             (ASCII)  (3030 in    SID: 0    code (ASCII (ASCII code)
                      ASCII)      (30 in    code)
                                  ASCII)
```
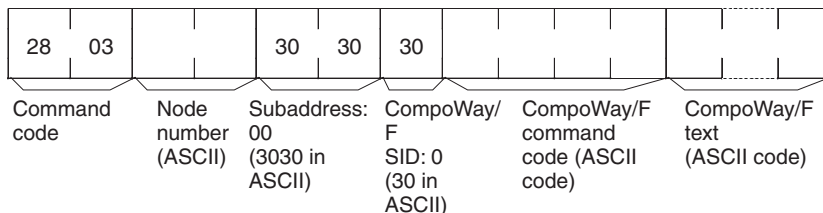
Response Format
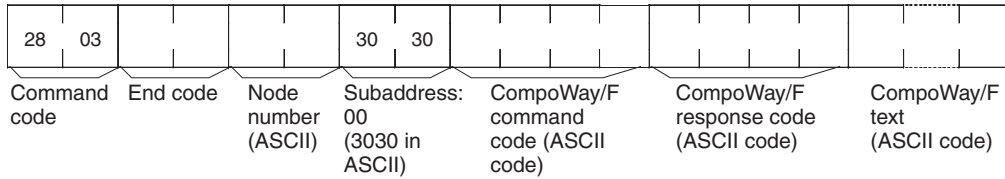
Parameters

Command

Node Number

This is the destination ID number (00 to 99 or XX) in the CompoWay/F system. The characters are specified in ASCII. When sending a broadcast transmission, set the node number to XX (two X's).

Subaddress

The subaddress is 00 for most models and the value is specified in ASCII as 3030 hex. For some models, other values must be set.

CompoWay/F SID (Service ID)

The Service ID is 0 for most models and the value is specified in ASCII as 30 hex. For some models, other values must be set.

CompoWay/F Command Code

This is the CompoWay/F command code. For details, refer to the command manual for the CompoWay/F Slave.

CompoWay/F Text (Command and Response)

This is the data that follows the command code.

Response

Node Number

This is the destination ID number (00 to 99 or XX) in the CompoWay/F system. The characters are specified in ASCII. When a broadcast transmission is sent, the node number is set to XX (two X's).

Subaddress

The subaddress is 00 for most models and the value is specified in ASCII as 3030 hex. For some models, other values must be set.

CompoWay/F SID (Service ID)

The Service ID is 0 for most models and the value is specified in ASCII as 30 hex. For some models, other values must be set.

End Code (Response)

The end code indicates the command frame's execution result. (The end code is not the same as the response code, which is described below.)

CompoWay/F Command Code

This is the CompoWay/F command code. For details, refer to the command manual for the CompoWay/F Slave.

CompoWay/F Response Code

The CompoWay/F response code indicates the results of the service requested by the command code. For details, refer to the command manual for the CompoWay/F Slave.

CompoWay/F Text

This is the data that follows the response code.

Precautions

- FINS Header (Destination Address)
  The following settings are required.

- Destination Network Address (DNA):
  - When a routing table is created to treat the serial communications path as a network, this is the network address associated with the Serial Communications Unit or Board's serial port by the routing table
  - When a routing table is not created to treat the serial communications path as a network, this is the actual network address used to specify the destination PLC.

- Destination Node Address (DA1):
  - When a routing table is created to treat the serial communications path as a network, set 00 hex for communications within the local PLC or the "Host Link unit number + 1" for serial → serial → serial conversion.
  - When a routing table is not created to treat the serial communications path as a network, this is the actual node address used to specify the destination PLC (the "Host Link unit number + 1" for serial → serial → serial conversion).

- Destination Unit Address (DA2):
  This is the serial port's unit address.
  Settings for a Serial Communications Board or Unit:

  - Unit addresses for serial port 1:

Unit number	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	Board
Hexadecimal	80	84	88	8C	90	94	98	9C	A0	A4	A8	AC	B0	B4	B8	BC	E4
Decimal	128	132	136	140	144	148	152	156	160	164	168	172	176	180	184	188	228

  - Unit addresses for serial port 2:

Unit number	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	Board
Hexadecimal	81	85	89	8D	91	95	99	9D	A1	A5	A9	AD	B1	B5	B9	BD	E5
Decimal	129	133	137	141	145	149	153	157	161	165	169	173	177	181	185	189	229

- Sending CompoWay/F Commands with the CMND Instruction
  - Set FINS command code 2803 hex (CONVERT TO COMPOWAY/F) in S.
  - Set the following parameters starting at S+1 in ASCII with the leftmost byte first: CompoWay/F node number (2-byte ASCII), subaddress (2-byte ASCII), SID (2-byte ASCII), CompoWay/F command MRC (2-byte ASCII), CompoWay/F command SRC (2-byte ASCII), and text (ASCII, $2 \times n$ bytes)

  Note For CompoWay/F, set SID 0 (1-byte ASCII: 30 hex) in the leftmost byte of S+3 and the most significant digit of the CompoWay/F command code's MRC (1-byte ASCII) in the rightmost byte of S+3. Set the least significant digit of the CompoWay/F command code's MRC (1-byte ASCII) in the leftmost byte of S+4 and the most significant digit of the CompoWay/F command code's SRC (1-byte ASCII) in the rightmost byte of S+4. Be sure to set the remaining data with this 1-byte offset as well.

5-3-47 CONVERT TO MODBUS-RTU COMMAND: 28 04

When this command is sent to a CS/CJ-series CPU Unit with unit version 3.0 or later, serial port C on the Controller Section of an NSJ Controller, serial port 1 or 2 on an Option Board of a CP-series CPU Unit, or a serial port on a Serial Communications Unit/Board (version 1.2 or later), the CPU Unit or Serial Communications Unit/Board removes the FINS header and sends the enclosed Modbus-RTU command.

With this command, OMRON components connected to a PLC through Modbus-RTU communications can be accessed from a PLC or PT by sending a FINS message containing a Modbus-RTU command.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

Command code | Slave address | Function code | Communications data
28 04

Response Format

Command code | End code | Slave address | Function code | Communications data
28 04

Parameters

Command

Slave Address

Specify the Modbus-RTU device address. Set the address in hexadecimal between 01 and F7 hex (1 to 247 decimal).

Function Code

Specify the function code of the Modbus-RTU command. Set the address in hexadecimal between 01 and FF hex (1 to 255 decimal).

Communications Data

Specify the required parameters associated with the function code. The amount of communications data varies. (In some cases, there is no communications data.)

Response

The response is the same as the command except that it contains an end code.

Precautions

• FINS Header (Destination Address) Contents
The following settings are required.

• Destination Network Address (DNA):

- When a routing table is created to treat the serial communications path as a network, this is the network address associated with the Serial Communications Unit or Board's serial port by the routing table

- When a routing table is not created to treat the serial communications path as a network, this is the actual network address used to specify the destination PLC.

- Destination Node Address (DA1):

  - When a routing table is created to treat the serial communications path as a network, set 00 hex for communications within the local PLC or the "Host Link unit number + 1" for serial → serial → serial conversion.

  - When a routing table is not created to treat the serial communications path as a network, this is the actual node address used to specify the destination PLC (the "Host Link unit number + 1" for serial → serial → serial conversion).

- Destination Unit Address (DA2):
  This is the serial port's unit address.
  Settings for a CPU Unit:

CPU Unit

Peripheral port

RS-232C port

CPU Unit port	Unit address of port
Peripheral port	FD hex (253 decimal)
RS-232C port	FC hex (252 decimal)

Settings for a Serial Communications Board or Unit:

- Unit addresses for serial port 1:

Unit number	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	Board
Hexadecimal	80	84	88	8C	90	94	98	9C	A0	A4	A8	AC	B0	B4	B8	BC	E4
Decimal	128	132	136	140	144	148	152	156	160	164	168	172	176	180	184	188	228

- Unit addresses for serial port 2:

Unit number	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	Board
Hexadecimal	81	85	89	8D	91	95	99	9D	A1	A5	A9	AD	B1	B5	B9	BD	E5
Decimal	129	133	137	141	145	149	153	157	161	165	169	173	177	181	185	189	229

- Sending Modbus-RTU Commands with the CMND Instruction

  - Set FINS command code 2804 hex (CONVERT TO MODBUS-RTU COMMAND) in S.

  - Set the following parameters starting at S+1 with the leftmost byte first (see note): Slave address (1 byte), Function code (1 byte), and the communications data (n bytes).

  Note For Modbus-RTU, set the Modbus-RTU Slave address (1 byte) in the leftmost byte of S+1 and the function code (1 byte) in the rightmost byte of S+1.

5-3-48 CONVERT TO MODBUS-ASCII COMMAND: 28 05

When this command is sent to a serial port on a Serial Communications Unit or Board (Ver. 1.2 or later), the Serial Communications Unit/Board removes the FINS header and sends the enclosed Modbus-ASCII command.

With this command, OMRON components connected to a PLC through Modbus-ASCII communications can be accessed from a PLC or PT by sending a FINS message containing a Modbus-ASCII command.

Execution Conditions

Access right at other device	UM read protection	DIP switch UM protection
OK	OK	OK

RUN mode	MONITOR mode	PROGRAM mode
OK	OK	OK

Command Format

Command code	Slave address (ASCII)	Function code (ASCII)	Communications data (ASCII)
28 05			

Response Format

Command code	End code	Slave address (ASCII)	Function code (ASCII)	Communications data (ASCII)
28 05				
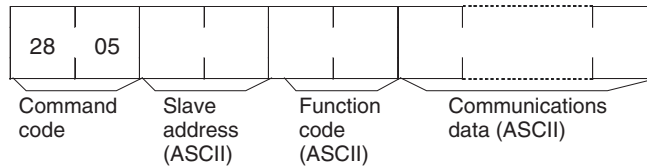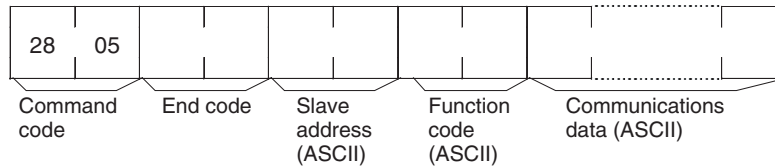
Parameters

Command

Slave Address

Specify the Modbus-ASCII device address. Set the address in ASCII between 01 and F7 hex (3031 to 4637 ASCII), which is 1 to 247 in decimal.

Function Code

Specify the function code of the Modbus-ASCII command. Set the address in ASCII between 01 and FF hex (3031 to 4646 ASCII), which is 1 to 255 in decimal.

Communications Data

Specify the required parameters (in ASCII) associated with the function code. The amount of communications data varies. (In some cases, there is no communications data.)

Response

The response is the same as the command except that it contains an end code.

Precautions

- FINS Header (Destination Address) Contents
  The following settings are required.

- Destination Network Address (DNA):

  - When a routing table is created to treat the serial communications path as a network, this is the network address associated with the Serial Communications Unit or Board's serial port by the routing table

- When a routing table is not created to treat the serial communications path as a network, this is the actual network address used to specify the destination PLC.

- Destination Node Address (DA1):

  - When a routing table is created to treat the serial communications path as a network, set 00 hex for communications within the local PLC or the "Host Link unit number + 1" for serial → serial → serial conversion.

  - When a routing table is not created to treat the serial communications path as a network, this is the actual node address used to specify the destination PLC (the "Host Link unit number + 1" for serial → serial → serial conversion).

- Destination Unit Address (DA2):
  This is the serial port's unit address.
  Settings for a CPU Unit:

CPU Unit

Peripheral port
RS-232C port

CPU Unit port	Unit address of port
Peripheral port	FD hex (253 decimal)
RS-232C port	FC hex (252 decimal)

Settings for a Serial Communications Board or Unit:

- Unit addresses for serial port 1:

Unit number	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	Board
Hexadecimal	80	84	88	8C	90	94	98	9C	A0	A4	A8	AC	B0	B4	B8	BC	E4
Decimal	128	132	136	140	144	148	152	156	160	164	168	172	176	180	184	188	228

- Unit addresses for serial port 2:

Unit number	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	Board
Hexadecimal	81	85	89	8D	91	95	99	9D	A1	A5	A9	AD	B1	B5	B9	BD	E5
Decimal	129	133	137	141	145	149	153	157	161	165	169	173	177	181	185	189	229

- Sending Modbus-ASCII Commands with the CMND Instruction

  - Set FINS command code 2805 hex (CONVERT TO MODBUS-ASCII COMMAND) in S.

  - Set the following parameters in ASCII starting at S+1 with the leftmost byte first: Slave address (2-byte ASCII), Function code (2-byte ASCII), and the communications data (ASCII, 2 × n bytes).

  Note For Modbus-RTU, set the Modbus-RTU Slave address (1 byte) in the leftmost byte of S+1 and the function code (1 byte) in the rightmost byte of S+1.

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Revision History

A manual revision code appears as a suffix to the catalog number on the front cover of the manual.

Cat. No. W342-E1-11
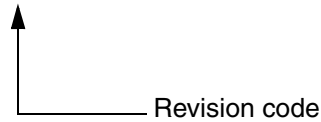
Revision code

The following table outlines the changes made to the manual during each revision. Page numbers refer to the previous version.

Revision code	Date	Revised content
01	February 1999	Original production
02	September 1999	**Page 18:** Catalog number corrected for the CQM1 PC. **Pages 31, 117:** The S+2 beginning read address for the first command word corrected for CMND(490).
03	April 2000	**Page 26:** Internal communications setting added for DA1 and SA1. **Page 28:** Values for node address changed in table. **Page 37:** Last two sentences removed from SA2 description.
04	May 2001	Changes were made throughout the manual to include information for new products (CJ1G-CPU44/45 and CJ1W-SCU41). In addition, the following changes were made. **Page 15:** Information on words per frame and the response format for MS commands added. **Page 18:** Note added after first table. **Page 45:** Information on formats for commands to and responses from the host computer added. **Page 57:** Information on end code 23 changed. **Page 60:** Description of "UM Area, Read-protected" changed. **Page 63:** Information added under "Limitations." **Page 85:** Text under second format diagram changed. **Page 88:** Some error names in the response format diagram changed. **Page 118:** Information on volume labels and file names changed. **Page 125:** Information under "Comments" changed. **Page 131:** Command format diagram changed. **Pages 154, 157, 158, 160, 161, 163, 164, 166, 167:** Description of directory length changed. **Pages 155, 157, 158, 160, 161, 163, 165, 166, 167:** Description of absolute directory path changed. **Page 156:** Information on attribute, and date and time added. "12 bytes" removed from response format diagram. **Pages 158, 160:** Reference added under "file name." **Page 160:** Second paragraph under "Comments" removed. **Page 161:** Sentence added to first paragraph. Reference added under "old and new file names." **Page 167:** Changes made to information under "directory name."
05	October 2001	Changes were made throughout the manual to include information for new products (CS1G/H-CPU□□H and CJ1G/H-CPU□□H). In addition, the following changes were made. **Page ix:** Table updated. **Pages 16, 21:** New models added. **Page 49:** Response Wait Time description corrected. **Page 115:** "06: Program missing" corrected. **Page 117:** "02: Parity of checksum" corrected. **Page 118:** "SFC" removed from "01: No access right." **Page 120:** Two illustrations added and top illustration reworded. **Page 125:** "Hex" added. **Page 128:** Notes added. **Page 132:** Sentence added after table. **Page 135:** Addition made to bottom of page. **Page 137:** Sentence added toward end of 5-3-8. **Pages 139 and 140:** Number corrected at end of 5-3-10 and 5-3-11. **Page 140:** Number of bytes description corrected. **Page 141:** "All clear" removed twice and "execution" changed to "cyclic" twice. **Page 143:** Addition made to command format and sentence added to end of 5-3-14. **Page 144:** End of CPU Unit model and version description corrected. **Page 145:** "Always 23" added to table. **Page 151:** Addition made to response format. **Page 161:** Last two lines removed. **Page 162:** End of 5-3-28 corrected. **Page 178:** Note moved. **Page 179:** Table column removed.

Revision History

Revision code	Date	Revised content
06	August 2002	"PC" was changed to "PLC" throughout the manual in the sense of "Programmable Controller." CJ1M CPU Units and new versions of Serial Communications Units/Boards were added. **Page 28:** Description of GCT changed. **Page 35:** Note added. **Page 125:** Information added following table.
07	May 2003	Changes were made throughout the manual to include information for new products (CS1D-CPU☐☐H and CJ1G/H-CPU☐☐EV1). **Page ix:** Table updated to correct catalog numbers and add new catalogs. **Page xiii:** A caution added regarding back up information. **Page xiv:** Corrected "CJ Series CPU Units" to "CJ1, CJI-H, CJ1M, or CS1D CPU Units." **Page xv:** A caution added regarding operating differences between CS1 and CJ1, CJI-H, CJ1M, or CS1D CPU Units when using factory settings. **Page 22:** Table corrected to include new CS/CJ-series models. **Page 30** "00 0A Hex" for first read address in graphic corrected to "0A 00 Hex." **Page 55:** Order of steps 9 and 10 corrected in graphic. **Page 93:** "Bit 1" corrected to "Bit 0" in graphic of response format. **Page 113:** Note on flags in end code added. **Page 119, 120:** Information on flags in end codes and handling errors changed. **Page 132:** "00" corrected to "---" in CV mode memory area code column for CIO Area and AR Area. **Page 150:** Information on operating status parameters updated for new models. **Page 151:** "Reserved for system" changed to "1: Duplex error" in bit 14 of non-fatal error data response. **Page 163:** Table of error codes updated for new models.
08	December 2003	**Pages xi to xvii:** PLP information updated. **Front of manual:** Information added on unit versions. **Pages 4, 5, 110, and 111:** Note and references to it added and 21 40 and 21 41 added. **Pages 24 and 28:** Note added. **Page 45:** Information on destination unit address changed. **Page 55:** Addresses corrected in program **Page 110:** **Pages 111 to 113:** Column added and 21 40 and 21 41 added. **Pages 146 and 167:** "Version" changed to "internal system version." **Page 163:** "FFFF" added to table. **Page 166:** Sections added on 21 40 and 21 41.
09	August 2004	"CompoBus/D" was changed to "DeviceNet" throughout the manual. **Pages 8, 38, and 111:** Notes added. **Page 15:** Section 2-4 replaced. **Page 24:** Note changed. **Page 28:** Description of ICV and RSV changed. **Pages 28, 29, 41, 49, and 50:** Information on GCT changed. **Pages 28, 29, 31, 40, 45, 46, and 48:** Information added on new Ethernet Units and other settings changed. **Page 33:** Information on unit addresses added. **Page 34:** Graphic changed. **Page 35:** Values for gateway count changed. **Pages 39, 41, 44, 45, 47, 49, and 50:** Values of GCT/RSV changed. **Page 41:** Description of RSV changed. **Page 58:** Section added. **Page 70:** Status definitions added to graphic. **Pages 111 and 113:** Commands added to table. **Page 185:** Commands 28 03, 28 04, and 28 05 added.
10	January 2006	**Page v:** Information on general precautions notation added. **Page xxiii:** Information on liability and warranty added.
11	October 2006	Corrections and additions were made throughout the manual to include the following Unit: CP-series PLCs, CJ1G-CPU☐☐P, X-, XA-, and Y-type CP1H CPU Units, NSJ Controllers, and version 1 of the Serial Communications Units. Other changes and corrections are as follows: **Pages x to xvi:** Changed and expanded**.** **Pages xix and xx:** Models and manuals added. **Page xxxiv:** Added precaution on dispose of the product and batteries. **Pages 5, 149, 152, and 223:** Added MEMORY CASSETTE TRANSFER command. **Page 15:** Replaced most of page. **Page 19:** Corrected last two rows of table. **Page 41:** Changed last part of note 1. **Pages 72 and 78:** Changed "PC" to "PLC" (multiple places). **Pages 84, 227, 229, and 231:** Added *Board* column. **Page 171:** Changed *Comments* section. **Page 191:** Changed description of bits 00 and 01.

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